

Rešitve nalog 1. kolokvija iz TEORIJE ELEKTROMAGNETIKE

13/12/1989

$$\textcircled{1} \quad \Delta V = -\frac{\rho(r)}{\epsilon}; \frac{\partial}{\partial \theta} = 0; \frac{\partial}{\partial \phi} = 0; \beta_N = \rho_0 \frac{r^4}{a^4}$$

$$V_z = -C_{1z} r^{-1} + C_{2z} \quad C_{2z} = 0 \leftarrow V(\infty) = 0$$

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial V}{\partial r} \right) = -\frac{\rho(r)}{\epsilon}$$

$$\beta_2 = 0 \quad V_N = -\frac{\rho_0}{42\epsilon a^4} r^6 - C_{1N} r^{-1} + C_{2N} \quad C_{1N} = 0 \leftarrow V(0) < \infty$$

$$r^2 \frac{\partial V}{\partial r} = -\int r^2 \frac{\rho(r)}{\epsilon} dr + C_1 \quad V_z(a) = V_N(a)$$

$$V = \int r^2 \left[ \int r^2 \frac{\rho(r)}{\epsilon} dr + C_1 \right] dr + C_2 \quad -C_{1z} a^{-1} = -\frac{\rho_0 a^2}{42\epsilon} + C_{2N}$$

$$\frac{\partial V_z}{\partial r} \Big|_{r=a} = \frac{\partial V_N}{\partial r} \Big|_{r=a}$$

$$\frac{\rho_0 a^2}{7\epsilon} = -\frac{\rho_0 a^2}{42\epsilon} + C_{2N} \quad C_{1z} a^{-1} = -\frac{\rho_0 a}{7\epsilon}$$

$$C_{2N} = -\frac{8\rho_0 a^2}{42\epsilon} \quad V_z = \frac{\rho_0 a^5}{7\epsilon} r^{-1}$$

$$V_N = \frac{\rho_0}{42\epsilon} \left[ \frac{r^6}{a^4} + \frac{7a^2}{7} \right] \quad \vec{E}_z = \hat{r} \frac{\rho_0 a^3}{7\epsilon} r^{-2}$$

$$\vec{E}_N = \hat{r} \frac{\rho_0}{7\epsilon a^4} r^5$$

$$W = \frac{1}{2} \int_V \rho V dV = \frac{1}{2} \int_0^a \rho V_N 4\pi r^2 dr = 2\pi \int_0^a \rho_0 \frac{r^4}{a^4} \cdot \frac{\rho_0}{42\epsilon} \left[ -\frac{r^6}{a^4} + \frac{7a^2}{7} \right] r^2 dr = \frac{\pi \rho_0^2}{24\epsilon a^4} \left[ -\frac{a^9}{13} + \frac{7a^9}{7} \right] = \frac{4\pi \rho_0^2 a^5}{91\epsilon}$$

$$\textcircled{2} \quad V = (Ar^n + Br^{-(n+1)}) P_n(\cos \theta) \quad V = V_0 \cos \theta \rightarrow n=1$$

$$V_N = \frac{V_0}{a} r \cos \theta; B_N = 0 \leftarrow V(r=0) < \infty; \vec{E}_N = \frac{V_0}{a} (\hat{r} \cos \theta + \hat{\theta} \sin \theta) = -\vec{A}_z V_0 a^{-2}$$

$$V_z = V_0 a^2 r^{-2} \cos \theta; A_2 = 0 \leftarrow V(r=\infty) = 0; \vec{E}_z = V_0 a^2 (\hat{r} \cdot 2r^{-3} \cos \theta + \hat{\theta} r^{-3} \sin \theta)$$

$$W = \frac{\epsilon}{2} \int_V E^2 dV \quad W_N = \frac{\epsilon}{2} \int_V (-\vec{A}_z \frac{V_0}{a})^2 dV = \frac{\epsilon}{2} \frac{V_0^2}{a^2} \frac{4\pi a^3}{3} = \frac{2\pi \epsilon V_0^2 a}{3}$$

$$W_z = \frac{\epsilon}{2} \int_V [V_0 a^2 (\hat{r} \cdot 2r^{-3} \cos \theta + \hat{\theta} r^{-3} \sin \theta)]^2 dV = \frac{\epsilon V_0^2 a^4}{2} \int_V (4r^{-6} \cos^2 \theta + r^{-6} \sin^2 \theta) dV = \frac{\epsilon V_0^2 a^4}{2} \int_a^\infty r^{-6} r^2 dr \int_0^T [4 \cos^2 \theta + \sin^2 \theta] 2\pi \sin \theta d\theta$$

$$W_z = \pi \epsilon V_0^2 a^4 \frac{1}{3a^3} \int_0^T [3 \cos^2 \theta + 1] (-d \cos \theta) = \frac{\pi \epsilon V_0^2 a}{3} \int_{-1}^1 (3u^2 + 1) du = \frac{4\pi \epsilon V_0^2 a}{3}$$

$$\textcircled{3} \quad \begin{cases} 4V_1 = 2V_2 + V \\ 4V_2 = V_1 + V_3 + V_4 \\ 4V_3 = 2V_2 \\ 4V_4 = 2V_2 + 2V \end{cases} \quad \begin{cases} 4V_1 = 4V_3 + V \\ 8V_3 = V_1 + V_3 + V_4 \\ 4V_4 = 4V_3 + 2V \end{cases} \quad \begin{cases} 4V_1 = 4V_3 + V \\ 16V_3 = 2V_1 + 2V_3 + 2V_3 + V \\ 12V_3 = 2V_1 + V \end{cases} \quad \begin{cases} 24V_3 = (4V_3 + V) + 2V \\ \downarrow \\ V_3 = \frac{3}{20} V = 0.15V \end{cases} \quad \begin{cases} V_2 = \frac{6}{20} V = 0.3V \\ V_1 = \frac{3}{20} V = 0.15V \\ V_4 = \frac{13}{20} V = 0.65V \end{cases}$$

$$\textcircled{4} \quad S = 8 \cdot \frac{\alpha^2}{a^2} \quad \vec{J} = \vec{y} \cdot \vec{E} \quad ; \quad I = 2\pi g l \gamma \quad ; \quad \vec{J} = \hat{y} \gamma \vec{J} \quad ; \quad \vec{E} = \hat{y} \cdot \vec{E}$$

$$\vec{E} = \hat{y} \frac{I}{2\pi g l S} \quad U = \int_a^b \frac{I}{2\pi g l S} dy = \int_a^b \frac{I a^2}{2\pi g l S_0} \frac{dy}{y^2} = \frac{I a^2}{2\pi g l S_0} \cdot \frac{1}{2} \left( \frac{1}{a^2} - \frac{1}{b^2} \right)$$

$$P = U \cdot I = \frac{4\pi g l S_0 U^2}{a^2 \left( \frac{1}{a^2} - \frac{1}{b^2} \right)}$$

$$\frac{P}{l} = \frac{4\pi g l S_0 U^2}{a^2 \left( \frac{1}{a^2} - \frac{1}{b^2} \right)} = \frac{4\pi g l S_0 U^2 b^2}{b^2 - a^2}$$

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Rešitve 2. kolokvija iz TEORIJE ELEKTROMAGNETIKE (1. List)

①  $\Delta V_m = 0$  v vseh treh prostorih

$$V_n = A_n \sin \varphi$$

$$V_v = (A_v \rho + B_v \rho^{-1}) \sin \varphi$$

$$V_z = (A_z \rho + B_z \rho^{-1}) \sin \varphi$$

$$\vec{H} = -\text{grad } V_m$$

$$\vec{H}_n = -A_n (\vec{1}_\varphi \sin \varphi + \vec{1}_\rho \cos \varphi)$$

$$\vec{H}_v = -[\vec{1}_\varphi (A_v - \frac{B_v}{\rho^2}) \sin \varphi + \vec{1}_\rho (A_v + \frac{B_v}{\rho^2}) \cos \varphi]$$

$$\vec{H}_z = -[\vec{1}_\varphi (A_z - \frac{B_z}{\rho^2}) \sin \varphi + \vec{1}_\rho (A_z + \frac{B_z}{\rho^2}) \cos \varphi]$$

tangencialni:  $\vec{H}$ : normalni:  $\vec{B}$ :

$$① A_n = A_v + \frac{B_v}{a^2}; ③ A_n = \mu_r (A_v - \frac{B_v}{a^2})$$

$$② + ④ \rightarrow A_v (1 + \mu_r) + \frac{B_v}{b^2} (1 - \mu_r) = 2 A_z \quad ⑤$$

$$② A_v + \frac{B_v}{b^2} = A_z + \frac{B_z}{b^2}; ④ \mu_r (A_v - \frac{B_v}{b^2}) = A_z - \frac{B_z}{b^2}$$

$$① + ③ \rightarrow A_v = \frac{A_n (1 + \mu_r)}{2 \mu_r} \quad ⑥$$

$$B_v = \frac{-a^2 A_n (1 - \mu_r)}{2 \mu_r} \quad ⑦$$

$$⑤, ⑥ + ⑦ \rightarrow A_n \frac{(1 + \mu_r)^2}{2 \mu_r} - A_n \frac{a^2}{b^2} \frac{(1 - \mu_r)^2}{2 \mu_r} = 2 A_z$$

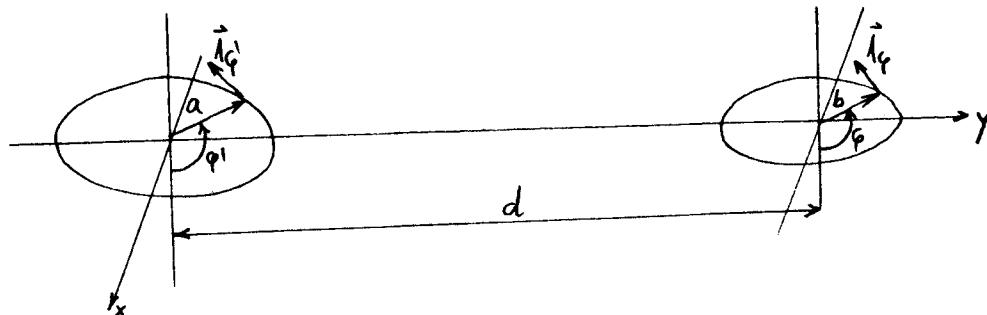
$$\underline{\underline{\frac{A_n}{A_z} = \frac{A_n}{H_z(\infty)} = \frac{4 \mu_r}{(1 + \mu_r)^2 - \frac{a^2}{b^2} (1 - \mu_r)^2}}}$$

②  $a, b \ll d$

$$\vec{V}_m = \frac{\mu}{4\pi} \int_{\text{r} \neq 0} \frac{\vec{j}(\vec{r}')}{|\vec{r} - \vec{r}'|} d\sigma' = \frac{\mu}{4\pi} \int_0^{2\pi} \frac{\vec{1}_\varphi I}{r - a \sin \varphi} a d\varphi = \frac{\mu I a}{4\pi} \int_0^{2\pi} \frac{-\vec{1}_x \sin \varphi + \vec{1}_y \cos \varphi}{r - a \sin \varphi} d\varphi$$

$$\vec{V}_m \approx \frac{\mu I a}{4\pi} \int_0^{2\pi} (-\vec{1}_x \sin \varphi + \vec{1}_y \cos \varphi) \frac{1}{r} (1 + \frac{a}{r} \sin \varphi) d\varphi = \frac{\mu I a}{4\pi r} (-\vec{1}_x) \pi \frac{a}{r} = -\vec{1}_x \frac{\mu I a^2}{4r^2}$$

$$\begin{aligned} M &= \frac{1}{I} \int_A \vec{B} d\vec{A} = \frac{1}{I} \int_A (\text{rot } \vec{V}_m) d\vec{A} = \frac{1}{I} \oint \vec{V}_m d\vec{s} = \frac{1}{I} \frac{\mu I a^2}{4} \int_0^{2\pi} (-\vec{1}_x) \cdot (\vec{1}_\varphi) \frac{1}{r^2} b d\varphi = \\ &= \frac{\mu a^2 b}{4} \int_0^{2\pi} \frac{\sin \varphi}{(d + b \sin \varphi)^2} d\varphi \approx \frac{\mu a^2 b}{4d^2} \int_0^{2\pi} \sin \varphi \left(1 - \frac{2b}{d} \sin \varphi\right) d\varphi = -\frac{\pi \mu a^2 b^2}{2d^3} \end{aligned}$$



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Rešitve 2. kolokvija iz TEORIJE ELEKTROMAGNETIKE (2. list)

(3)  $\vec{E} = \vec{1}_2 E_0 \vec{j}_0(kz) ; k = \frac{2.405}{a}$

$$\vec{H} = \frac{-1}{j\omega\mu} \text{rot } \vec{E} = \frac{-1}{j\omega\mu} \frac{1}{j} \begin{vmatrix} \vec{1}_p & j\vec{1}_q & \vec{1}_z \\ \frac{\partial}{\partial z} & \frac{\partial}{\partial q} & \frac{\partial}{\partial z} \\ 0 & 0 & E_0 \vec{j}_0(kz) \end{vmatrix} = \frac{-1}{j\omega\mu} j \vec{1}_q (-E_0 k \vec{j}_0(kz)) = \underline{\underline{\vec{1}_q \frac{E_0 k}{j\omega\mu} \vec{j}_0(kz)}}$$

$$\vec{E} = \frac{1}{j\omega\epsilon} \text{rot } \vec{H} = \frac{1}{j\omega\epsilon} \frac{1}{j} \begin{vmatrix} \vec{1}_p & j\vec{1}_q & \vec{1}_z \\ \frac{\partial}{\partial z} & \frac{\partial}{\partial q} & \frac{\partial}{\partial z} \\ 0 & j \frac{E_0 k}{j\omega\mu} \vec{j}_0(kz) & 0 \end{vmatrix} = \vec{1}_z \frac{1}{j\omega\epsilon} \cdot \frac{E_0 k}{j\omega\mu} \frac{1}{j} (\vec{j}_0(kz) + k \vec{j}_0''(kz)) =$$

$$= \vec{1}_z \frac{E_0 k^2}{\omega^2 \mu \epsilon} \vec{j}_0(kz) \rightarrow k^2 = \omega^2 \mu \epsilon ; \omega = \frac{k}{\sqrt{\mu \epsilon}} ; f = \frac{2.405}{2\pi a \sqrt{\mu \epsilon}} = \frac{2.405 \text{ c}}{2\pi a}$$

$$\vec{1}_n \times \vec{H} = \vec{K} \text{ na steni rezonatorja.}$$

Na spodnji steni :  $\vec{1}_n = \vec{1}_z ; z=0$   $\vec{K} = \vec{1}_z \times \vec{1}_q \frac{E_0 k}{j\omega\mu} (\vec{j}_0'(kz)) = \underline{\underline{\vec{1}_p \frac{j E_0 k}{\omega\mu} \vec{j}_0'(kz)}}$

Na obodu valja :  $\vec{1}_n = -\vec{1}_p ; p=a$   $\vec{K} = -\vec{1}_p \times \vec{1}_q \frac{E_0 k}{j\omega\mu} \vec{j}_0'(ka) = \underline{\underline{\vec{1}_z \frac{j E_0 k}{\omega\mu} \vec{j}_0'(2.405)}}$

Na zgornji steni :  $\vec{1}_n = -\vec{1}_z ; z=b$   $\vec{K} = -\vec{1}_z \times \vec{1}_q \frac{E_0 k}{j\omega\mu} \vec{j}_0'(kb) = \underline{\underline{-\vec{1}_p \frac{j E_0 k}{\omega\mu} \vec{j}_0'(kb)}}$

(4)  $\vec{E}_1 = \vec{1}_x E_1 e^{-jk_0 z}$   $\vec{H}_1 = \vec{1}_y \frac{E_1}{Z_0} e^{-jk_0 z}$   
 $\vec{E}_2 = \vec{1}_x (E_{2+} e^{-jk_0 z} + E_{2-} e^{jk_0 z})$   $\vec{H}_2 = \vec{1}_y \left( \frac{E_{2+}}{Z_0} e^{-jk_0 z} - \frac{E_{2-}}{Z_0} e^{jk_0 z} \right)$   
 $\vec{E}_3 = \vec{1}_x E_3 e^{-jk_0 z}$   $\vec{H}_3 = \vec{1}_y \frac{E_3}{Z_0} e^{-jk_0 z}$

Na prednji steni :  $\vec{E}_1 = \vec{E}_2 ; \vec{H}_1 = \vec{H}_2$

$$E_1 = E_{2+} + E_{2-} ; \frac{E_1}{Z_0} = \frac{E_{2+}}{Z} - \frac{E_{2-}}{Z}$$

$$E_{2+}(z-z_0) = -E_{2-}(z+z_0)$$

$$\frac{E_{2-}}{E_{2+}} = \frac{z_0 - z}{z_0 + z}$$

$$e^{2jk_0 d} = 1 \rightarrow 2kd = m \cdot 2\pi ; m=0,1,2\dots$$

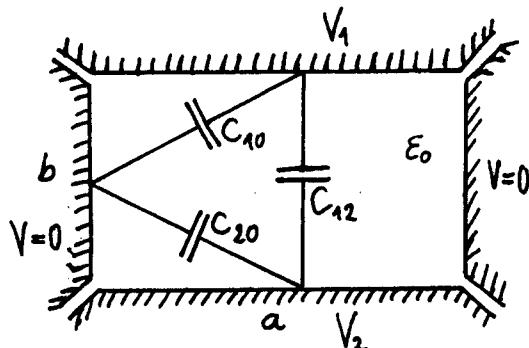
Na zadnji steni :  $\vec{E}_2 = \vec{E}_3 ; \vec{H}_2 = \vec{H}_3$

$$E_{2+} e^{-jk_0 d} + E_{2-} e^{jk_0 d} = E_3 e^{-jk_0 d}$$

$$\frac{E_{2+}}{Z} e^{-jk_0 d} - \frac{E_{2-}}{Z} e^{jk_0 d} = \frac{E_3}{Z_0} e^{-jk_0 d}$$

$$\frac{E_{2-}}{E_{2+}} e^{2jk_0 d} = \frac{z_0 - z}{z_0 + z}$$

$$d = \frac{m \cdot 2\pi}{2k} = \frac{m \cdot 2\pi \cdot \lambda}{2 \cdot 2\pi} = m \cdot \frac{\lambda}{2} \quad (\lambda \text{ v dielektriku!})$$

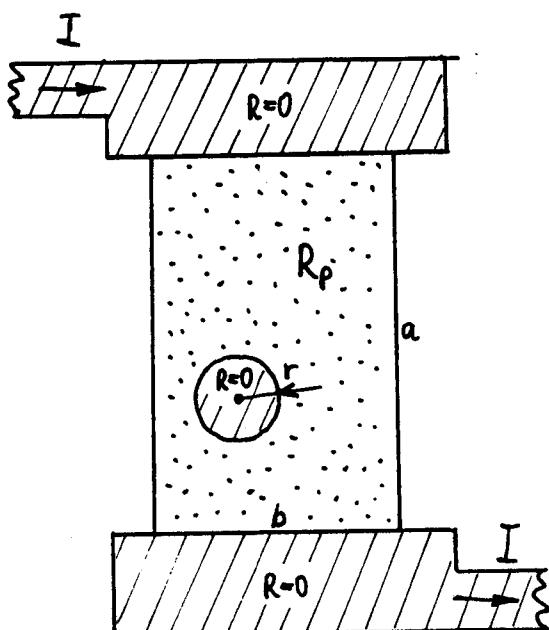
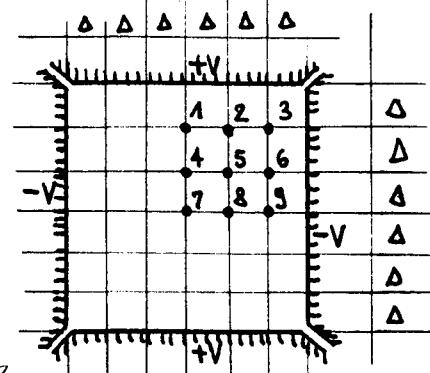


- 1) Izračunajte delno kapacitivnost na enoto dolžine med gornjo in spodnjo elektrodo v kovinskem žlebu ( $C_{12}$ ), če so stranske elektrode ozemljene!

$$C_{12} = 8\epsilon_0 \sum_{k=0}^{\infty} \frac{1}{(2k+1)\pi} \operatorname{sh} \frac{(2k+1)\pi b}{a}$$

- 2) Izračunajte potenciale v točkah 1, 2, 3, 4, 5, 6, 7, 8 in 9 z metodo končnih diferenc, če se (neskončno dolga) gornja in spodnja elektroda nahajata na potencialu  $+V$ , stranski elektrodi pa na potencialu  $-V$ .

$$V_1 = \frac{6}{13}V, V_2 = \frac{19}{52}V, V_4 = \frac{3}{26}V$$



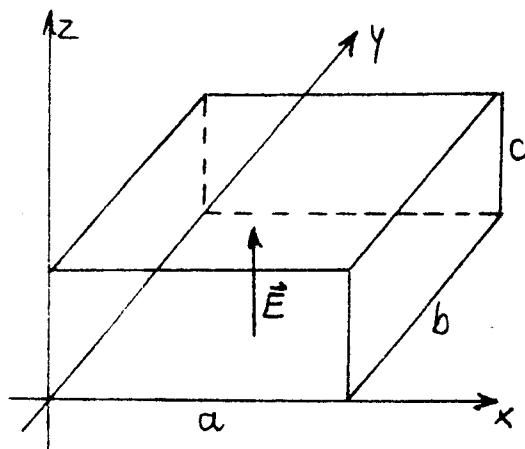
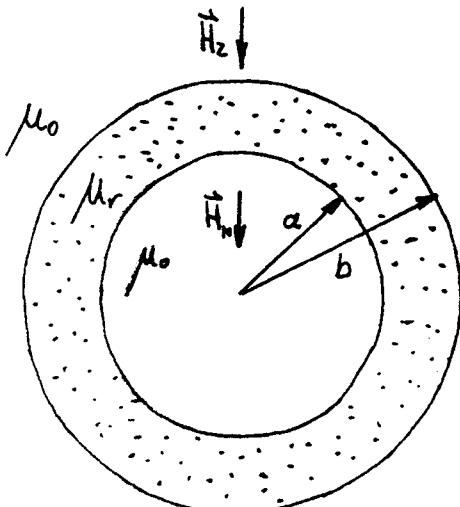
- 3) Skozi tankoslojni upor dolžine  $a$  in širine  $b$  teče tok  $I$ . Upor je izdelan iz snovi s plastično upornostjo  $R_p$ . Zaradi tehničke napake je sredi upora ostal majhen okrogel otok polmera  $r$  ( $r \ll a$  in  $r \ll b$ ) iz zelo dobro prevodnega materiala (za elektrode upora). Izračunajte električno polje v okolici napake! Kolikokrat je gostota moči na enoto ploskve tu večja od tiste v brezhibnem uporu?

$$\vec{E} = \frac{IR_p}{b} \left( -\vec{1}_\phi \left( 1 + \frac{r^2}{\beta^2} \right) \sin \varphi - \vec{1}_\phi \left( 1 - \frac{r^2}{\beta^2} \right) \cos \varphi \right)$$

$$P_{\max} = 4P_0 \quad \text{pri} \quad \beta = r \quad \text{in} \quad \varphi = \frac{\pi}{2}$$

1) Izračunajte učinkovitost magnetnega oklopa (razmerje med zunanjim in notranjim poljem) v obliki krogelne lupine z notranjim polmerom  $a$  in zunanjim polmerom  $b$ , ki je narejen iz feromagnetne snovi z relativno permeabilnostjo  $\mu_r$ .

$$\frac{A_2}{A_W} = \frac{H_2}{H_W} = \frac{(\mu_r + 2)(2\mu_r + 1) - (1 - \mu_r)^2 \frac{2a^3}{b^3}}{g_{\mu_r}}$$



2) V pravokotnem rezonatorju z dimenzijami  $a$ ,  $b$  in  $c$  je dano električno polje:

$$\vec{E} = \frac{1}{2} A \sin \frac{2\pi}{a} x \sin \frac{3\pi}{b} y$$

Izračunajte pripadajoče magnetno polje, rezonančno frekvenco, tokove v stenah rezonatorja in celotno energijo, ki jo vsebuje rezonator.

3) V prostoru je podano električno polje:

$$\vec{E} = \vec{A}_\theta A \frac{\sin \theta}{r} e^{-jk r}$$

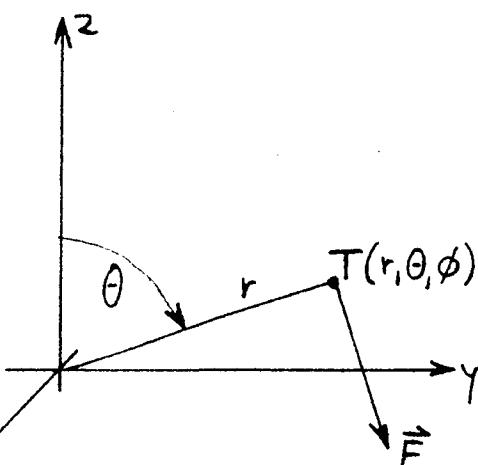
Izračunajte pripadajoče magnetno polje, gostoto električnega toka in Poyntingov vektor.

$$\vec{H} = \frac{j}{\omega \mu} \text{rot} \vec{E} = \vec{A}_\phi \frac{A}{Z_0} \frac{\sin \theta}{r} e^{-jk r}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \vec{A}_r \frac{AA^* \sin^2 \theta}{2Z_0 r^2}$$

$$\vec{j} = \text{rot} \vec{H} - j\omega \epsilon \vec{E} = \vec{A}_r \frac{1}{r^2 \sin \theta} \frac{A}{Z_0} 2 \sin \theta \cos \theta e^{-jk r} + \vec{A}_\theta \frac{jk}{r \sin \theta} \frac{A}{Z_0} \sin^2 \theta e^{-jk r} - \vec{A}_\theta A \frac{\sin \theta}{r} e^{-jk r} j\omega \epsilon$$

$$\vec{j} = \vec{A}_r \frac{2A}{Z_0} \frac{\cos \theta}{r^2} e^{-jk r}$$



## 2. LIST REŠITEV

2. K ELEKTROMAGNETIKA

17/1/1991

$$\textcircled{1} \quad \Delta V_m = 0$$

$$V_{mn} = A_N r \cos\theta$$

$$V_{mv} = A_v r \cos\theta + B_v r^{-2} \cos\theta$$

$$V_{mz} = A_z r \cos\theta + B_z r^{-2} \cos\theta$$

$$\textcircled{1} \quad A_n = \left( A_v - \frac{2B_v}{a^3} \right) \mu_r \quad \textcircled{3} \quad A_n = A_v + \frac{B_v}{a^3} \quad \textcircled{1} + \textcircled{3} \cdot 2 \mu_r \Rightarrow A_n (1 + 2 \mu_r) = 3 \mu_r A_v$$

$$\textcircled{2} \quad \mu_r \left( A_v - \frac{2B_v}{b^3} \right) = A_z - \frac{2B_z}{b^3} \quad \textcircled{4} \quad A_v + \frac{B_v}{b^3} = A_z + \frac{B_z}{b^3}$$

$$A_v = \frac{1 + 2 \mu_r}{3 \mu_r} A_n$$

$$\textcircled{2} + \textcircled{4} \cdot 2 \Rightarrow (\mu_r + 2) A_v + (1 - \mu_r) \frac{2B_v}{b^3} = 3 A_z \quad \textcircled{1} - \textcircled{3} \mu_r \Rightarrow A_n (1 - \mu_r) = -3 \mu_r \frac{B_v}{a^3}$$

$$B_v = -\frac{1 - \mu_r}{3 \mu_r} a^3 A_n$$

$$(\mu_r + 2) \frac{1 + 2 \mu_r}{3 \mu_r} A_n - (1 - \mu_r) \frac{1 - \mu_r}{3 \mu_r} \frac{2 a^3}{b^3} A_n = 3 A_z$$

$$\textcircled{2} \quad \vec{E} = \vec{i}_2 A \sin \frac{\pi x}{a} \times \sin \frac{3\pi y}{b}$$

pogoj za rezonanco  $\text{rot } \vec{H} = j\omega \epsilon \vec{E}$ 

$$\frac{jA}{\omega \mu} \left( \left( \frac{3\pi}{b} \right)^2 + \left( \frac{2\pi}{a} \right)^2 \right) = j\omega \epsilon A$$

$$\boxed{\omega = \frac{\sqrt{\left( \frac{3\pi}{b} \right)^2 + \left( \frac{2\pi}{a} \right)^2}}{\sqrt{\mu \epsilon'}}$$

$$W = \frac{\epsilon}{2} \int_V E_{\max}^2 dr = \frac{\epsilon |A|^2 abc}{8}$$

$$\vec{H} = \frac{j}{\omega \mu} \text{rot} \vec{E} = \vec{i}_x \frac{jA}{\omega \mu} \frac{3\pi}{b} \sin \frac{2\pi}{a} x \cos \frac{3\pi}{b} y -$$

$$- \vec{i}_y \frac{jA}{\omega \mu} \frac{2\pi}{a} \cos \frac{\pi}{a} x \sin \frac{3\pi}{b} y$$

$$\vec{K} = \vec{i}_n \times \vec{H} \quad \vec{i}_n \text{ gleda v skatlo!}$$

$$z=0; \vec{i}_n = \vec{i}_2; \vec{K}(z=0) = \vec{i}_y \frac{jA}{\omega \mu} \frac{3\pi}{b} \sin \frac{2\pi}{a} x \cos \frac{3\pi}{b} y + \vec{i}_x \frac{jA}{\omega \mu} \frac{2\pi}{a} \cos \frac{\pi}{a} x \sin \frac{3\pi}{b} y$$

$$z=c, \vec{i}_n = -\vec{i}_2; \vec{K}(z=c) = -\vec{i}_y \frac{jA}{\omega \mu} \frac{3\pi}{b} \sin \frac{2\pi}{a} x \cos \frac{3\pi}{b} y - \vec{i}_x \frac{jA}{\omega \mu} \frac{2\pi}{a} \cos \frac{\pi}{a} x \sin \frac{3\pi}{b} y$$

$$x=0; \vec{i}_n = \vec{i}_x; \vec{K}(x=0) = -\vec{i}_z \frac{jA}{\omega \mu} \frac{2\pi}{a} \sin \frac{3\pi}{b} y$$

$$x=a, \vec{i}_n = -\vec{i}_x; \vec{K}(x=a) = \vec{i}_z \frac{jA}{\omega \mu} \frac{2\pi}{a} \sin \frac{3\pi}{b} y$$

$$y=0; \vec{i}_n = \vec{i}_y; \vec{K}(y=0) = -\vec{i}_z \frac{jA}{\omega \mu} \frac{3\pi}{b} \sin \frac{2\pi}{a} x$$

$$y=b, \vec{i}_n = -\vec{i}_y; \vec{K}(y=b) = -\vec{i}_z \frac{jA}{\omega \mu} \frac{3\pi}{b} \sin \frac{2\pi}{a} x$$

Rešitve analog 1. kolokvija iz TEMAS 19/11/1991

$$\textcircled{1} \quad V = \sum_n (A_n g^n + B_n g^{-n}) \sin n\varphi$$

1. L(ST.)

$$V(g=a) = 0 = \sum_n (A_n a^n + B_n a^{-n}) \sin n\varphi \rightarrow B_n = -A_n a^{2n}$$

$$V = \sum_n A_n (g^n - a^{2n} g^{-n}) \sin n\varphi$$

$$V(g=b) = \begin{cases} +V_0 ; & 0 < \varphi < \pi \\ -V_0 ; & \pi < \varphi < 2\pi \end{cases} \rightarrow A_n = \frac{2V_0 (1 - \cos n\pi)}{n\pi (b^n - a^{2n} b^{-n})}$$

$$V(g, \varphi) = \sum_{k=0}^{\infty} \frac{4V_0}{(2k+1)\pi} \frac{1}{b^{\frac{(2k+1)}{2}} - a^{\frac{2k+1}{2}} b^{-\frac{(2k+1)}{2}}} \left( g^{2k+1} - a^{4k+2} g^{-(2k+1)} \right) \sin((2k+1)\varphi)$$

$$\vec{E} = -\operatorname{grad} V$$

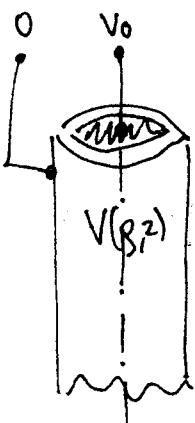
$$\vec{E} = -\vec{i}_g \frac{4V_0}{\pi} \sum_{k=0}^{\infty} \frac{1}{b^{\frac{2k+1}{2}} - a^{\frac{2k+1}{2}} b^{-\frac{2k+1}{2}}} \left( g^{2k} + a^{4k+2} g^{-(2k+2)} \right) \sin(2k+1)\varphi -$$

$$-\vec{i}_{\varphi} \frac{4V_0}{\pi} \sum_{k=0}^{\infty} \frac{1}{b^{\frac{2k+1}{2}} - a^{\frac{2k+1}{2}} b^{-\frac{2k+1}{2}}} \left( g^{2k} - a^{4k+2} g^{-(2k+2)} \right) \cos(2k+1)\varphi$$

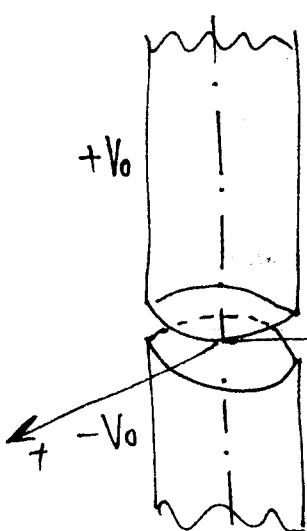
(2) Poznamo reziter problema:

RESITVE 1.k TEMA 6 19/11/1991

2. LIST



$$V(r, z) = \sum_{k=1}^{\infty} \frac{-2V_0}{\lambda_k a J_0'(\lambda_k a)} J_0(\lambda_k r) \cdot e^{\lambda_k z} = f(r, z)$$



$$V(r, z) = \begin{cases} f(r, z) - V_0 & ; z < 0 \\ V_0 - f(r, -z) & ; z > 0 \end{cases}$$

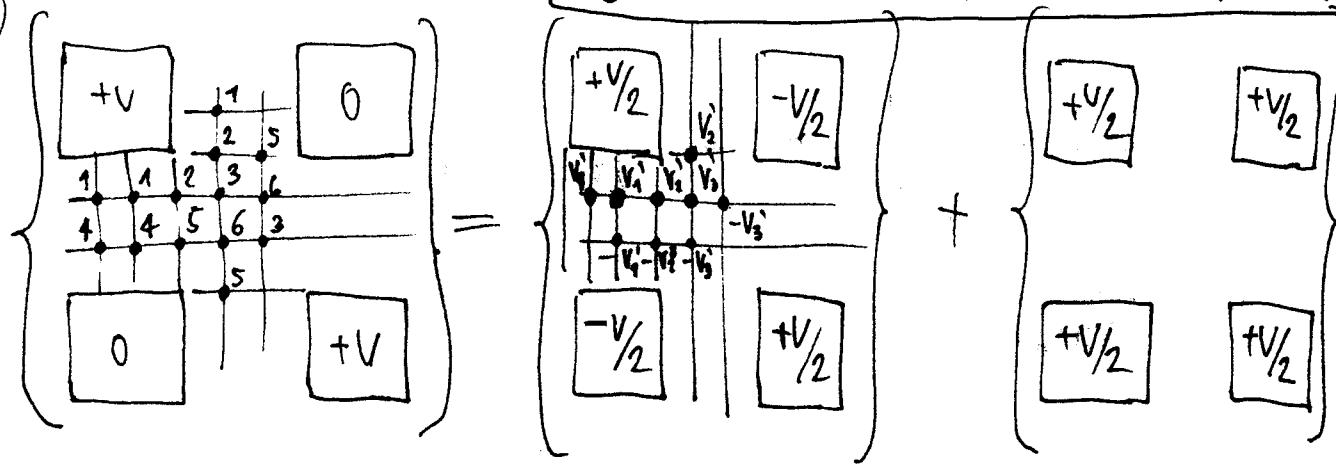
na ravni;

x-y je potencial 0!

$$V(r, z) = \begin{cases} \sum_{k=1}^{\infty} \frac{-2V_0}{\lambda_k a J_0'(\lambda_k a)} J_0(\lambda_k r) e^{\lambda_k z} - V_0 & ; z < 0 \\ V_0 - \sum_{k=1}^{\infty} \frac{-2V_0}{\lambda_k a J_0'(\lambda_k a)} J_0(\lambda_k r) e^{-\lambda_k z} & ; z > 0 \end{cases}$$

3.

RESITVE 1. K TEMA 6 13/11/1991. 3. LIST



$$\left. \begin{array}{l} 4V_1' = V_2' + V_1' - V_1' + V_2' \\ 4V_2' = V_2' + V_1' - V_2' + V_3' \\ 4V_3' = V_2' + V_2' - V_3' - V_3' \end{array} \right\} \rightarrow \begin{array}{l} 8V_1' = V + 2V_2' \\ 5V_2' = V_2' + V_1' + V_3' \rightarrow 10V_2' = V + 2V_1' + 2V_3' \\ 6V_3' = 2V_2' \rightarrow 3V_3' = V_2' \end{array}$$

$$8V_1' = V + 2V_2'$$

$$\underline{30V_2' = 3V + 6V_1' + 2V_3'}$$

$$28V_2' = 3V + 6V_1'$$

$$2V_2' = 8V_1' - V$$

$$\underline{112V_1' - 11V = 3V + 6V_1'}$$

$$106V_1' = 17V$$

$$\underline{V_1' = \frac{17}{106}V}$$

$$\underline{V_2' = \frac{15}{106}V}$$

$$\underline{V_3' = \frac{5}{106}V}$$

$$V_1 = V_1' + V_2' = \frac{70}{106}V$$

$$V_2 = V_1' + V_2' = \frac{68}{106}V$$

$$V_3 = V_3' + V_2' = \frac{58}{106}V$$

$$V_4 = -V_1' + V_2' = \frac{36}{106}$$

$$V_5 = -V_2' + V_2' = \frac{38}{106}$$

$$V_6 = -V_3' + V_2' = \frac{48}{106}$$

(4)

$$\frac{1}{dR} = dG = \int_a^b \frac{d\cdot g}{r dq} dr = \frac{d\cdot g}{dq} \ln \frac{b}{a}$$

$$dR = \frac{1}{8d \ln \frac{b}{a}} dq$$

$$R(q) = R \cdot \frac{U}{U_0} = R \cdot \frac{e^{kq} - 1}{e^{kT} - 1}$$

$$\frac{dR(q)}{dq} = R \frac{k e^{kq}}{e^{kT} - 1} = \frac{1}{8d \ln \frac{b}{a}}$$

$$g = \underline{\underline{\frac{e^{kT} - 1}{R k d \ln \frac{b}{a}} e^{-kq}}}$$

Rešitve nalog 2. kolokvija iz TEORIJE ELEKTROMAGNETIKE 14/1/1992

① Polje same zankice:  $\vec{H}_0 = \frac{\mu_0 I r_0^2}{4r^3} (\vec{l}_r \cdot 2 \cos\theta + \vec{l}_\theta \cdot \sin\theta)$

$$\Delta V_m = 0 \rightarrow V_m = (Ar + Br^{-2}) \cos\theta$$

$$\vec{H} = -\text{grad } V_m = +\vec{l}_r (A + 2Br^{-3}) \cos\theta + \vec{l}_\theta (A + Br^{-3}) \sin\theta$$

$$(A) \rightarrow B = \frac{\mu_0 I r_0^2}{4} \quad ; \quad (B) \rightarrow A = -Ba^{-3}$$

$$\vec{H} = \vec{l}_r \frac{\mu_0 I r_0^2}{4} (a^{-3} + 2r^{-3}) \cos\theta + \vec{l}_\theta (r^{-3} - a^{-3}) \sin\theta$$

pogoji:

$$(A) \vec{H} \approx \vec{H}_0 \text{ pri } r \rightarrow 0$$

$$(B) \vec{l}_\theta \cdot \vec{H} = 0 \text{ pri } r = a \text{ in } \mu_r \rightarrow \infty$$

②  $M = \frac{1}{I} \oint_b \vec{V}_{ma} \cdot d\vec{s} = 4 \cdot \left[ \frac{1}{I} \int_{-\frac{b}{2}}^{+\frac{b}{2}} \vec{V}_{ma} \cdot \vec{l}_x dx \right] \approx \frac{4}{I} (\vec{V}_{ma} \cdot \vec{l}_x) b$

$$\vec{V}_{ma} \cdot \vec{l}_x = \left[ \frac{\mu_0}{4\pi} \oint_a \frac{\vec{l}_I \cdot I}{|\vec{r} - \vec{r}'|} ds \right] \cdot \vec{l}_x = -\frac{\mu_0}{4\pi} \int_{-\frac{a}{2}}^{+\frac{a}{2}} \left[ \underbrace{\frac{I}{\sqrt{d^2 + \left(\frac{a+b}{2}\right)^2}}}_{\text{prednja stranica}} - \underbrace{\frac{I}{\sqrt{d^2 + \left(\frac{a-b}{2}\right)^2}}}_{\text{zadnja stranica}} \right] dx = \frac{1}{1+\epsilon} \approx 1 - \frac{\epsilon}{2}$$

$$= \frac{\mu_0 I a}{4\pi d} \left[ 1 - \frac{(a-b)^2}{8d^2} - 1 + \frac{(a+b)^2}{8d^2} \right] = \frac{\mu_0 I a}{4\pi d} \frac{4ab}{8d^2}$$

$$M = \frac{4}{I} \left( \frac{\mu_0 I a}{4\pi d} \cdot \frac{4ab}{8d^2} \right) \cdot b = \frac{\mu_0 a^2 b^2}{2\pi d^3}$$

③  $\vec{E} = \vec{l}_E \cdot E \quad \vec{l}_E = \frac{\vec{S} \times \vec{l}_z}{|\vec{S} \times \vec{l}_z|} = \frac{-\vec{l}_y + \vec{l}_x}{|-l_y + l_x|} = \vec{l}_x \frac{1}{\sqrt{2}} - \vec{l}_y \frac{1}{\sqrt{2}} \quad E = \sqrt{2 S Z_0} = \sqrt{2 \sqrt{S} 120\pi} = 36.14 \frac{V}{m}$

$$\vec{H} = \vec{l}_H \cdot H \quad \vec{l}_H = \frac{\vec{S} \times \vec{l}_E}{|\vec{S} \times \vec{l}_E|} = \frac{1/\sqrt{2}(-\vec{l}_z - \vec{l}_x + \vec{l}_y)}{1/\sqrt{2} \sqrt{4+1+1}} = \vec{l}_x \frac{1}{\sqrt{6}} + \vec{l}_y \frac{1}{\sqrt{6}} - \vec{l}_z \frac{2}{\sqrt{6}} \quad H = \frac{E}{Z_0} = 0.096 \frac{A}{m}$$

$$\vec{R} = \vec{l}_k \cdot k \quad \vec{l}_k = \vec{l}_s = \frac{\vec{S}}{|\vec{S}|} = \vec{l}_x \frac{1}{\sqrt{3}} + \vec{l}_y \frac{1}{\sqrt{3}} + \vec{l}_z \frac{1}{\sqrt{3}}$$

$$2\pi = \vec{k} \cdot \vec{l}_z (z_1 - z_2) = \frac{k}{\sqrt{3}} (1m - 0m) \rightarrow k = 2\pi \sqrt{3} = 10.88 \text{ rad/m}$$

$$f = \frac{c}{\lambda} \quad ; \quad k = \frac{2\pi}{\lambda} \rightarrow f = \frac{c \cdot k}{2\pi} = 3 \cdot 10^8 \cdot \sqrt{3} = 519.6 \text{ MHz}$$

④  $P = \frac{1}{2} |I|^2 Z_k ; \quad Z_k = \frac{Z_0}{\pi} \ln \frac{2d-r_0}{r_0}$

$$dP = -\frac{1}{2} |I|^2 dR ; \quad dR = 2R_p \frac{1}{2\pi r_0} dl ; \quad R_p = \sqrt{\frac{\omega \mu_0}{2\pi}} = 3.755 \text{ m}\Omega$$

$$\frac{dP}{P} = -\frac{dR}{Z_k} = -\frac{2R_p}{2\pi r_0 Z_k} dl = -\frac{R_p}{\pi r_0 Z_k} dl$$

$$\ln P = -\frac{R_p}{\pi r_0 Z_k} l + C$$

$$A = 10 \log \frac{P(0)}{P(l)} = \frac{10}{\ln 10} \ln \frac{P(0)}{P(l)} = \frac{10}{\ln 10} \frac{R_p l}{\pi r_0 Z_k} = \frac{10}{\ln 10} \frac{l \sqrt{\frac{\omega \mu_0}{2\pi}}}{r_0 Z_k \ln \frac{2d-r_0}{r_0}} = 0.734 \text{ dB}$$

Rešitve nalog 1. Kolokvija iz Teorije Elektromagnetike - 30/11/1993

$$\textcircled{1} \quad V = \sum_n A_n g^{2n} \cos 2n\varphi$$

$$\text{Na pokrovu: } g=a \quad ; \quad \int_{-\frac{\pi}{4}}^{\frac{\pi}{4}} V_0 \cos 2n\varphi d\varphi = \int_{-\frac{\pi}{4}}^{\frac{\pi}{4}} \left( \sum_m A_m a^{2m} \cos 2m\varphi \right) \cos 2n\varphi d\varphi$$

$$\frac{V_0}{2n} \left( \sin \frac{\pi}{2} n - \sin \left( -\frac{\pi}{2} n \right) \right) = A_n a^{2n} \frac{\pi}{4}$$

$$A_n = \frac{4V_0 \sin(\frac{\pi}{2}n)}{n\pi a^{2n}}$$

$$V(g, \varphi, z) = \sum_{n=1}^{\infty} \frac{4V_0 \sin(\frac{\pi}{2}n)}{n\pi a^{2n}} g^{2n} \cos 2n\varphi$$

$$\vec{E} = -\operatorname{grad} V = -\vec{1}_g \sum_{n=1}^{\infty} \frac{8V_0 \sin(\frac{\pi}{2}n)}{\pi a^{2n}} g^{2n-1} \cos 2n\varphi + \vec{1}_\varphi \sum_{n=1}^{\infty} \frac{8V_0 \sin(\frac{\pi}{2}n)}{\pi a^{2n}} g^{2n-1} \sin 2n\varphi$$

Pri praktičnem računu vzamemo:  $n = 2k+1$ ;  $k=0, 1, 2, \dots$ ;  $\sin(\frac{\pi}{2}n) = (-1)^k$

$$\textcircled{2} \quad \text{Iz geometrije sledi: } \vec{E} = \vec{1}_r E(r) \quad ; \quad \vec{D} = \vec{1}_r \frac{Q}{r^2} E(r)$$

$$\frac{dW}{dV} = \text{konst.} = \frac{1}{2} \vec{D} \cdot \vec{E} = \frac{1}{2} \epsilon(r) E^2(r) = -\frac{W}{r^2} = \frac{2C}{\frac{4\pi}{3}(r_2^3 - r_1^3)} \quad ; \quad Q = \oint \vec{D} \cdot d\vec{A} = 4\pi r^2 \epsilon(r) E(r)$$

$$\frac{1}{2} \epsilon(r) E^2(r) = \frac{(4\pi r^2)^2 \epsilon^2(r) E^2(r)}{2C \frac{4\pi}{3}(r_2^3 - r_1^3)} \quad \rightarrow \quad \underline{\underline{\epsilon(r) = \frac{r_2^3 - r_1^3}{12\pi r^4} C}}$$

$$\textcircled{3} \quad \text{Uporabimo reziter iz elektrostatike: } \delta \rightarrow \epsilon \quad ; \quad I/l \rightarrow q$$

$$\text{Valj: } V_r(R) = -\frac{q}{2\pi\epsilon} \ln \frac{R}{r_0} + V_0 \quad ; \quad \text{Trak: } V_t(R) = -\frac{q}{2\pi\epsilon} \mu + V_0 \quad ; \quad x = a \cosh \mu \cos \nu \quad y = a \sinh \mu \sin \nu \quad z = z$$

$$R = \sqrt{x^2 + y^2} = \sqrt{a^2 \cosh^2 \mu \cos^2 \nu + a^2 \sinh^2 \mu \sin^2 \nu} \approx \frac{a}{2} e^\mu \rightarrow \mu \approx \ln \frac{2R}{a} \text{ pri } R \gg a$$

$$V_v(R) = V_t(R) \rightarrow \ln \frac{R}{r_0} = \ln \frac{2R}{a} \rightarrow \underline{\underline{a = 2r_0 \quad ; \quad 2a = 4r_0}}$$

$$\textcircled{4} \quad \text{Iz simetrije sledi: } \underline{\underline{V_1 = V_6 = V_{11} = V_{16} = \frac{V_0}{2}}} \quad ; \quad V_{12} = V_2; V_8 = V_3; V_5 = V_0 - V_2 = V_{15}; V_9 = V_0 - V_3 = V_{14}$$

Ostanejo 4 neznanke:  $V_2; V_3; V_4; V_7$

$$V_{13} = V_0 - V_4; \quad V_{10} = V_0 - V_7$$

$$4V_2 = V_0 + \frac{V_0}{2} + \frac{V_0}{2} + V_3$$

$$\underline{\underline{V_3 = \frac{9}{11} V_0 = V_8}}$$

$$\underline{\underline{V_9 = \frac{2}{11} V_0 = V_{14}}}$$

$$4V_3 = V_0 + V_2 + V_7 + V_4$$

$$\underline{\underline{V_2 = \frac{31}{44} V_0 = V_{12}}}$$

$$\underline{\underline{V_5 = \frac{13}{44} V_0 = V_{15}}}$$

$$4V_4 = V_0 + V_3 + V_3 + V_0$$

$$\underline{\underline{V_4 = \frac{10}{11} V_0}}$$

$$\underline{\underline{V_{13} = \frac{1}{11} V_0}}$$

$$4V_7 = V_3 + \frac{V_0}{2} + \frac{V_0}{2} + V_3$$

$$\underline{\underline{V_7 = \frac{23}{44} V_0}}$$

$$\underline{\underline{V_{10} = \frac{15}{44} V_0}}$$

$$4V_2 = 2V_0 + V_3$$

$$4V_3 = V_0 + V_2 + V_4 + V_7 / 4$$

$$4V_4 = 2V_0 + 2V_3$$

$$4V_7 = V_0 + 2V_3$$

$$16V_3 = 4V_0 + 2V_0 + V_3 + 2V_0 + 2V_3 + V_0 + 2V_3$$

Rešitve nalog 2. kolokvija iz TEORIJE ELEKTROMAGNETIKE - 19/1/94

①

$$\vec{V}_m = \frac{\mu_0}{4\pi} \int_V \frac{\vec{j}(\vec{r}')}{|\vec{r}-\vec{r}'|} dV = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{s}}{|\vec{r}-\vec{r}'|} \quad d\vec{s} = \left( \vec{l}_q a + \vec{l}_z \frac{h}{2\pi} \right) d\varphi$$

$$|\vec{r}-\vec{r}'| = \sqrt{(r \sin \theta \cos \phi - a \cos \varphi)^2 + (r \sin \theta \sin \phi - a \sin \varphi)^2 + (r \cos \theta - \frac{h}{2\pi} \varphi)^2}$$

$$|\vec{r}-\vec{r}'| \approx r \left( 1 - \frac{a}{r} \sin \theta \cos (\phi - \varphi) - \frac{h}{2\pi r} \varphi \cos \theta \right)$$

$$\vec{V}_m \approx \frac{\mu_0 I}{4\pi r} \int_0^{2\pi} \left( 1 + \frac{a}{r} \sin \theta \cos (\phi - \varphi) + \frac{h}{2\pi r} \varphi \cos \theta \right) \left( \vec{l}_q a + \vec{l}_z \frac{h}{2\pi} \right) d\varphi$$

$$\vec{V}_m \approx \frac{\mu_0 I}{4\pi r} \int_0^{2\pi} \vec{l}_z \frac{h}{2\pi} d\varphi = \vec{l}_z \frac{\mu_0 I h}{4\pi r}$$

največja člena,  
produkt ne upada z  $\frac{a}{r}$  ali  $\frac{h}{r}$ !  
rezultat upada z  $r$ , ker tok ni zaključen!

② Znotraj:  $V_{mn} = (A_n g + B_n g^{-1}) \sin \varphi \quad \vec{H}_n = -[\vec{l}_g (A_n - B_n g^{-2}) \sin \varphi + \vec{l}_q (A_n + B_n g^{-2}) \cos \varphi]$

V steni:  $V_{nv} = (A_v g + B_v g^{-1}) \sin \varphi \quad \vec{H}_v = -[\vec{l}_g (A_v - B_v g^{-2}) \sin \varphi + \vec{l}_q (A_v + B_v g^{-2}) \cos \varphi]$

Zunaj:  $V_{nz} = B_z g^{-1} \sin \varphi \quad \vec{H}_z = -[\vec{l}_g B_z g^{-2} \sin \varphi + \vec{l}_q B_z g^{-2} \cos \varphi]$

Zunaj ni polja v  $\infty$ , zato je  $A_z = 0$

Učinkovitost oklopa =  $\frac{B_n}{B_z}$

$g=a: \quad ① A_n + B_n a^{-2} = A_v + B_v a^{-2}$

③  $A_n - B_n a^2 = \mu_r (A_v - B_v a^2)$

$g=b: \quad ② A_v + B_v b^{-2} = B_z b^{-2} \quad ④ \mu_r (A_v - B_v b^{-2}) = -B_z b^{-2}$

Izločimo  $A_n: \quad ① - ③ \quad 2B_n a^{-2} = A_v (1 - \mu_r) + B_v a^{-2} (1 + \mu_r)$

Izrazimo  $A_v$  in  $B_v$  z  $B_z$ :  $\mu_r \cdot ② \pm ④ \quad 2\mu_r A_v = B_z b^{-2} (\mu_r - 1) \quad A_v = B_z b^{-2} \frac{\mu_r - 1}{2\mu_r}$

$$2\mu_r B_v b^{-2} = B_z b^{-2} (\mu_r + 1) \quad B_v = B_z \frac{\mu_r + 1}{2\mu_r}$$

$$2B_n a^{-2} = B_z b^{-2} \frac{\mu_r - 1}{2\mu_r} (1 - \mu_r) + B_z \frac{\mu_r + 1}{2\mu_r} a^{-2} (1 + \mu_r) \rightarrow \frac{B_n}{B_z} = \frac{(1 + \mu_r)^2 - a^2/b^2 (1 - \mu_r)^2}{4\mu_r}$$

③  $\vec{k} = \vec{l}_k \cdot \vec{k} \quad \vec{l}_k = \pm \frac{\vec{E} \times \vec{l}_z}{|\vec{E} \times \vec{l}_z|} = \pm \frac{(-\vec{l}_x + \vec{l}_y \cdot 2 + \vec{l}_z \cdot 2) \times \vec{l}_z}{\sqrt{5}} = \pm \frac{\vec{l}_x \cdot 2 + \vec{l}_y}{\sqrt{5}} \quad k = \frac{2\pi}{\lambda} = \frac{2\pi f}{c} = \frac{\omega}{c} = 3.33 \text{ m}^{-1}$

$$\vec{H} = \vec{l}_H \cdot H \quad \vec{l}_H = \vec{l}_k \times \vec{l}_E \quad H = \vec{l}_k \times \vec{E} \frac{1}{Z_0} = \pm \frac{\vec{l}_x \cdot 2 + \vec{l}_y}{\sqrt{5}} \times (-\vec{l}_x + \vec{l}_y \cdot 2 + \vec{l}_z \cdot 2) \frac{A}{120\pi m} = \pm (\vec{l}_x \cdot 2 - \vec{l}_y \cdot 4 + \vec{l}_z \cdot 5) \frac{A/m}{\sqrt{5} \cdot 120\pi}$$

$$\vec{S} = \vec{l}_s \cdot S \quad \vec{l}_s = \vec{l}_k \quad S = \frac{|E|^2}{2Z_0} = \frac{9}{2 \cdot 120\pi} \frac{W}{m^2} = 0.012 \text{ W/m}^2$$

④  $U = E \cdot d; \quad I = H \cdot w = \frac{E \cdot \epsilon_r}{Z_0} \cdot w; \quad Z_k = \frac{U}{I} = \frac{d Z_0}{w \sqrt{\epsilon_r}}; \quad P = \frac{1}{2} |I|^2 Z_k$

$$R_p = \sqrt{\frac{\mu_0 \omega}{28 c_u}}; \quad dR = 2 R_p \frac{dl}{w} = \sqrt{\frac{\mu_0 \omega}{28 c_u}} 2 \frac{dl}{w}; \quad dP = -\frac{1}{2} |I|^2 dR = \frac{1}{2} |I|^2 \sqrt{\frac{\mu_0 \omega}{28 c_u}} 2 \frac{dl}{w}$$

$$\frac{dP}{P} = -\sqrt{\frac{\mu_0 \omega}{28 c_u}} \frac{2 \sqrt{\epsilon_r}}{dZ_0} dl; \quad \ln \frac{P_1}{P_2} = -\frac{l}{Z_0 d} \sqrt{\frac{2 \mu_0 \omega \epsilon_r}{8 c_u}}$$

$$A = 10 \log_{10} \frac{P_1}{P_2} = \frac{10}{\ln 10} \ln \frac{P_1}{P_2} = \frac{10}{\ln 10} \frac{l}{Z_0 d} \sqrt{\frac{2 \mu_0 \omega \epsilon_r}{8 c_u}} = 12.2 \text{ dB}$$

Rešitev 1. kolokvija iz TEORIJE ELEKTROMAGNETIKE - 29/11/1994

$$\textcircled{1} \quad 0 = \operatorname{div} \vec{D} = \operatorname{div} (\epsilon_r \epsilon_0 \vec{E}) = \epsilon_0 \vec{E} \cdot \operatorname{grad} \epsilon_r + \epsilon_r \epsilon_0 \operatorname{div} \vec{E} \quad \vec{E} = \text{konst.} = \vec{I}_g \cdot E_0$$

$$0 = \epsilon_0 \vec{I}_g E_0 \cdot \vec{I}_g \frac{\partial \epsilon_r}{\partial g} + \epsilon_r \epsilon_0 \frac{E_0}{g} \rightarrow \frac{d \epsilon_r}{\epsilon_r} = - \frac{dg}{g} \rightarrow \ln \epsilon_r = - \ln g + \ln A$$

$$\epsilon_r = \frac{A}{g}$$

$$q = \int_0^{2\pi} \vec{D} \cdot \vec{I}_g g d\varphi = 2\pi \frac{A}{g} \epsilon_0 E_0 g = 2\pi A \epsilon_0 E_0 \quad U = (b-a) E_0$$

$$C/l = \frac{q}{U} = \frac{2\pi A \epsilon_0 E_0}{(b-a) E_0} = \frac{2\pi \epsilon_0 A}{b-a} \rightarrow A = \frac{C/l (b-a)}{2\pi \epsilon_0} = \underline{54 \text{ mm}} \quad \underline{\epsilon_r = \frac{54 \text{ mm}}{g}}$$

$$\textcircled{2} \quad \zeta(x, y=0) = - \frac{4V_0 \epsilon_0}{a} \sum_{k=0}^{\infty} \frac{\sin((2k+1)\frac{\pi}{a}x)}{\operatorname{sh}(2k+1)\frac{\pi}{a}b} \rightarrow \begin{cases} k=0: -30 \cdot 10^{-3} \frac{As}{m^2} = - \frac{4V_0 \epsilon_0}{a} \frac{1}{\operatorname{sh} \pi \frac{b}{a}} \\ k=1: -1 \cdot 10^{-3} \frac{As}{m^2} = - \frac{4V_0 \epsilon_0}{a} \frac{1}{\operatorname{sh} 3\pi \frac{b}{a}} \end{cases}$$

Vzamemo samo  $k=0,1$ ; öleni  $k \geq 2 \rightarrow$  majhna napaka!

$$30 = \frac{\operatorname{sh} 3\pi \frac{b}{a}}{\operatorname{sh} \pi \frac{b}{a}} = \frac{\mu^3 - \mu^{-3}}{\mu - \mu^{-1}} = \mu^2 + 1 + \mu^{-2}; \mu = e^{\frac{\pi b}{a}} \rightarrow \mu^4 - 29\mu^2 + 1 = 0; \mu^2 = \frac{29 \pm \sqrt{29^2 - 4}}{2}$$

$$\mu^2 = 28.965; \mu = 5.382; b = \frac{a}{\pi} \ln \mu = \underline{0.536 \text{ m}}$$

$$V_0 = \frac{a}{4\epsilon_0} \operatorname{sh} \pi \frac{b}{a} \cdot 30 \cdot 10^{-3} \frac{As}{m^2} = \underline{22 \text{ kV}}$$

$$\textcircled{3} \quad \vec{E}_0 = -\vec{I}_r E_0 = (-\vec{I}_r \cos \theta + \vec{I}_\theta \sin \theta) E_0 \quad \zeta = \vec{I}_r \cdot (\vec{D}_z - \vec{D}_N) = \vec{I}_r \cdot (\epsilon_0 \vec{E}_0 - \epsilon_r \epsilon_0 \vec{E}_0)$$

$$\zeta = \vec{I}_r \cdot \vec{E}_0 \epsilon_0 (1-\epsilon_r) = \underline{E_0 \epsilon_0 (\epsilon_r - 1) \cos \theta = 79.6 \text{ nAs/m}^2 \cdot \cos \theta}$$

$$\textcircled{4} \quad V = A \ln \left( \operatorname{tg} \frac{\theta}{2} \right) \quad ; \quad \vec{E} = -\operatorname{grad} V = -\vec{I}_\theta \frac{A}{r \sin \theta} \quad ; \quad \vec{j} = 8 \vec{E} = -\vec{I}_\theta 8_0 e^{-\frac{r}{r_0}} \frac{A}{r \sin \theta}$$

$$I = \iint_0^{2\pi} \vec{j} \cdot (-\vec{I}_\theta) r \sin \theta d\theta dr = 2\pi \int_0^\infty 8_0 e^{-\frac{r}{r_0}} A dr = \underline{2\pi 8_0 r_0 A}$$

$$U = V_B - V_A = A \ln \left( \operatorname{tg} \frac{\theta}{2} \right) - A \ln \left( \operatorname{tg} \frac{\alpha}{2} \right) = \underline{A \ln \frac{\operatorname{tg} 5\pi/12}{\operatorname{tg} \pi/12}}$$

$$R = \frac{U}{I} = \frac{\ln \frac{\operatorname{tg} 5\pi/12}{\operatorname{tg} \pi/12}}{2\pi 8_0 r_0} = \underline{0.419 \Omega}$$

## Rešitve 2. kolokvija iz TEORIJE ELEKTROMAGNETIKE - 10/1/95

$$\textcircled{1} \quad I = \oint \vec{H} d\vec{s} \rightarrow \vec{H} = \vec{I}_\varphi \frac{I}{2\pi r} \quad \vec{I}_2 = \vec{I}_r \cos \theta - \vec{I}_\theta \sin \theta ; \quad r = r \sin \theta$$

$$\vec{H} = \frac{1}{\mu_0} \operatorname{rot} \vec{V}_m ; \quad \vec{V}_m = \vec{I}_2 V_m(r) ; \quad \operatorname{rot} \vec{V}_m = -\vec{I}_\varphi \frac{\partial V_m(r)}{\partial r} = \vec{I}_\varphi \frac{\mu_0 I}{2\pi r}$$

$$\vec{V}_m = -\vec{I}_2 \left( \frac{\mu_0 I}{2\pi} \ln r + C \right) = \underline{\underline{(-\vec{I}_r \cos \theta + \vec{I}_\theta \sin \theta) \left( \frac{\mu_0 I}{2\pi} \ln (r \sin \theta) + C \right)}}$$

$$\textcircled{2} \quad V_{m_0} = \frac{IN}{l} z = \frac{IN}{l} r \cos \theta ; \quad \text{rešujemo } \Delta V_m = 0$$

$$V_{m_2} = \left( \frac{IN}{l} r + \frac{B}{r^2} \right) \cos \theta ; \quad \vec{H}_2 = -\vec{I}_r \left( \frac{IN}{l} - \frac{2B}{r^3} \right) \cos \theta + \vec{I}_\theta \left( \frac{IN}{l} + \frac{B}{r^3} \right) \sin \theta$$

$$V_{m_N} = A r \cos \theta ; \quad \vec{H}_N = -\vec{I}_r A \cos \theta + \vec{I}_\theta A \sin \theta$$

$$H_{tz} = H_{tN} \rightarrow \frac{IN}{l} + \frac{B}{r_0^3} = A ; \quad B_{nz} = B_{nN} \rightarrow \left( \frac{IN}{l} - \frac{2B}{r_0^3} \right) \mu_0 \mu_r = A \mu_0$$

$$\frac{IN}{l} \beta_{ur} = A(2\mu_r + 1) \rightarrow A = \frac{IN}{l} \frac{3\mu_r}{2\mu_r + 1} ; \quad \vec{H}_N = -\vec{I}_2 \frac{IN}{l} \frac{3\mu_r}{2\mu_r + 1}$$

$$\textcircled{3} \quad \Delta V = 0 \rightarrow V = E_0 e^{j\omega t} \left( \frac{1}{r} - \frac{\alpha^2}{r^2} \right) \sin \varphi$$

$$\vec{E} = -\operatorname{grad} V = -\vec{I}_\varphi E_0 e^{j\omega t} \left( 1 + \frac{\alpha^2}{r^2} \right) \sin \varphi - \vec{I}_\varphi E_0 e^{j\omega t} \left( 1 - \frac{\alpha^2}{r^2} \right) \cos \varphi$$

$$\vec{I}_n = \vec{I}_\varphi \quad \vec{\zeta} = \vec{I}_n \cdot \epsilon_0 \vec{E} = -2 \epsilon_0 E_0 e^{j\omega t} \sin \varphi$$

$$\operatorname{div} \vec{\zeta} + j\omega \rho = 0 \rightarrow \operatorname{div} \vec{K} + j\omega \zeta = 0 \quad \vec{K} = \vec{I}_\varphi K(\varphi)$$

$$\operatorname{div} \vec{K} = \frac{1}{r} \left( \frac{\partial K}{\partial \varphi} \right) = -j\omega \zeta$$

$$\frac{\partial K}{\partial \varphi} = \alpha 2 j \omega \epsilon_0 E_0 e^{j\omega t} \sin \varphi \rightarrow \underline{\underline{\vec{K} = -\vec{I}_\varphi \left( 2 j \omega \epsilon_0 E_0 e^{j\omega t} \cos \varphi + C \right)}}$$

$$\textcircled{4} \quad (\alpha + j\beta_\delta)^2 = j\omega \mu_0 (\gamma + j\omega \epsilon_0 \epsilon_r)$$

$$\text{Uvedemo } \mu = \frac{\omega \epsilon_0 \epsilon_r}{\gamma}$$

$$\alpha^2 - \beta_\delta^2 + 2j\alpha\beta_\delta = j\omega \mu_0 \gamma - \omega^2 \mu_0 \epsilon_0 \epsilon_r$$

$$1\% \text{ napaka} \rightarrow \sqrt[4]{1 + \mu^2} - \mu' = 0.99$$

$$\alpha^2 - \beta_\delta^2 = -\omega^2 \mu_0 \epsilon_0 \epsilon_r \quad 2\alpha\beta_\delta = \omega \mu_0 \gamma$$

$$\mu \approx 0.02$$

$$\beta_\delta = \frac{\omega \mu_0 \gamma}{2\alpha}$$

$$f = \frac{\omega}{2\pi} = \frac{\omega \gamma}{2\pi \epsilon_0 \epsilon_r} = \underline{\underline{22.5 \text{ MHz}}}$$

$$\alpha^2 - \frac{\omega^2 \mu_0^2 \gamma^2}{4\alpha^2} = -\omega^2 \mu_0 \epsilon_0 \epsilon_r$$

$$\alpha^4 + \alpha^2 \omega^2 \mu_0 \epsilon_0 \epsilon_r - \frac{\omega^2 \mu_0^2 \gamma^2}{4} = 0$$

$$\alpha^2 = \frac{-\omega^2 \mu_0 \epsilon_0 \epsilon_r \pm \sqrt{\omega^4 \mu_0^2 \epsilon_0^2 \epsilon_r^2 + \omega^2 \mu_0^2 \gamma^2}}{2}$$

$$\alpha = \sqrt{\frac{\omega \mu_0 \gamma}{2}} \cdot \sqrt{\sqrt{1 + \frac{\omega^2 \epsilon_0^2 \epsilon_r^2}{\gamma^2}} - \frac{\omega \epsilon_0 \epsilon_r}{\gamma}}$$

Rešitev 1. kolokvija iz TEORIJE ELEKTROMAGNETIKE - 28/11/1995

$$\textcircled{1} \quad h_{q_i} = \sqrt{\left(\frac{\partial x}{\partial q_i}\right)^2 + \left(\frac{\partial y}{\partial q_i}\right)^2 + \left(\frac{\partial z}{\partial q_i}\right)^2}$$

$$h_u = a \sqrt{\sin^2 u + \sin^2 v}$$

$$h_v = a \sqrt{\sin^2 u + \sin^2 v}$$

$$h_w = a \sin u \cos v$$

$$\operatorname{div} \vec{F} = \frac{1}{a^3 (\sin^2 u + \sin^2 v) \sin u \cos v} \left[ \frac{\partial}{\partial u} \left( a^2 \sqrt{\sin^2 u + \sin^2 v} \sin u \cos v F_u \right) + \frac{\partial}{\partial v} \left( a^2 \sqrt{\sin^2 u + \sin^2 v} \sin u \cos v F_v \right) + \frac{\partial}{\partial w} \left( a^2 \sqrt{\sin^2 u + \sin^2 v} F_w \right) \right]$$

$$\textcircled{2} \quad \vec{E} = -\operatorname{grad} V = -\vec{l}_r V_0 \cos 3\theta + \vec{l}_\theta V_0 3 \sin 3\theta \quad \vec{D} = \epsilon_0 \vec{E} \quad g = \operatorname{div} \vec{D} = \operatorname{div} (\epsilon_0 \vec{E})$$

$$g = \frac{1}{r^2 \sin \theta} \left[ \frac{\partial}{\partial r} \left( r^2 \sin \theta (-\epsilon_0 \cos 3\theta) \right) + \frac{\partial}{\partial \theta} \left( r \sin \theta \epsilon_0 3 \sin 3\theta \right) \right] = -\frac{2\epsilon_0 V_0}{r} \cos 3\theta +$$

$$+ \frac{3\epsilon_0 V_0 \cos \theta \sin 3\theta}{r \sin \theta} + \frac{3\epsilon_0 V_0}{r} 3 \cos 3\theta = \frac{\epsilon_0 V_0}{r} (4 \cos 3\theta + 3 \operatorname{ctg} \theta \sin 3\theta)$$

$$\textcircled{3} \quad V(\beta_1 q_1 z) = \sum_n C_n \beta^n \cos^n \varphi \quad \int_{-\pi}^{+\pi} \left[ \sum_n C_n \alpha^n \cos^n \varphi \right] \cos m\varphi d\varphi = \int_{-\pi}^{+\pi} V_0 \cos m\varphi d\varphi = \frac{2V_0}{m} \sin m \frac{\pi}{4} = \overbrace{\pi C_m \alpha^m}^{m \neq 0}$$

$$C_m = \frac{V_0}{2\alpha^m} \frac{\sin \frac{m\pi}{4}}{\frac{m\pi}{4}} \quad \text{pri } m \neq 0; \quad C_0 = \frac{V_0}{4}$$

$$V(\beta_1 q_1 z) = \frac{V_0}{4} + \frac{V_0}{2} \sum_{m=1}^{\infty} \frac{\beta^m}{\alpha^m} \frac{\sin \frac{m\pi}{4}}{\frac{m\pi}{4}} \cos m\varphi$$

Veljale pri  
 $m \neq 0$

$$\textcircled{4} \quad r \ll l \rightarrow V = -V_0 \ln \left( \tan \frac{\theta}{2} \right); \quad \vec{E} = \vec{l}_\theta V_0 \frac{1}{r \sin \theta} \quad ; \quad \vec{j} = \vec{l}_\theta 8V_0 \frac{1}{r \sin \theta}$$

$$\frac{dI}{dz} = \int_0^{2\pi} \vec{j} \cdot \vec{l}_\theta r \sin \theta d\phi = 2\pi 8V_0 \rightarrow V_0 = \frac{\frac{dI}{dz}}{2\pi 8} = \frac{I}{2\pi 8l}$$

$$\vec{E} = \vec{l}_\theta \frac{I}{2\pi 8l} \frac{1}{r \sin \theta}$$

$$\textcircled{5} \quad U = \frac{I}{\Omega 8a}; \quad R = \frac{1}{\Omega 8a}; \quad \Omega = 2\pi \left( 1 - \cos \frac{\alpha}{2} \right)$$

$$R = \frac{1}{2\pi \left( 1 - \cos \frac{\alpha}{2} \right) 8a}$$

Rešitev 2. kotokvija iz TEORIJE ELEKTROMAGNETIKE - 17/01/1996

$$\textcircled{1} \quad \vec{H} = \frac{1}{\mu_0} \operatorname{rot} \vec{A} = \frac{1}{\mu_0 \rho} \begin{vmatrix} \vec{1}_\rho & \rho \vec{1}_\phi & \vec{1}_z \\ \frac{\partial}{\partial \rho} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ 0 & \rho \cdot 0 & C \ln \rho \end{vmatrix} = -\vec{1}_\phi \frac{C}{\mu_0 \rho} \quad \vec{j} = \operatorname{rot} \vec{H} = \frac{1}{\rho} \begin{vmatrix} \vec{1}_\rho & \rho \vec{1}_\phi & \vec{1}_z \\ \frac{\partial}{\partial \rho} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ 0 & -\rho \cdot \frac{C}{\mu_0 \rho} & 0 \end{vmatrix} = 0$$

$$I = \oint \vec{H} \cdot d\vec{s} = \int_0^{2\pi} -\vec{1}_\phi \frac{C}{\mu_0 \rho} \cdot \vec{1}_\phi \rho d\phi = -\frac{2\pi C}{\mu_0} \text{ tok v osi } z!$$

$$\textcircled{2} \quad \Delta W = \pm 2 \cdot 2 \frac{1}{2} \int_V \vec{j} \cdot \vec{A} dV = \pm 2 \int_0^{2\pi} I \vec{1}_\phi \cdot \vec{1}_\phi \frac{C}{\rho^2} \sin \frac{\pi}{2} d\phi = \pm \frac{4\pi I C}{a}$$

$$\textcircled{3} \quad \operatorname{div} \vec{j} = -j\omega \rho \rightarrow \operatorname{div} \vec{K} = -j\omega \sigma$$

$$\sigma = \frac{j}{\omega} \operatorname{div} \vec{K} = \frac{j}{\omega} \frac{\partial}{\partial x} (\sin \alpha x) = \frac{j \alpha}{\omega} \cos \alpha x$$

$$\textcircled{4} \quad \vec{H} = \frac{j}{\omega \mu_0} \operatorname{rot} \vec{E} = \frac{j}{\omega \mu_0} \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{1}_r & r \vec{1}_\theta & r \sin \theta \vec{1}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & r C \frac{e^{ikr}}{r \sin \theta} & 0 \end{vmatrix} = \vec{1}_\phi \frac{j}{\omega \mu_0 r} C (-jk) e^{-jkr} \sin \theta = \vec{1}_\phi \frac{C}{Z_0} \frac{e^{-jkr}}{r} \sin \theta$$

$$\vec{j} = \operatorname{rot} \vec{H} - j\omega \epsilon_0 \vec{E} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{1}_r & r \vec{1}_\theta & r \sin \theta \vec{1}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & 0 & r \sin \theta \frac{C}{Z_0} \frac{e^{-jkr}}{r} \sin \theta \end{vmatrix} - \vec{1}_\theta j \omega \epsilon_0 C \frac{e^{-jkr}}{r} \sin \theta = \vec{1}_r \frac{C}{Z_0} \frac{e^{-jkr}}{r^2} 2 \cos \theta$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \vec{1}_r \frac{|C|^2}{2Z_0} \frac{\sin^2 \theta}{r^2}$$

$$\textcircled{5} \quad P = \frac{1}{2} A |\vec{K}|^2 R_p ; \quad R_p = \sqrt{\frac{\omega \mu}{2 \gamma}}$$

$$|\vec{K}|^2 = \frac{2P}{A \sqrt{\frac{\omega \mu}{2 \gamma}}} = |\vec{H}|^2 \quad |\vec{H}| = \sqrt{\frac{2P}{A \sqrt{\frac{\omega \mu}{2 \gamma}}}}$$

# Rešitev 1. kolokvija iz TEORIJE ELEKTROMAGNETIKE - 26/11/1996

①  $\vec{E} \cdot \vec{D} = \alpha$ ;  $\vec{D} = \epsilon_r \epsilon_0 \vec{E}$ ;  $\vec{D} = \vec{l}_S \frac{q}{2\pi s} \rightarrow \frac{|\vec{D}|^2}{\epsilon_0 \epsilon_r} = \alpha$ ;  $\epsilon_r = \frac{q^2}{(2\pi)^2 s^2 \epsilon_0 \alpha}$

$\alpha$  konstanta

$$U = - \int_b^a \vec{E} ds = \int_a^b |\vec{E}| ds = \int_a^b \frac{\alpha}{|\vec{D}|} ds = \int_a^b \frac{\alpha 2\pi s}{q} ds = \frac{2\pi \alpha}{q} \frac{b^2 - a^2}{2}; \frac{C}{l} = \frac{q}{U} = \frac{2q^2}{2\pi \alpha (b^2 - a^2)}$$

$$\alpha = \frac{q^2}{\pi \frac{C}{l} (b^2 - a^2)}; \underline{\underline{\epsilon_r = \frac{C}{l} \frac{b^2 - a^2}{4\pi \epsilon_0} \frac{1}{s^2} = \frac{6.75 \cdot 10^{-4} m^2}{s^2}}}$$

$$\epsilon_0 = \frac{1}{4\pi \cdot 9 \cdot 10^9} \frac{As}{Vm}$$

②  $V = \sum_k C_k s^{-k} \sin k\varphi$ ;  $\vec{E} = +\vec{l}_S \frac{k C_k}{s^{k+1}} \sin k\varphi - \vec{l}_Q \frac{k C_k}{s^{k+1}} \cos k\varphi$ ;  $\vec{E}(s \gg a) \approx \vec{l}_S \frac{C_1}{s^2} \sin \varphi - \vec{l}_Q \frac{C_1}{s^2} \cos \varphi$

$$\int_0^\pi V_0 \sin \varphi d\varphi = \int_0^\pi \frac{C_1}{a} \sin^2 \varphi d\varphi \rightarrow C_1 = \frac{4aV_0}{\pi}; \vec{E}(s \gg a) \approx \vec{l}_S \frac{4aV_0}{\pi s^2} \sin \varphi - \vec{l}_Q \frac{4aV_0}{\pi s^2} \cos \varphi$$

Premi dipol  $\vec{m} = \vec{l}_y m$ :  $\vec{E} = \frac{m}{2\pi \epsilon_0} \left( \vec{l}_S \frac{\sin \varphi}{s^2} - \vec{l}_Q \frac{\cos \varphi}{s^2} \right) \rightarrow \underline{\underline{\vec{m} = \vec{l}_y 8aV_0 \epsilon_0}}$

③ Koordinate ( $u, v, z$ ):  $x = a \cosh u \cos v$ ;  $y = a \sinh u \sin v$ ,  $z = z$

$$V = -\frac{q}{2\pi \epsilon_0} u \rightarrow u = \frac{2\pi \epsilon_0 (-V)}{q} = \frac{2\pi As \cdot 360 V_m}{4\pi \cdot 9 \cdot 10^9 V_m \cdot 2 \cdot 10^{-8} As} = \underline{\underline{1}}$$

Ekvipotencialna ploskev:  $u=1$

$$\frac{x}{a \cosh 1} = \cos v; \frac{y}{a \sinh 1} = \sin v; \underline{\underline{\frac{x^2}{a^2 \cosh^2 1} + \frac{y^2}{a^2 \sinh^2 1} = 1}}$$

$$\frac{x^2}{1.488 \cdot 10^3 m^2} + \frac{y^2}{8.632 \cdot 10^4 m^2} = \underline{\underline{1}} \quad \text{Enačba elipse}$$

④  $\vec{E} = -\vec{l}_r E_0 \left( 1 + \frac{2a^3}{r^3} \right) \cos \theta + \vec{l}_\theta E_0 \left( 1 - \frac{a^3}{r^3} \right) \sin \theta$ ;  $\vec{j} = \frac{\vec{E}}{s}$ ;  $\vec{j}_r(r=a) = -\frac{3E_0}{s} \cos \theta$

$$I = \iint_0^{2\pi} \int_0^a j_r a^2 \sin \theta d\theta dr d\varphi = -\frac{3\pi E_0 a^2}{s} \int_0^a \left[ 2 \cos \theta \sin \theta d\theta \right] = -\frac{3\pi E_0 a^2}{s} \left( \frac{1}{2} \cos 2\theta \right) \Big|_0^a = \frac{3\pi E_0 a^2}{2s} (\cos 2a - 1) = -\frac{3\pi E_0 a^2}{s} \sin a$$

$$\vec{K} = -\vec{l}_\theta \frac{I}{2\pi a \sin \theta} = \vec{l}_\theta \frac{3E_0 a}{2s} \sin \theta = \underline{\underline{1.015 \frac{A}{m} \sin \theta}}$$

⑤ Ozka razdalina razpoka polja NE MOTI!

$$\vec{k} = -\vec{l}_y \frac{I}{W} = \underline{\underline{-\vec{l}_y 2 \frac{A}{m}}}$$

Rešitev 2. kolokvija iz TEORIJE ELEKTROMAGNETIKE - 14/1/1997

$$\textcircled{1} \quad \vec{H} = \frac{1}{\mu} \operatorname{rot} \vec{V}_m = \frac{1}{\mu r^2 \sin \theta} \begin{vmatrix} \vec{1}_r & r \vec{1}_\theta & r \sin \theta \vec{1}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & 0 & r \sin \theta \frac{\sin \theta}{r^2} \end{vmatrix} = \vec{1}_r 2C \frac{\cos \theta}{\mu r^3} + \vec{1}_\theta C \frac{\sin \theta}{\mu r^3}$$

$$\vec{J} = \operatorname{rot} \vec{H} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{1}_r & r \vec{1}_\theta & r \sin \theta \vec{1}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 2C \frac{\cos \theta}{\mu r^3} & rC \frac{\sin \theta}{\mu r^3} & 0 \end{vmatrix} = \frac{1}{r} \vec{1}_\phi \left( -2C \frac{\sin \theta}{\mu r^3} + 2C \frac{\sin \theta}{\mu r^3} \right) = 0 ; \text{ razen v izhodisču!}$$

Magnetni dipol  $I\Delta A \rightarrow \vec{V}_m = \vec{1}_\phi \frac{\mu}{4\pi r^2} I\Delta A \sin \theta \longrightarrow \text{dipol } I\Delta A = \frac{4\pi C}{\mu} \text{ v izhodisču}$

$$\textcircled{2} \quad \vec{V}_{m1} = \vec{1}_\phi \frac{\mu_0 I_1 r_1^2}{4} \frac{\sin \theta}{r^2} \text{ pri } r \gg r_1$$

$$M = \frac{1}{I_1} \oint_{2\pi} \vec{V}_{m1} d\vec{s}_2 = \frac{1}{I_1} \int_0^{2\pi} \vec{1}_\phi \frac{\mu_0 I_1 r_1^2}{4} \frac{1}{r_2} \cdot \vec{1}_\phi r_2 d\phi = \frac{\pi \mu_0 r_1^2}{2r_2}$$

$$\textcircled{3} \quad \vec{H} = \frac{j}{\omega \mu} \operatorname{rot} \vec{E} = \frac{j}{\omega \mu} \frac{1}{S} \begin{vmatrix} \vec{1}_\phi & S \vec{1}_\phi & \vec{1}_z \\ \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} & \frac{\partial}{\partial z} \\ \frac{C}{S} e^{ikz} & 0 & 0 \end{vmatrix} = \vec{1}_\phi \frac{Ck}{\omega \mu_0} \frac{1}{S} e^{-ikz} = \vec{1}_\phi \frac{C}{z} \frac{1}{S} e^{-ikz} ; z = \sqrt{\frac{\mu_0}{\epsilon}}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times H^* = \vec{1}_z \frac{|C|^2}{2z} \frac{1}{S^2} \quad P = \iint_A \vec{S} \cdot d\vec{A} = \iint_{a0}^{b2\pi} \vec{1}_z \frac{|C|^2}{2z} \frac{1}{S^2} \cdot d\phi dz d\phi = \frac{\pi |C|^2}{z} \ln \frac{b}{a}$$

$$\textcircled{4} \quad f = \frac{c_0}{2} \sqrt{\left(\frac{l}{a}\right)^2 + \left(\frac{m}{b}\right)^2 + \left(\frac{n}{c}\right)^2}$$

$$l=1, m=1, n=0 \rightarrow f_{110} = 5.02 \text{ GHz}$$

$$l=1, m=0, n=1 \rightarrow f_{101} = 5.43 \text{ GHz}$$

$$l=0, m=1, n=1 \rightarrow f_{011} = 5.70 \text{ GHz}$$

$$l=1, m=1, n=1 \rightarrow f_{111} = 6.60 \text{ GHz}$$

$$l=2, m=1, n=0 \rightarrow f_{210} = 7.65 \text{ GHz}$$

$$\textcircled{5} \quad \vec{S} = \vec{1}_z \cdot 1 \text{ W/m}^2 ; \vec{E} = \frac{\vec{1}_x + \vec{1}_y}{\sqrt{2}} E ; \vec{1}_s = \vec{1}_E \times \vec{1}_H \rightarrow \vec{1}_H = \vec{1}_s \times \vec{1}_E = \frac{-\vec{1}_x + \vec{1}_y}{\sqrt{2}}$$

$$H = \frac{E}{Z_0} ; \vec{H} = \vec{1}_H H = \frac{-\vec{1}_x + \vec{1}_y}{\sqrt{2}} \frac{E}{Z_0} ; \vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \vec{1}_z \frac{|E|^2}{2Z_0}$$

$$|E| = \sqrt{2Z_0 S} = 27.46 \text{ V/m}$$

$$|H| = \frac{|E|}{Z_0} = 0.073 \text{ A/m}$$

$$\vec{E} = \frac{\vec{1}_x + \vec{1}_y}{\sqrt{2}} \cdot 27.46 \text{ V/m} \cdot e^{j\varphi}$$

kjer je  $\varphi$  poljuben fazni kot!

$$\vec{H} = \frac{-\vec{1}_x + \vec{1}_y}{\sqrt{2}} \cdot 0.073 \text{ A/m} \cdot e^{j\varphi}$$

# Rešitev 1. kolokvija iz TEORIJE ELEKTROMAGNETIKE - 28/11/1997

$$\textcircled{1} \quad \vec{E} = -\text{grad } V = \vec{\lambda}_r V_0 \frac{2\sin\theta\cos\phi}{r^3} - \vec{\lambda}_\theta V_0 \frac{\cos\theta\cos\phi}{r^3} + \vec{\lambda}_\phi V_0 \frac{\sin\phi}{r^3}$$

$$g = \text{div}(\epsilon_0 \vec{E}) = \frac{\epsilon_0}{r^2 \sin\theta} \left( -V_0 \frac{2\sin^2\theta\cos\phi}{r^2} - V_0 \frac{(-\sin^2\theta + \cos^2\theta)\cos\phi}{r^2} + V_0 \frac{\cos\phi}{r^2} \right) = 0$$

Odvisnost  $r^{-2}$  → točkasti dipol v izhodišču!  $\sin\theta\cos\phi = \cos\theta_x \rightarrow$  dipol v smeri  $x$ !

$$V = V_0 \frac{\sin\theta\cos\phi}{r^2} = V_0 \frac{\cos\theta_x}{r^2} = \frac{Qd}{4\pi\epsilon_0} \frac{\cos\theta_x}{r^2} \rightarrow m = Q \cdot d = 4\pi\epsilon_0 V_0$$

$$\textcircled{2} \quad \text{Koordinate } (u, n, z): x = a \cosh u \cos n; y = a \sinh u \sin n; z = z$$

$$\Delta V = 0 \rightarrow V = C_1 u + C_2 \quad (\text{glej vaje na tabli dne 17/10/1997})$$

$$u \gg 1 \rightarrow g \approx \frac{a}{2} e^u; V \approx -\frac{q}{2\pi\epsilon_0} \ln g + C_3 \approx -\frac{q}{2\pi\epsilon_0} u + C_2 \rightarrow C_1 = -\frac{q}{2\pi\epsilon_0}$$

$$x=0; z=0 \rightarrow n = \frac{\pi}{2}; y = a \sinh u; u = \text{arsh} \frac{y}{a}; V = -\frac{q}{2\pi\epsilon_0} \text{arsh} \frac{y}{a} + C_2$$

$$\vec{E} = -\text{grad } V = -\vec{\lambda}_y \frac{d}{dy} \left( -\frac{q}{2\pi\epsilon_0} \text{arsh} \frac{y}{a} + C_2 \right) = \vec{\lambda}_y \frac{q}{2\pi\epsilon_0} \frac{1}{\sqrt{y^2 + a^2}} \quad \text{pri } y > 0$$

$$\text{pri } y < 0 \rightarrow n = \frac{3\pi}{2} \rightarrow \text{obraten predznak } \vec{E}$$

$$\textcircled{3} \quad \Delta V = 0 \rightarrow V = \sum_m C_m g^m \cos m\varphi; V\left(\varphi = \frac{\pi}{2}\right) = 0 \rightarrow m \frac{\alpha}{2} = (2k+1) \frac{\pi}{2}; k = 0, 1, 2, 3, 4, \dots$$

$$g = r_0 \rightarrow \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} V_0 \cosh^n \varphi d\varphi = \sum_m \left[ \sum_m C_m r_0^m \cos m\varphi \right] \cosh^n \varphi d\varphi$$

$$V_0 \alpha \frac{\sin \frac{\pi}{2}(2k+1)}{\frac{\pi}{2}(2k+1)} = C_m r_0^m \frac{\pi}{2} (2k+1) \frac{\alpha}{2} \rightarrow V = \sum_{k=0}^{\infty} 2V_0 \frac{\sin \frac{\pi}{2}(2k+1)}{\frac{\pi}{2}(2k+1)} \frac{q^{\frac{\pi}{2}(2k+1)}}{r_0^{\frac{\pi}{2}(2k+1)}} \cos \frac{\pi}{2k+1} \varphi$$

$$\textcircled{4} \quad V_2(r \geq r_0) = \frac{I}{A8} \left( r + \frac{r_0^3}{2r^2} \right) \cos\theta \quad (\text{glej vaje na tabli dne 21/11/1997})$$

$$z = r \cos\theta$$

$$\text{Znotraj mehurčka } (r \leq r_0): \Delta V_n = 0 \rightarrow V_n = C r \cos\theta$$

$$r = r_0 \rightarrow V_2 = V_N \quad ; \quad \frac{I}{A8} \left( r_0 + \frac{r_0^3}{2r_0^2} \right) \cos\theta = C r_0 \cos\theta \rightarrow C = \frac{3}{2} \frac{I}{A8} \quad ; \quad V_n = \frac{3I}{2A8} r \cos\theta = \frac{3I}{2A8} z$$

$$\vec{E} = -\text{grad } V_N = -\vec{\lambda}_z \frac{3I}{2A8}$$

$$\textcircled{5} \quad 4V_1 = 10 + 10 + V_5 + V_2 \quad \textcircled{1}-\textcircled{4} \quad V_1 - V_6 = 2.5 \quad V_6 = \frac{1}{12} (20 + 8V_5) = \frac{140}{22} = V_7$$

$$4V_2 = 10 + V_1 + V_6 + V_2 \quad \textcircled{1} \quad V_1 = V_6 + \frac{5}{2}$$

$$\textcircled{2} \quad 6V_2 = 25 + 4V_6 \quad V_1 = \frac{140}{22} + \frac{5}{2} = \frac{195}{22} = V_4$$

$$4V_5 = V_1 + 10 + (10 - V_5) + V_6 \quad \textcircled{3} \quad 10V_5 = 45 + 4V_6 / \cdot 3 \quad V_2 = \frac{5}{3} \frac{155}{22} - \frac{10}{3} = \frac{185}{22} = V_5$$

$$4V_6 = V_2 + V_5 + (10 - V_6) + V_6 \quad \textcircled{3}-\textcircled{2} \quad 10V_5 - 6V_2 = 20 \quad V_9 = V_{12} = 10 - V_5 = \frac{65}{22}$$

$$\textcircled{1} \quad 4V_1 = 20 + V_5 + V_2$$

$$\textcircled{2} \quad 3V_2 = 10 + V_1 + V_6$$

$$\textcircled{3} \quad 5V_5 = 20 + V_1 + V_6$$

$$\textcircled{4} \quad 4V_6 = 10 + V_2 + V_5$$

$$\textcircled{4} \quad \frac{V_2 = \frac{5}{3}V_5 - \frac{10}{3}}{12V_6 = 20 + 8V_5 / + 3 \cdot \textcircled{3}}$$

$$22V_5 = 155$$

$$V_5 = \frac{155}{22} = V_8$$

$$V_{10} = V_{11} = 10 - V_6 = \frac{80}{22}$$

$$V_{13} = V_{16} = 10 - V_1 = \frac{25}{22}$$

$$V_{14} = V_{15} = 10 - V_2 = \frac{35}{22}$$

## Rešitev 2. kolokvija iz ELEKTROMAGNETIKE - 16/1/1998

①  $\vec{H}_N = \vec{l}_z \frac{N}{\ell} I$     predpostavimo:  $\vec{A} = \vec{l}_q A_q(r)$  (iz smeri toka)

$\vec{H}_z = 0$      $\int_2^2 O E II$

$|\vec{H}| = \frac{1}{\mu_0} \frac{\partial}{\partial r} (\rho A_q)$

$\mu_0 |\vec{H}| = \frac{\partial}{\partial r} (\rho A_q) / S d\rho$

$\frac{\mu_0^2 |\vec{H}|}{2} + C = \rho A_q$

$\vec{H} = \frac{1}{\mu_0} \text{rot } \vec{A} = \frac{1}{\mu_0} \frac{1}{r} \begin{vmatrix} \vec{l}_s & \vec{r} \vec{l}_q & \vec{l}_z \\ \frac{\partial}{\partial \rho} & \frac{\partial}{\partial q} & \frac{\partial}{\partial z} \\ 0 & \rho \vec{A}_q & 0 \end{vmatrix} = \vec{l}_z \frac{1}{\mu_0} \frac{\partial}{\partial \rho} (\rho A_q)$

$A_q = \frac{\mu_0 |\vec{H}|}{2} + C/r$

Zvezan prehod:  $A_{qN}(r) = A_{qz}(r)$

Znotraj:  $A_{qN} = \frac{\mu_0 NI}{2\ell} + C_N/r$

Zunanj:  $A_{qz} = C_z/r$

$\vec{A}_N = \vec{l}_q \left( \frac{\mu_0 NI}{2\ell} + \frac{C_N}{r} \right); \vec{A}_z = \vec{l}_q \left( \frac{\mu_0 NI}{2\ell r} + \frac{C_z}{r} \right)$

② brez jeder:  $M^1 = \frac{\pi \mu_0 r_1^2 r_2^2}{2d^3}$  (vaje 9/1/98);  $\vec{B}$  v feromag. kroglici:  $\vec{B}_N = \frac{3\mu_r}{2+\mu_r} \vec{B}_0$  (vaje strani 152/153)

$\mu_r \rightarrow \infty \Rightarrow \vec{B}_N = 3\vec{B}_0$  eno jedro:  $M^4 = 3M^1 = \frac{3\pi \mu_0 r_1^2 r_2^2}{2d^3}$

dve jcdri (recipročnost M!):  $M = 3M^4 = 9M^1 = \frac{9\pi \mu_0 r_1^2 r_2^2}{2d^3}$

③ Prestopni pogoji:  $\vec{E}_x = E_{x0} \cos \frac{\pi}{a} x \sin \frac{\pi}{b} y \sin \frac{\pi}{c} z$ ;  $\vec{E}_y = E_{y0} \sin \frac{\pi}{a} x \cos \frac{\pi}{b} y \sin \frac{\pi}{c} z$  (isti tk!)

Prostorske elektrine ni:  $0 = \text{div } \vec{D} = \text{div } \epsilon \vec{E}$ ;  $0 = \text{div } \vec{E} = E_{x0} \frac{\pi}{a} \sin \frac{\pi}{a} x \sin \frac{\pi}{b} y \sin \frac{\pi}{c} z + E_{y0} \frac{\pi}{b} \sin \frac{\pi}{a} x \cos \frac{\pi}{b} y \sin \frac{\pi}{c} z + E_{z0} \frac{\pi}{c} \sin \frac{\pi}{a} x \sin \frac{\pi}{b} y \sin \frac{\pi}{c} z$

$O = E_{x0} \frac{\pi}{a} + E_{y0} \frac{\pi}{b} + E_{z0} \frac{\pi}{c}$

$E_{x0} = -a \left( \frac{E_{y0}}{b} + \frac{E_{z0}}{c} \right)$

$k^2 = \omega^2 \cdot \mu_0 \epsilon_0 = k_x^2 + k_y^2 + k_z^2 = \left(\frac{\pi}{a}\right)^2 + \left(\frac{\pi}{b}\right)^2 + \left(\frac{\pi}{c}\right)^2; \frac{1}{\sqrt{\mu_0 \epsilon_0}} = c_0$

$\omega = c_0 \pi \sqrt{\frac{1}{a^2} + \frac{1}{b^2} + \frac{1}{c^2}}$ ;  $f = \frac{c_0}{2} \sqrt{\frac{1}{a^2} + \frac{1}{b^2} + \frac{1}{c^2}}$

④  $|\vec{H}| = 2|\vec{H}_v| = 2\sqrt{\frac{2|S|}{Z_0}}$ ;  $|S| = \frac{1}{2} |\vec{H}|^2 Z_0$ ;  $|\vec{K}| = |\vec{H}| = 2\sqrt{\frac{2S}{Z_0}}$ ;  $P = \frac{dP}{dA} = \frac{1}{2} |\vec{K}|^2 R_p$

$P = \frac{1}{2} \left( 4 \frac{2S}{Z_0} \right) R_p = \frac{4R_p}{Z_0} S = \frac{4S}{Z_0} \sqrt{\frac{\omega \mu_0}{28}} = 4S \sqrt{\frac{\pi f \epsilon_0}{8}} = 0.282 \text{ W/m}^2$

$R_p = \sqrt{\frac{\omega \mu_0}{28}}$

⑤  $\vec{A} = \frac{\mu_0}{4\pi} \int_{\Gamma} \frac{\vec{r}_q(\vec{r}')}{|\vec{r}-\vec{r}'|^3} e^{-jk|\vec{r}-\vec{r}'|} d\Gamma \approx \frac{\mu_0}{4\pi} \frac{e^{-ikr}}{r} \int_A \vec{K}(\vec{r}') dA = \vec{l}_x \frac{\mu_0}{4\pi} K_0 a^2 \frac{e^{-ikr}}{r}$

$\vec{l}_x = \vec{l}_r \sin \theta \cos \phi + \vec{l}_\theta \cos \theta \cos \phi - \vec{l}_\phi \sin \phi$ ;  $\vec{A} = (\vec{l}_r \sin \theta \cos \phi + \vec{l}_\theta \cos \theta \cos \phi - \vec{l}_\phi \sin \phi) \frac{\mu_0}{4\pi} K_0 a^2 \frac{e^{-ikr}}{r}$

$\vec{H} = \frac{1}{\mu_0} \text{rot } \vec{A} = \frac{K_0 a^2}{4\pi} \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{l}_r & r \vec{l}_\theta & r \sin \theta \vec{l}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ \frac{e^{ikr}}{r} \sin \theta \cos \phi & e^{ikr} \cos \theta \cos \phi & -e^{ikr} \sin \theta \sin \phi \end{vmatrix} = \frac{K_0 a^2}{4\pi} \frac{e^{-ikr}}{r} \left( \frac{1}{r} + jk \right) \left[ -\vec{l}_\theta \sin \phi - \vec{l}_\phi \cos \theta \cos \phi \right]$

$$1) \quad \vec{E} = \vec{1}_\theta C \frac{e^{-jkr}}{r \sin \theta} \quad h_r = 1 \quad h_\phi = r \quad h_\theta = r \sin \theta$$

Prostorske veličine → izračunamo iz Maxwellovih enačb

$$\vec{H} = -\frac{1}{j\omega\mu_0} \text{rot} \vec{E} = -\frac{C}{j\omega\mu_0} \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{1}_r & r\vec{1}_\theta & r \sin \theta \vec{1}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & \frac{e^{-jkr}}{\sin \theta} & 0 \end{vmatrix} = \vec{1}_\phi \frac{C}{Z_0} \frac{e^{-jkr}}{r \sin \theta}$$

$$\text{rot} \vec{H} = \frac{1}{r^2 \sin \theta} \frac{C}{Z_0} \begin{vmatrix} \vec{1}_r & r\vec{1}_\theta & r \sin \theta \vec{1}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & 0 & e^{-jkr} \end{vmatrix} = \vec{1}_\theta j C \epsilon_0 \omega \frac{e^{-jkr}}{\sin \theta}$$

$$\vec{J} = \text{rot} \vec{H} - j\omega \epsilon_0 \vec{E} = \vec{1}_\theta j C \epsilon_0 \omega \frac{e^{-jkr}}{r \sin \theta} - \vec{1}_\theta j C \epsilon_0 \omega \frac{e^{-jkr}}{r \sin \theta} = 0$$

$$\rho = \text{div}(\epsilon \vec{E}) = C \epsilon_0 \frac{1}{r^2 \sin \theta} \left( \frac{\partial}{\partial \theta} r \sin \theta \frac{e^{-jkr}}{r \sin \theta} \right) = 0$$

Ploskovne veličine

$$\vec{K} = 0 \quad \text{in } \sigma = -\frac{1}{j\omega} \text{div} \vec{K} = 0 \rightarrow N \text{ singularnih ploskev}$$

3. Preme veličine, singularnost pri  $\theta = 0, \pi$  na osi z različno za + / - z

$$I = \oint \vec{H} \cdot d\vec{s} = \frac{C}{Z_0} \int_0^{2\pi} \frac{e^{-jkr}}{r \sin \theta} r \sin \theta d\theta d\phi = \frac{C}{Z_0} 2\pi e^{-jkr}$$

$$dQ = \oint \vec{D} \cdot d\vec{A}$$

$$dQ = \int_0^{2\pi} \vec{1}_\theta \epsilon_0 C \frac{e^{-jkr}}{r \sin \theta} dr \vec{1}_\theta r \sin \theta d\phi$$

$$dQ = \epsilon_0 C \frac{e^{-jkr}}{1} dr 2\pi = q dr$$

$$q = 2\pi \epsilon_0 C e^{-jkr}$$

4. Točkasta veličina v koordinatnem izhodišču

$$Q|_{r=0} = \int_{k \rightarrow 0} \vec{D} \cdot d\vec{A} = \int_V \text{div} \vec{D} dv = 0$$

2) Valjni eliptični koordinatni sistem ( $u, v, z$ )

$$x = f \cosh u \cos v$$

$$y = f \sinh u \sin v$$

$$z = z$$

$$\Delta V = 0 \quad \frac{\partial}{\partial u} = 0 \quad \frac{\partial}{\partial z} = 0$$

$$hu = f \sqrt{\sinh u^2 + \sin v^2}$$

$$hv = f \sqrt{\sinh u^2 + \sin v^2}$$

$$hz = 1$$

$$\Delta V = \text{div}(\text{grad} V) = \frac{1}{f^2 (\sinh u^2 + \sin v^2)} \left[ \frac{\partial^2 V}{\partial^2 u} + \frac{\partial^2 V}{\partial^2 v} \right] + \frac{\partial^2 V}{\partial^2 z} = 0$$

$$0 = \frac{1}{f^2 (\sinh u^2 + \sin v^2)} \frac{\partial^2 V}{\partial^2 v} \rightarrow V = C_1 v + C_2$$

$$10V = C_1 0 + C_2 \rightarrow C_2 = 10V$$

$$0V = C_1 \frac{\pi}{2} + C_2$$

$$C_1 = -\frac{2}{\pi} C_2 = -\frac{20V}{\pi}$$

$$V = -\frac{20V}{\pi} v + 10V$$



$$\text{Točka } T: u = 0 \quad x = \frac{f}{2}$$

$$\frac{f}{2} = f * 1 * \cos v \rightarrow v = \frac{\pi}{3}$$

$$V(T) = \frac{20V}{\pi} \frac{\pi}{3} + 10V = 3,33V$$

## Elektromagnetika 1.kolokvij 9.12.1998, řešitve

3) Najprej določimo polje v levih polovicih korita. V desni polovici je porazdelitev potenciala zrcalno simetrična

$$\Delta V = 0 \quad V(a-x, y) = -V(x, y)$$

$$a) 0 \leq x \leq \frac{a}{2}$$

$$V(x, y) = \sum_m C_m \sin\left(\frac{m\pi}{a/2}x\right) \sinh\left(\frac{m\pi}{a/2}y\right) \rightarrow V(x, y=b) = \sum_m C_m \sin\left(\frac{m\pi}{a/2}x\right) \sinh\left(\frac{m\pi}{a/2}b\right) = V_0$$

S Fourierjevo analizo dolžčino koeficiente  $C_m$

$$\int_0^{a/2} V_0 \sin\left(\frac{m\pi}{a/2}x\right) dx + \int_{a/2}^a (-V_0) \sin\left(\frac{m\pi}{a/2}x\right) dx = \sum_m C_m \sin\left(\frac{m\pi}{a/2}x\right) \sinh\left(\frac{m\pi}{a/2}b\right) \sin\left(\frac{m\pi}{a/2}x\right) dx$$

$$\left( \frac{V_0}{2} \left( 2 \sin\left(\frac{\pi m}{2}\right)^2 - (\cos(mx) - \cos(2m\pi)) \right) \right) = C_m \sinh\left(\frac{m\pi}{a}b\right) \frac{a}{8} \left( \frac{4m\pi - \sin(4m\pi)}{m\pi} \right)$$

če je m.sodo

$$\frac{2V_0a}{m\pi} = \frac{a}{2} C_m \sinh\left(\frac{m\pi}{a/2}b\right) \rightarrow C_m = \begin{cases} 0 \\ \frac{4V_0}{m\pi} \sinh\left(\frac{m\pi}{a/2}b\right) \end{cases} \quad \text{če je m liho}$$

b) Upoštevamo zrcalno simetrijo, saj je  $\sin\left(\frac{(2k+1)\pi(a-x)}{a/2}\right) = -\sin\left(\frac{(2k+1)\pi x}{a/2}\right)$

$$V(x, y) = \sum_{k=0}^{\infty} \frac{4V_0}{(2k+1)\pi} \sinh\left(\frac{(2k+1)\pi}{a/2}b\right) \sin\left(\frac{(2k+1)\pi}{a/2}x\right) \sinh\left(\frac{(2k+1)\pi}{a/2}y\right)$$

$$4) \quad \Delta V(r, \theta, \Phi) = 0 \quad \frac{\partial}{\partial \Phi} = 0 \quad V(\infty) \rightarrow \infty$$

$$V(r, \theta) = \sum_{n=0}^{\infty} B_n r^{-(n+1)} P_n(\cos\theta) \quad za \quad r > r_0$$

$$B_n = \frac{1}{r_0^n} \frac{-V_0 \int_{-1}^0 P_n(t) dt + V_0 \int_0^1 P_n(t) dt}{\int_{-1}^1 P_n^2(t) dt} \quad V(\cos\theta) = \begin{cases} +V_0; & 1 > \cos\theta > 0 \\ -V_0; & 0 > \cos\theta \geq -1 \end{cases}$$

$$B_n = \frac{1}{r_0^n} \frac{-V_0 \int_{-1}^0 P_n(t) dt + V_0 \int_0^1 P_n(t) dt}{\int_{-1}^1 P_n^2(t) dt} \quad ; \quad t = \cos\theta \rightarrow B_n = \frac{2n+1}{n(n+1)a^n} V_0 P_n(0)$$

Koeficienti  $B_n : B_{2K} = 0 \quad K = 1, 2, \dots$

$$B_{2K-1} = V_0 r_0^{2K} [P_{2K}(0) - P_{2K-2}(0)]$$

Funkcija potenciala za  $r > r_0$

$$V(r, \theta) = V_0 \sum_{K=1}^{\infty} \frac{P_{2K}(0) - P_{2K-2}(0)}{r^{2K}} r_0^{-2K} P_{2K-1}(\cos\theta)$$

Poenostavimo za  $r > r_0$

$$za \quad K = 1 \quad V(r, \theta) = V_0 \frac{3}{2} \frac{r_0^2}{r^2} \cos\theta$$

$$za \quad K = 2 \quad V(r, \theta) = V_0 \frac{7}{8} \frac{r_0^4}{r^4} (5 \cos\theta^3 - 3 \cos\theta)$$

$$za \quad K = 3 \quad V(r, \theta) = V_0 \frac{3}{16} \frac{r_0^6}{r^6} (63 \cos\theta^5 - 70 \cos\theta^3 + 15 \cos\theta)$$

$$V(r, \theta) = V_0 \frac{3}{2} \frac{r_0^2}{r^2} \cos\theta \quad za \quad r > r_0$$

$$5) \quad \vec{E} = -\vec{j}_y \frac{IR\rho}{a} \quad V = \frac{IR\rho}{a} y + V_0$$

$$P = \gamma E^2 \quad P_1 = 2P_2 \quad \gamma E_1^2 = 2\gamma E_2^2 \quad E_2 = \frac{E_1}{\sqrt{2}}$$

Nastavek:

$$V = (A\rho + B\rho^{-1}) \sin\varphi \rightarrow V = A\rho \sin\varphi \approx \frac{IR\rho}{a} y \quad A = \frac{IR\rho}{a}$$

$$\rho = r \rightarrow V = 0 = (A\rho + B\rho^{-1}) \sin\varphi \Big|_{\rho=r}$$

$$B = -Ar^2 = \frac{IR\rho}{a} r^2$$

$$\vec{K}_0 = -\vec{j}_y \frac{I}{W} \quad E_0 = \vec{K}_0 \cdot RP = \vec{j}_y \frac{IR\rho}{a} \quad V = \frac{IR\rho}{a} (\rho - \frac{r^2}{\rho}) \sin\varphi$$

$$V_1 = (-E_0\rho + \frac{B}{\rho}) \sin\varphi \quad V_2 = A\rho \sin\varphi$$

$$\vec{E}_1 = -grad V_1 = \vec{j}_\rho (E_0 + \frac{B_1}{\rho^2}) \sin\varphi + \vec{i}_\rho (E_0 - \frac{B_1}{\rho^2}) \cos\varphi$$

$$\vec{E}_2 = -grad V_2 = -\vec{j}_\rho A \sin\varphi - \vec{i}_\rho A \cos\varphi = -\vec{j}_y A$$

$$Prestopni pogoji: \begin{cases} E_{\varphi 1} = E_{\varphi 2} \rightarrow (E_0 + \frac{B_1}{\rho^2}) \sin\varphi \rightarrow E_0 - \frac{B_1}{\rho^2} \\ K_{\rho 1} = K_{\rho 2} \rightarrow (E_0 + \frac{B_1}{\rho^2}) \sin\varphi \frac{1}{R_{\rho 1}} = \frac{A_2}{R_{\rho 2}} \sin\varphi \rightarrow E_0 + \frac{B_1}{\rho^2} = -A \frac{R_{\rho 1}}{R_{\rho 2}} \end{cases}$$

$$\vec{E}_1 = \vec{j}_\rho (-A \frac{R_{\rho 1}}{R_{\rho 2}}) \sin\varphi + \vec{i}_\rho (-A) \cos\varphi = -\vec{j}_\rho A \frac{R_{\rho 1}}{R_{\rho 2}} \sin\varphi - \vec{i}_\rho A \cos\varphi$$

$$\vec{E}_2 = -\vec{j}_\rho A \sin\varphi - \vec{i}_\rho A \cos\varphi$$

$$2E_0 = -A(1 + \frac{R_{\rho 1}}{R_{\rho 2}}) = E_2 (1 + \frac{R_{\rho 1}}{R_{\rho 2}})$$

$$\frac{2E_0}{E_2} = 1 + \frac{R_{\rho 1}}{R_{\rho 2}} \rightarrow R_{\rho 2} = R_{\rho 1} \frac{1}{2E_0 - 1} = \frac{100\Omega}{2E_1 \sqrt{2} - 1} = \underline{\underline{54,69\Omega}}$$

$1) \quad r_0 = 1m \quad d = 30m \quad I = 10A \quad \Delta V = ?$ $A_n = I_\Delta \phi = -\Delta W \quad d \ll r_0$ $M_{12} = \frac{\phi_{12}}{I_L} \quad \Delta \phi = -2\phi_D$ $M = \frac{\pi \mu_0 N_1 N_2 a^2 a^2}{2d^3} = \frac{\pi 4\pi 10^{-7} 1H}{2 \cdot 30^3} = 7,31 \cdot 10^{-11} H$ $\Delta W = I \cdot 2\phi_D = I^2 2M = \underline{\underline{1,462 \cdot 10^{-8} Ws}}$	$3) \quad W = 20mm \quad d = 5mm \quad f = 100MHz \quad \vec{H} = \vec{1}_x H_0 e^{-jk_0 z} \quad H_0 = 100A/m$ $\vec{E} = ? \quad \vec{S} = ? \quad \vec{P} = ? \quad \vec{U} = ? \quad \vec{I} = ?$ $\vec{E} = \frac{1}{j\omega \epsilon_0} rot \vec{H} = \frac{1}{j\omega \epsilon_0} \left  \begin{array}{ccc} \vec{1}_x & \partial & \partial \\ \partial & \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ H_0 e^{-jk_0 z} & 0 & 0 \end{array} \right  = \frac{1}{j\omega \epsilon_0} (\vec{1}_y H_0 e^{-jk_0 z} (-jk)) = -\frac{H_0 k}{\omega \epsilon_0} \vec{1}_y e^{-jk_0 z} =$ $-\vec{1}_y H_0 Z_0 e^{-jk_0 z} = -\vec{1}_y E_0 e^{-jk_0 z} = -\vec{1}_y 37699 \frac{V}{m} e^{-jk_0 z}$
$2) \quad r_o = 1mm \quad l = 10m \quad f = 1MHz \quad \gamma_{cu} = 56 \cdot 10^6 S/m$ $\delta \ll r_0 \quad in \quad l \ll \lambda \quad \frac{R_\sim}{R_\equiv} = ?$ $R_\equiv = \frac{l}{\gamma A} = \frac{l}{\gamma \pi r_0} = \frac{10\Omega}{56 \cdot 10^{-6} \pi (1 \cdot 10^{-3})^2} = 56,8 \cdot 10^{-3} \Omega$ $\delta = \sqrt{\frac{2}{\alpha \mu_0 \gamma}} = 67,25 \cdot 10^{-6} m$ $R_\sim = \frac{l}{\gamma A_\sim} = \frac{l}{\gamma 2\pi r \delta} = 422,6 \cdot 10^{-3} \Omega$	$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \left  \begin{array}{ccc} \vec{1}_x & \vec{1}_y & \vec{1}_z \\ 0 & -H_0 Z_0 e^{-jk_0 z} & 0 \\ H_0 e^{+jk_0 z} & 0 & 0 \end{array} \right  = \vec{1}_z \frac{Z_0 H_0^2}{2} = \vec{1}_z 1,88 M \frac{W}{m^2}$ $P = \int_A S dA = \int_0^w \int_0^d \frac{Z_0 H_0^2}{2} dx dy = \frac{Z_0 H_0^2}{2} wd = \underline{\underline{188,496 W}}$ $\vec{K} = \vec{1}_n \times \vec{H} \Big _{y=0} = \vec{1}_y \times \vec{1}_x H_0 e^{-jk_0 z} = \left  \begin{array}{ccc} \vec{1}_x & \vec{1}_y & \vec{1}_z \\ 0 & 1 & 0 \\ H_0 e^{-jk_0 z} & 0 & 0 \end{array} \right  = -\vec{1}_z H_0 e^{-jk_0 z} = -\vec{1}_z 100 \frac{A}{m} e^{-jk_0 z}$ $I = \int_o \vec{K} \vec{ds} = \int_o H_0 e^{-jk_0 z} dx = H_0 w e^{-jk_0 z} = I_0 e^{-jk_0 z} = \pm 2A e^{-jk_0 z} \rightarrow \pm \frac{gornja plosča}{spodnja plosča}$ $U = -\int \vec{E} \vec{ds} = -\int_0^d (-\vec{1}_y) \frac{H_0 k}{\omega \epsilon_0} e^{-jk_0 z} \vec{1}_y dy = \frac{H_0 k}{\omega \epsilon_0} de^{-jk_0 z} = H_0 Z_0 de^{-jk_0 z} = U_0 e^{-jk_0 z} = \underline{\underline{188,4V e^{-jk_0 z}}}$

$$\begin{aligned}
 4) \quad & a = 1\text{cm} \quad b = 2\text{cm} \quad c = 3\text{cm} \quad f_{MN} = 1\text{GHz} \quad \epsilon_r = ? \\
 & f = \frac{1}{2\sqrt{\epsilon_0 \epsilon_r \mu_0}} = \sqrt{\left(\frac{m}{a}\right)^2 + \left(\frac{n}{b}\right)^2 + \left(\frac{p}{c}\right)^2} \\
 & f_{\min} = f_{011} \quad m, n, p \rightarrow \text{cela števila, vsaj 2 različna od 0} \\
 & f^2 = \frac{1}{4\epsilon_0 \epsilon_r \mu_0} \left[ \left(\frac{1}{b}\right)^2 + \left(\frac{1}{c}\right)^2 \right] \quad \text{poisčemo 2 največja izmed } a, b, c \\
 & \epsilon_r = \frac{c_o^2}{4f} \left( \left(\frac{1}{b}\right)^2 + \left(\frac{1}{c}\right)^2 \right) = \\
 & \frac{3 * 10^8}{4(1 * 10^9)^2} \left[ \left(\frac{1}{0,02}\right)^2 + \left(\frac{1}{0,03}\right)^2 \right] = \underline{\underline{81,176}}
 \end{aligned}$$

$  \begin{aligned}  5) \quad & \epsilon_r = 2 \quad f = 10\text{GHz} \quad Z_0 = \sqrt{\frac{\mu_0}{\epsilon_r}} = \sqrt{\frac{Z_0}{\epsilon_r}} = \sqrt{\frac{\mu_0}{\epsilon_r}} = \sqrt{\frac{Z_0}{\epsilon_r}} \\  & \vec{E}_{1+} = \vec{1}_x A_{1+} e^{-jk_0 z} \quad \vec{H}_{1+} = \frac{j}{\omega \mu_0} \text{rot} \vec{E}_{1+} = \frac{j}{\omega \mu_0} \left  \begin{array}{c} \vec{1}_x \\ \frac{\partial}{\partial x} \\ A_{1+} e^{-jk_0 z} \\ 0 \end{array} \right  = \vec{1}_y \frac{A_{1+}}{Z_0} e^{-jk_0 z} \\  & \vec{E}_{1-} = \vec{1}_x A_{1-} e^{jk_0 z} \quad \vec{H}_{1-} = -\vec{1}_y \frac{A_{1-}}{Z_0} e^{jk_0 z} \quad \vec{E}_{2+} = \vec{1}_x A_{2+} e^{-jk_0 z} \\  & \vec{H}_{2+} = \vec{1}_y \frac{A_{2+}}{Z} e^{-jk_0 z} \rightarrow \vec{1}_{E_{1-}} \times \vec{1}_{H_{1-}} = -\vec{1}_z \text{ orbiti val} \\  & pri \quad z = 0: \quad \vec{E}_{1+} + \vec{E}_{1-} = \vec{E}_{2+} \rightarrow A_{1+} + A_{1-} = A_{2+} \\  & \vec{H}_{1+} + \vec{H}_{1-} = \vec{H}_{2+} \rightarrow \frac{A_{1+}}{Z_0} - \frac{A_{1-}}{Z_0} = \frac{A_{2+}}{Z} \rightarrow A_{2+} = \frac{Z}{Z_0} (A_{1+} - A_{1-}) \\  & A_{1+} + A_{1-} = \frac{Z}{Z_0} (A_{1+} - A_{1-}) \rightarrow A_{1-} = \frac{Z - Z_0}{Z + Z_0} A_{1+} = -\frac{\sqrt{\epsilon_r} - 1}{\sqrt{\epsilon_r} + 1} A_{1+} \\  & \Gamma = \frac{A_{1-}}{A_{1+}} = -\frac{\sqrt{2} - 1}{\sqrt{2} + 1} = -0,172 \quad A_{2+} = A_{1+} + A_{1-} = (1 + \Gamma) A_{1+} \\  & \vec{S}_{2+} = \vec{S}_2 = \frac{1}{2} \vec{E}_{2+} \times \vec{H}_{2+}^* = \frac{1}{2} \vec{1}_x (1 + \Gamma) A_{1+} e^{-jk_0 z} \times \vec{1}_y \frac{(1 + \Gamma) A_{1+}^*}{Z} e^{jk_0 z} = \vec{1}_z \frac{(1 + \Gamma)^2 A_{1+}^2}{2Z} = \\  & \underline{\underline{\vec{1}_z 0,515 \frac{W}{m^2}}}  \end{aligned}  $	$  \begin{aligned}  & \vec{S}_1 = \frac{1}{2} (\vec{E}_{1+} + \vec{E}_{1-}) \times (\vec{H}_{1+} + \vec{H}_{1-})^* = \frac{1}{2} \vec{1}_x (A_{1+} e^{jk_0 z} + \Gamma A_{1+} e^{jk_0 z}) \times \vec{1}_y \left( \frac{A_{1+}}{Z_0} e^{jk_0 z} - \frac{\Gamma A_{1+}}{Z_0} e^{-jk_0 z} \right) = \\  & \vec{1}_z \frac{A_{1+}^2}{2Z_0} (e^{-jk_0 z} + \Gamma e^{jk_0 z}) (e^{jk_0 z} + \Gamma e^{-jk_0 z}) = \vec{1}_z \frac{ A_{1+} ^2}{Z_0} (1 -  \Gamma ^2 + j2\Gamma \sin 2k_0 z) = \\  & \underline{\underline{\vec{1}_z 0,531 \frac{W}{m^2} (0,971 + j0,343 \sin 2k_0 z)}}  \end{aligned}  $
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Rešitev pisnega izpita iz ELEKTROMAGNETIKE (UNI) - 5/3/1999

$$\textcircled{1} (\eta, \psi, \phi) \rightarrow x = a \operatorname{ch} \eta \sin \psi \cos \phi; y = a \operatorname{ch} \eta \sin \psi \sin \phi; z = a \operatorname{sh} \eta \cos \psi$$

$$h_y = h_\psi = a \sqrt{\operatorname{sh}^2 \eta + \cos^2 \psi}; h_\phi = a \operatorname{ch} \eta \sin \psi; \text{ Geometrija naloge: } \frac{\partial}{\partial \psi} = \frac{\partial}{\partial \phi} = 0$$

$$0 = \Delta V = \frac{1}{h_y h_\psi h_\phi} \frac{\partial}{\partial \eta} (h_\psi h_\phi \frac{1}{h_y} \frac{\partial V}{\partial \eta}) \rightarrow 0 = \frac{\partial}{\partial \eta} (\operatorname{ch} \eta \frac{\partial V}{\partial \eta}) \rightarrow \frac{\partial V}{\partial \eta} = \frac{C}{\operatorname{ch} \eta}$$

$$\vec{D} = \epsilon \vec{E} = -\epsilon \operatorname{grad} V = -\vec{\eta} \frac{1}{h_y} \frac{\partial V}{\partial \eta} = \vec{\eta} \frac{-\epsilon C}{h_y \operatorname{ch} \eta} ; z=0 \rightarrow \eta=0; \operatorname{ch} \eta=1; h_y = \sqrt{a^2 - x^2 - y^2}$$

$$\vec{G} = \vec{\lambda}_n \cdot \vec{D} = \frac{-2\epsilon C}{\sqrt{a^2 - x^2 - y^2}}; Q = \iint_0^{a\pi} G(\rho, \varphi) \rho d\rho d\varphi = -4\pi \epsilon C \int_0^a \frac{\rho d\rho}{\sqrt{a^2 - \rho^2}} = -4\pi \epsilon C a \rightarrow C = \frac{-Q}{4\pi \epsilon a}$$

$$\textcircled{2} \Delta V=0 \rightarrow V(\rho, \psi, z) = \sum_n C_n \rho^n \cos n(\psi - \frac{\pi}{2}); \text{ SAMO SODI}$$

$$h \ll a \rightarrow n=2 \text{ zadostja} \quad \int_{\frac{\pi}{4}}^{\frac{3\pi}{4}} \sum_n C_n \rho^n \cos n(\psi - \frac{\pi}{2}) \cos 2(\psi - \frac{\pi}{2}) d\psi = \int_{\frac{\pi}{4}}^{\frac{3\pi}{4}} V_0 \cos 2(\psi - \frac{\pi}{2}) d\psi = V_0 = \frac{\pi}{4} C_2 a^2$$

$$C_2 = \frac{4V_0}{\pi a^2} ; V(\rho=h; \psi=\frac{\pi}{2}; z) = C_2 \rho^2 \cos 2(\psi - \frac{\pi}{2}) = \frac{4V_0}{\pi a^2} \cdot h^2 \cdot 1 = \frac{4V_0 h^2}{\pi a^2} = 1.91 \text{ mV}$$

$$\textcircled{3} \vec{A} = \vec{\lambda}_{\phi_x} \frac{\mu_0 I a^2}{4\pi r^2} \sin \theta_x; \text{ koordinate } (r, \theta_x, \phi_x) \quad \sin \theta_x = \sqrt{1 - \sin^2 \theta \cos^2 \phi}$$

$$\vec{\lambda}_{\phi_x} = -\vec{\lambda}_\theta \frac{\sin \phi}{\sqrt{1 - \sin^2 \theta \cos^2 \phi}} - \vec{\lambda}_\phi \frac{\cos \theta \cos \phi}{\sqrt{1 - \sin^2 \theta \cos^2 \phi}}$$

$$\vec{A} = \frac{\mu_0 I a^2}{4\pi r^2} (-\vec{\lambda}_\theta \sin \phi - \vec{\lambda}_\phi \cos \theta \cos \phi)$$

$$\textcircled{4} \operatorname{rot} \vec{E} = -j\omega \mu \vec{H} \rightarrow \vec{H} = \frac{j\omega \mu}{\omega \mu} \operatorname{rot} \vec{E} = -\vec{\lambda}_x \frac{\omega \mu}{\omega \mu} \cos \alpha x e^{-j\beta_2} - \vec{\lambda}_z \frac{j\omega \mu}{\omega \mu} \sin \alpha x e^{-j\beta_2}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \vec{\lambda}_x \frac{j\omega \mu}{2\omega \mu} \cos \alpha x \sin \alpha x + \vec{\lambda}_z \frac{\omega \mu}{2\omega \mu} \cos^2 \alpha x \quad g = \operatorname{div} \vec{E} = 0$$

$$\vec{y} = \operatorname{rot} \vec{H} - j\omega \epsilon \vec{E} = \vec{\lambda}_y \left( \frac{j\omega \mu}{\omega \mu} \cos \alpha x e^{-j\beta_2} + \frac{j\omega^2}{\omega \mu} \cos \alpha x e^{-j\beta_2} \right) - j\omega \epsilon \vec{\lambda}_y \cos \alpha x e^{-j\beta_2} = 0$$

$$\textcircled{5} Z_K = \frac{d}{w} Z_0; dR = \frac{2dz}{w \operatorname{tg} \gamma} = \frac{2dz}{w \gamma \sqrt{\frac{2}{\operatorname{tg} \gamma}}} = \frac{2}{w} \sqrt{\frac{\omega \mu}{2\gamma}} dz$$

$$\frac{dP}{P} = -\frac{dR}{Z_K} = -\frac{2}{w Z_K} \sqrt{\frac{\omega \mu}{2\gamma}} dz \rightarrow \ln P = -\frac{2l}{w Z_K} \sqrt{\frac{\omega \mu}{2\gamma}} + C$$

$$A [\text{dB}] = 10 \log_{10} \frac{P(l)}{P(0)} = \frac{10}{\ln 10} \frac{2l}{w Z_K} \sqrt{\frac{\omega \mu}{2\gamma}} ; \mu = \mu_0 \text{ za baker}$$

$$A/l = \frac{10}{\ln 10} \frac{2}{w Z_K} \sqrt{\frac{\omega \mu_0}{2\gamma}} = \frac{10}{\ln 10} \frac{2}{d Z_0} \sqrt{\frac{\omega \mu_0}{2\gamma}} = 0.0061 \text{ dB/m} = 6.1 \text{ dB/km}$$

# Rešitev pisnega izpita iz ELEKTROMAGNETIKE - 9/7/1999

① A)  $\boxed{V_0}$   $\rightarrow V_A = \sum_{k=0}^{\infty} \frac{4V_0}{(2k+1)\pi} \sin \frac{(2k+1)\pi}{a} y \times \frac{\operatorname{sh} \frac{(2k+1)\pi}{a} y}{\operatorname{sh} (2k+1)\pi}$

B)  $\boxed{V_0}$   $\rightarrow V_B = \sum_{k=0}^{\infty} \frac{4V_0}{(2k+1)\pi} \sin \frac{(2k+1)\pi}{a} y \times \frac{\operatorname{sh} \frac{(2k+1)\pi}{a} (a-y)}{\operatorname{sh} (2k+1)\pi}$

$\boxed{V_0}$   $\rightarrow V = V_A + V_B = \sum_{k=0}^{\infty} \frac{4V_0}{(2k+1)\pi \operatorname{sh} (2k+1)\pi} \left( \sin \frac{(2k+1)\pi}{a} y \operatorname{sh} \frac{(2k+1)\pi}{a} y + \sin \frac{(2k+1)\pi}{a} y \operatorname{sh} \frac{(2k+1)\pi}{a} (a-y) \right)$

②  $(\mu, n, z)$   $\frac{\partial}{\partial n} = \frac{\partial}{\partial z} = 0 \rightarrow V = A \mu + B$   $M = -\frac{2\pi \epsilon_0 V}{a}$   $\cos N = \frac{x}{a} = \sqrt{1 - \sin^2 N} = \sqrt{1 - \left(\frac{y}{a}\right)^2}$

$x = a \operatorname{ch} \mu \cos N \quad \Delta V = 0$

$y = a \operatorname{sh} \mu \sin N \quad V(\mu=0)=0 \rightarrow B=0$

$z=z$

$A = -\frac{q}{2\pi \epsilon_0} \rightarrow V = -\frac{q}{2\pi \epsilon_0} \mu$

PLANEV:

$x = a \operatorname{ch} \left(-\frac{2\pi \epsilon_0 V}{q}\right) \cos N = \alpha \cos N$

$\left(\frac{x}{a}\right)^2 + \left(\frac{y}{a}\right)^2 = 1$

$y = a \operatorname{sh} \left(-\frac{2\pi \epsilon_0 V}{q}\right) \sin N = \beta \sin N$

$\left(\frac{x}{a \operatorname{ch} \left(-\frac{2\pi \epsilon_0 V}{q}\right)}\right)^2 + \left(\frac{y}{a \operatorname{sh} \left(-\frac{2\pi \epsilon_0 V}{q}\right)}\right)^2 = 1$

ENAČBA ELIPSE  
(v eliptičnega prereza)

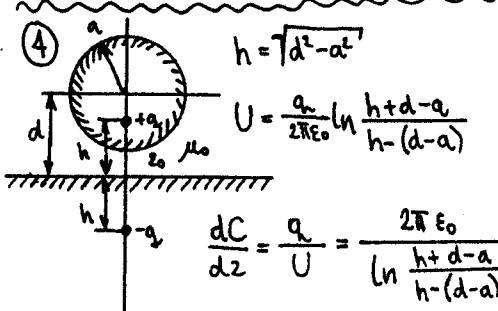
③  $\Delta V = 0 ; \vec{E}_0 = -\vec{I}_2 E_0 e^{j\omega t} = [-\vec{I}_r \cos \theta + \vec{I}_0 \sin \theta] E_0 e^{j\omega t}$   $\operatorname{div} \vec{j} + j\omega \sigma = 0 \rightarrow \operatorname{div} \vec{K} + j\omega \sigma = 0$

$\vec{E} = \left[ -\vec{I}_r \left(1 + \frac{2a^3}{r^3}\right) \cos \theta + \vec{I}_0 \left(1 - \frac{a^3}{r^3}\right) \sin \theta \right] E_0 e^{j\omega t} \quad \vec{K} = \vec{I}_0 K(\theta) ; \operatorname{div} \vec{K} = \frac{1}{r^2 \sin \theta} \frac{d}{dr} (r \sin \theta K(\theta)) = \frac{1}{a \sin \theta} \frac{d}{d\theta} (\sin \theta K(\theta))$

$\vec{\sigma} = \vec{I}_r \cdot \vec{D} \Big|_{r=a} = -\left(1 + \frac{2a^3}{a^3}\right) \cos \theta E_0 e^{j\omega t} = -3 \cos \theta E_0 e^{j\omega t} \quad \frac{d}{d\theta} (\sin \theta K(\theta)) = 3 \cos \theta \sin \theta j\omega a \epsilon_0 E_0 e^{j\omega t}$

$\cos \theta \sin \theta = \frac{1}{2} \sin 2\theta ; \int \frac{1}{2} \sin 2\theta d\theta = -\frac{1}{4} \cos 2\theta + C ; \vec{K} = -\vec{I}_0 \frac{3}{4} j\omega a \epsilon_0 E_0 e^{j\omega t} \frac{\cos 2\theta - 1}{\sin \theta} \quad C = \frac{1}{4}$

$\cos 2\theta - 1 = \cos^2 \theta - \sin^2 \theta - 1 = -2 \sin^2 \theta ; \quad \vec{K} = \vec{I}_0 \frac{3}{2} j\omega a \epsilon_0 E_0 e^{j\omega t} \sin \theta \quad \text{daje rezultat} \quad \text{omejen } \theta = 0 \quad \theta = \pi$



$Z_K = \sqrt{\frac{\frac{dL}{dz}}{\frac{dC}{dz}}} \quad \text{TEM} \quad \text{Co} = \frac{1}{\sqrt{\frac{dL}{dz} \cdot \frac{dC}{dz}}} \rightarrow \frac{dL}{dz} = \frac{1}{C_0^2} \frac{dC}{dz} \rightarrow Z_K = \frac{1}{C_0} \frac{dC}{dz}$

$Z_K = \frac{\ln \frac{h+d-a}{h-(d-a)}}{2\pi \epsilon_0 C_0} = \frac{1}{2\pi} \sqrt{\frac{\mu_0}{\epsilon_0}} \ln \frac{\sqrt{d^2 - a^2} + (d-a)}{\sqrt{d^2 - a^2} - (d-a)}$

⑤  $\vec{E} = \vec{E}_v + \vec{E}_0 = \vec{I}_E E_v (e^{-jkz} - e^{jkz}) ; \quad \vec{S}_v = \frac{1}{2} \vec{E}_v \times \vec{H}_v = \vec{I}_2 \frac{|\vec{E}_v|^2}{2Z_0} \rightarrow E_v = \sqrt{2Z_0 S_v}$

$\vec{H} = \vec{I}_H \frac{E_v}{Z_0} (e^{-jkz} + e^{jkz})$

$|\vec{K}| = \frac{2}{Z_0} \sqrt{2Z_0 S_v} = \sqrt{\frac{8S_v}{Z_0}} = \sqrt{\frac{8 \cdot 10^3 \text{ W/m}^2}{120\pi \text{ V/A}}} = 4.607 \frac{\text{A}}{\text{m}}$

$\vec{H}(z=0) = \vec{I}_H \frac{2E_v}{Z_0}$

$\vec{K} = \vec{I}_H \times \vec{H}(z=0) = \vec{I}_E \frac{2E_v}{Z_0}$

$\vec{F} = I d\vec{x} \times \vec{B}_v = \vec{I}_2 |\vec{K}| \cdot A \cdot \mu_0 |\vec{H}_v| = \vec{I}_2 \frac{|K|^2 A \mu_0}{4} = 6.667 \cdot 10^{-4} \text{ N}$

REŠITEV 1. kolokvija iz elektromagnetike - 8.12.1999

$$\textcircled{1} V(x,y) = \sum_n C_n \sin\left(\frac{n\pi}{a}x\right) \sin\left(\frac{n\pi}{a}y\right); V(x,b) = \sum_n C_n \sin\left(\frac{n\pi}{a}x\right) \sinh\left(\frac{n\pi}{a}b\right) = \begin{cases} \frac{2V_0}{a}x & 0 \leq x \leq \frac{a}{2} \\ \frac{2V_0}{a}(x-a) & \frac{a}{2} < x \leq a \end{cases} \quad \int_0^a \sin\left(\frac{n\pi}{a}x\right) dx$$

$$\textcircled{#1} \int_0^a \left( \sum_n C_n \sin\left(\frac{n\pi}{a}x\right) \sinh\left(\frac{n\pi}{a}b\right) \right) \sin\left(\frac{n\pi}{a}x\right) dx = \int_0^a C_m \sin^2\left(\frac{n\pi}{a}x\right) \sinh\left(\frac{n\pi}{a}b\right) dx = C_m \frac{a}{2} \sinh\left(\frac{n\pi}{a}b\right)$$

$$\textcircled{#2} \int_0^{a/2} \frac{2V_0}{a}x \sin\left(\frac{n\pi}{a}x\right) dx + \int_{a/2}^a \frac{2V_0}{a}(x-a) \sin\left(\frac{n\pi}{a}x\right) dx = -\frac{2V_0 a}{n\pi} \cos\left(\frac{n\pi}{2}\right)$$

$$\textcircled{#1} = \textcircled{#2} \Rightarrow C_m = \frac{-4V_0}{n\pi \sinh\left(\frac{n\pi}{a}b\right)} \cos\left(\frac{n\pi}{2}\right) \Rightarrow V(x,y) = \sum_{m=1}^{\infty} \frac{-4V_0}{n\pi \sinh\left(\frac{n\pi}{a}b\right)} \cos\left(\frac{n\pi}{2}\right) \sin\left(\frac{n\pi}{a}x\right)$$

$$\textcircled{2} V_1 = V_{16} = -V_4 = -V_{13}; V_2 = V_5 = V_{12} = V_{15} = -V_3 = -V_8 = -V_9 = -V_{14}; V_6 = V_{11} = -V_7 = -V_{10}$$

$$\left. \begin{array}{l} 4V_1 = 10 + V_2 + V_5 + 10 \\ 4V_2 = 10 + V_3 + V_6 + V_1 \\ 4V_6 = V_2 + V_7 + V_{10} + V_5 \end{array} \right\} \left. \begin{array}{l} 4V_1 = 10 + V_2 + V_2 + 10 \\ 4V_2 = 10 - V_2 + V_6 + V_1 \\ 4V_6 = V_2 - V_6 - V_6 + V_2 \end{array} \right\} \left. \begin{array}{l} 4V_1 = 20 + 2V_2 / 3 \\ 5V_2 = 10 + V_1 + V_6 / 12 \\ 4V_6 = 2V_2 - 2V_6 / 2 \end{array} \right\} \left. \begin{array}{l} 12V_1 = 60 + 6V_2 \\ 60V_2 = 120 + 12V_1 + 12V_6 \\ 12V_6 = 4V_2 \end{array} \right\} \begin{array}{l} V_2 = \frac{18}{5} V \\ V_1 = \frac{34}{5} V \\ V_6 = \frac{6}{5} V \end{array}$$

$$\textcircled{3} \Delta V = 0 \quad \vec{E} = -\operatorname{grad} V = \left( -\vec{1}_r E_0 \left( 1 + 2 \frac{a^3}{r^3} \right) \cos\theta + \vec{1}_\theta E_0 \left( 1 - \frac{a^3}{r^3} \right) \sin\theta \right) e^{j\omega t} \quad \vec{1}_n = \vec{1}_r$$

$$C = \vec{1}_n \cdot \vec{E} = -3E_0 E_0 \cos\theta e^{j\omega t} \quad \operatorname{div} \vec{E} + j\omega \vec{E} = 0 \Rightarrow \operatorname{div} \vec{K} + j\omega \vec{E} = 0 \quad \vec{K} = \vec{1}_\theta K(\theta) \quad \frac{\partial}{\partial \theta} = 0 \quad r=a$$

$$\frac{1}{a \sin\theta} \frac{\partial}{\partial \theta} (\sin\theta K_\theta) = j\omega^2 E_0 E_0 \cos\theta e^{j\omega t} \rightarrow K_\theta = j \frac{3}{2} \omega E_0 E_0 a \sin\theta e^{j\omega t} + \frac{C}{\sin\theta}$$

$$\vec{K} = \vec{1}_\theta \left( j \frac{3}{2} \omega E_0 E_0 a \sin\theta e^{j\omega t} + \frac{C}{\sin\theta} \right)$$

$$\textcircled{4} h_{qi} = \sqrt{\left( \frac{\partial x}{\partial q_i} \right)^2 + \left( \frac{\partial y}{\partial q_i} \right)^2 + \left( \frac{\partial z}{\partial q_i} \right)^2}$$

$$h_y = a \sqrt{\sin^2\gamma + \cos^2\psi} \quad h_x = a \sqrt{\sin^2\gamma + \cos^2\psi} \quad h_z = a \sin\gamma \sin\psi$$

$$\left| \begin{array}{c} \vec{t}_y a \sqrt{\sin^2\gamma + \cos^2\psi} \\ \frac{\partial}{\partial \gamma} \\ \vec{t}_x a \sqrt{\sin^2\gamma + \cos^2\psi} \\ \frac{\partial}{\partial \psi} \end{array} \right|$$

$$a \sqrt{\sin^2\gamma + \cos^2\psi} \cdot F_y \quad a \sqrt{\sin^2\gamma + \cos^2\psi} \cdot F_x \quad a \sin\gamma \sin\psi \cdot F_z$$

$$\textcircled{5} \vec{H} = \frac{1}{\mu_0} \operatorname{rot} \vec{A} = \vec{1}_\theta \frac{C}{2\mu_0} \frac{\sin\varphi}{\rho} \cos\frac{\varphi}{2} - \vec{1}_\varphi \frac{C}{\mu_0 \rho} \sin\frac{\varphi}{2} \quad \vec{j} = \operatorname{rot} \vec{H} = \vec{1}_z \frac{C}{4\mu_0} \frac{\sin\varphi}{\rho^2} \sin\frac{\varphi}{2}$$

$$I = \oint \vec{H} d\vec{s} = \frac{C}{\mu_0} \int \left( \vec{1}_\theta \frac{\sin\varphi}{2\rho} \cos\frac{\varphi}{2} - \vec{1}_\varphi \frac{1}{\rho} \sin\frac{\varphi}{2} \right) \vec{1}_\varphi \rho d\varphi = -\frac{C}{\mu_0} \int \sin\frac{\varphi}{2} d\varphi = \frac{-4C}{\mu_0}$$

$$\textcircled{1} \quad \vec{E}_+ = (\vec{I}_x + j\vec{I}_y) A e^{-jk_0 z}; \vec{E}_+(z=0) + \vec{E}_-(z=0) = 0 \Rightarrow \vec{E}_- = -(\vec{I}_x + j\vec{I}_y) A e^{jk_0 z}$$

$$\vec{E} = \vec{E}_+ + \vec{E}_- = (\vec{I}_x + j\vec{I}_y) A (e^{-jk_0 z} - e^{jk_0 z}); \vec{H} = \frac{j}{\omega \mu_0} \text{rot} \vec{E} = \frac{A}{Z_0} (-j\vec{I}_x + \vec{I}_y) (e^{-jk_0 z} + e^{jk_0 z})$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} A (\vec{I}_x + j\vec{I}_y) (e^{-jk_0 z} - e^{jk_0 z}) \times \frac{A^*}{Z_0} (j\vec{I}_x + \vec{I}_y) (e^{jk_0 z} + e^{-jk_0 z}) = -\vec{I}_z \frac{j^2 A A^*}{Z_0} \sin 2k_0 z$$

$$\textcircled{2} \quad Q = \omega_0 \frac{W}{P}; \omega_0: \vec{E} = \vec{I}_p \frac{A}{\rho} \sin \frac{3\pi}{l} z; \vec{H} = \frac{j}{\omega \mu_0} \text{rot} \vec{E} = \vec{I}_p \frac{j 3\pi A}{\omega \mu_0 \rho l} \cos \frac{3\pi}{l} z$$

$$\vec{J}(\omega=\omega_0) = 0 = \text{rot} \vec{H} \Big|_{\omega=\omega_0} - j\omega_0 \epsilon \vec{E}; \text{rot} \vec{H} = \vec{I}_p \frac{j g \pi^2 A}{\omega_0 \mu_0 \rho l} \sin \frac{3\pi}{l} z = \vec{I}_p \frac{j \omega_0 \epsilon A}{\rho} \sin \frac{3\pi}{l} z \Rightarrow$$

$$\omega = \frac{3\pi}{l} \frac{1}{\sqrt{\mu_0 \epsilon}} = \frac{3\pi c_0}{l} \frac{1}{\sqrt{\epsilon_r}}; W = \frac{1}{2} \int_V |\vec{E}_{\text{max}}|^2 dv = \frac{1}{2} \int_0^{l/2} \int_0^{2\pi} \int_0^{\pi} \epsilon \frac{|A|^2}{r^2} \sin \frac{2\pi}{l} z r dr d\varphi dz =$$

$$= \frac{\epsilon |A|^2 \pi l}{2} \ln \frac{r_e}{r_n}; P = \frac{1}{2} \int_V |\vec{E}|^2 dv = \dots = \frac{\pi |A|^2 \pi l}{2} \ln \frac{r_e}{r_n}; Q = \omega_0 \frac{W}{P} = \frac{3\pi}{l} \sqrt{\frac{\epsilon}{\mu_0}}$$

$$\textcircled{3} \quad M = \frac{1}{I} \oint \vec{V}_m ds; \text{ zica: } \vec{V}_m = -\vec{I}_z \left( \frac{\mu_0 I}{2\pi l} \ln r + C \right)$$

$$M = \frac{1}{I} \int_0^{\infty} -\vec{I}_z \left( \frac{\mu_0 I}{2\pi l} \ln r + C \right) \cdot \vec{I}_y \cdot a \cdot d\varphi = 0 \quad \text{ker je } \vec{I}_z \cdot \vec{I}_y = 0$$

$$\textcircled{4} \quad \vec{E} = \vec{I}_y E_0 \sin \frac{3\pi}{a} x e^{-jbz}; \vec{H} = \frac{j}{\omega \mu_0} \text{rot} \vec{E} = -\vec{I}_x \frac{E_0 B}{\omega \mu_0} \sin \frac{3\pi}{a} x e^{jbz} + \vec{I}_z \frac{j 3\pi E_0}{\omega \mu_0 a} \cos \frac{3\pi}{a} x e^{-jbz}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} \left( \vec{I}_y E_0 \sin \frac{3\pi}{a} x e^{-jbz} \right) \times \left( -\vec{I}_x \frac{E_0^* B}{\omega \mu_0} \sin \frac{3\pi}{a} x e^{jbz} - \vec{I}_z \frac{j 3\pi E_0^*}{\omega \mu_0 a} \cos \frac{3\pi}{a} x e^{-jbz} \right) =$$

$$= \vec{I}_z \frac{E_0 E_0^* B}{2 \omega \mu_0} \sin \frac{2\pi}{a} x - \vec{I}_x \frac{j 3\pi E_0 E_0^*}{4 \omega \mu_0 a} \sin \frac{6\pi}{a} x$$

$$P = \iint_A dA = \iint_0^{ab} \left( \vec{I}_z \frac{|E_0|^2 B}{2 \omega \mu_0} \sin \frac{2\pi}{a} x - \vec{I}_x \frac{j 3\pi |E_0|^2}{4 \omega \mu_0 a} \sin \frac{6\pi}{a} x \right) \cdot \vec{I}_z dx dy = \frac{|E_0|^2 B ab}{4 \omega \mu_0}$$

$$x=0: \vec{K} = \vec{I}_x \times \vec{H} = -\vec{I}_y \frac{j 3\pi E_0}{\omega \mu_0 a} e^{-jbz}; y=0: \vec{K} = \vec{I}_y \times \vec{H} = \vec{I}_z \frac{E_0 B}{\omega \mu_0} \sin \frac{3\pi}{a} x e^{-jbz} + \vec{I}_x \frac{j 3\pi E_0}{\omega \mu_0 a} \cos \frac{3\pi}{a} x e^{-jbz}$$

$$x=a: \vec{K} = -\vec{I}_x \times \vec{H} = -\vec{I}_y \frac{j 3\pi E_0}{\omega \mu_0 a} e^{-jbz}; y=b: \vec{K} = -\vec{I}_y \times \vec{H} = -\vec{I}_z \frac{E_0 B}{\omega \mu_0} \sin \frac{3\pi}{a} x e^{-jbz} - \vec{I}_x \frac{j 3\pi E_0}{\omega \mu_0 a} \cos \frac{3\pi}{a} x e^{-jbz}$$

$$\textcircled{5} \quad f = \frac{1}{2 \sqrt{\mu_0 \epsilon_0 \epsilon_r}} \sqrt{\left(\frac{l}{a}\right)^2 + \left(\frac{m}{b}\right)^2 + \left(\frac{n}{c}\right)^2}; l, m, n \in \mathbb{Z}, \text{ vsaj dva morata biti razlicna od nic!}$$

Najnizja resonanca frekvencia v primeru, da bi bil  $\epsilon_r=1$  je za  $m=1, n=1$  ( $b, c > a$ !) enaka  $f(\epsilon_r=1) = 4.48 \text{ GHz}$ . Zahtevana resonanca frekvencia je nizja  $\Rightarrow \epsilon_r > 1$

$$f = \frac{f(\epsilon_r=1)}{\sqrt{\epsilon_r}} \Rightarrow \epsilon_r = \left( \frac{f(\epsilon_r=1)}{f} \right)^2 = 20.1$$

$$\begin{aligned} & \text{rot}(\vec{A}\vec{B}) + \text{rot}(\vec{B}\vec{C}) + \text{rot}(\vec{C}\vec{A}) + \\ & + \text{rot}(\text{rot}(\text{rot}(\vec{A} + \vec{B} + \vec{C}))) = ? \end{aligned}$$

$$\begin{cases} \vec{F} = \vec{A}_x A + \vec{A}_y B + \vec{A}_z C \\ A(x_1, y_1, z) \\ B(x_1, y_1, z) \\ C(x_1, y_1, z) \end{cases}$$

$$\begin{aligned} & \text{rot}(\Delta \vec{F}) + \text{rot}(\text{rot}(\text{rot} \vec{F})) = \\ & = \text{rot}(\text{grad}(\text{div} \vec{F}) - \text{rot}(\text{rot}^2)) + \text{rot}(\text{rot}(\text{rot} \vec{F})) = \\ & = \text{rot}(\text{grad}(\text{div} \vec{F})) = \quad \vec{V} = \text{div} \vec{V} \vec{F} \\ & = \text{rot}(\text{grad} V) = 0 \\ & = \text{rot}(\text{grad} V) = 0 \end{aligned}$$

$$\alpha = \frac{3 \pm \sqrt{9-4}}{2}$$

$$\alpha = \frac{3 \pm \sqrt{5}}{2}$$

$$V_n = \left( \frac{3-\sqrt{5}}{2} \right)^n V_0$$

$$\alpha^2 - 3\alpha + 1 = 0$$

$$\alpha = \frac{3 \pm \sqrt{9-4}}{2}$$

$$V_n = \left( \frac{3-\sqrt{5}}{2} \right)^n V_0$$

$$4V_n = V_{n-1} + V_n + V_{n+1} + 0$$

$$V_m = \sum \frac{C_m}{r^{m+1}} P_m(\cos \theta) \approx \frac{C_1}{r^2} \cos \theta$$

$$\begin{cases} \frac{C_1}{a^2} \cos \theta \cos \theta = \int V(a) \cos \theta d\cos \theta \\ \frac{C_1}{a^2} \cdot \frac{2}{3} = \frac{\pi}{2} \cdot \frac{1}{2} + \frac{\pi}{2} \cdot \frac{1}{2} = \frac{\pi}{2} \rightarrow C_1 = \frac{3}{4} a^2 I \end{cases}$$

$$\begin{aligned} V_m & \approx \frac{3}{4} a^2 I \frac{\cos \theta}{r^2} = \frac{3}{4 \pi r^2} \frac{\cos \theta}{r^2} \cos \theta \\ \vec{H} & = -\text{grad} V_m = \frac{3 \pi a^2 I}{4 \pi r^3} \left( \vec{A}_r 2 \cos \theta + \vec{A}_\theta \sin \theta \right) \end{aligned}$$

(3)

$$\begin{cases} \Delta = 2\pi(1-\cos \alpha) = \vec{H} \\ C = \Omega \varepsilon_r \varepsilon_0 \alpha + (\vec{A} \times \vec{B}) \varepsilon_0 \alpha = \end{cases}$$

$$\begin{aligned} & -\vec{H} \varepsilon_r \varepsilon_0 \alpha + 2\pi \varepsilon_0 \alpha = \vec{H} (1+\beta) \varepsilon_0 \alpha = \\ & = \vec{H} (6+3) \frac{1}{4\pi \cdot 3 \cdot 10^5} \frac{4\pi}{L} \cdot 0.01 \alpha = \end{aligned}$$

$$E_0 = \frac{1}{4\pi \varepsilon_0 \varepsilon_r L} \frac{As}{Vm}$$

$$\vec{H} = \frac{1}{\mu_0} \text{rot} \vec{E} = \frac{1}{\mu_0} \frac{\partial \vec{E}}{\partial x}$$

$$nt \vec{H} = \vec{H}_0 + \vec{A}_r \left( \sqrt{2} E_0 \text{exp}^{-j\omega t} \cos(\omega t) + \frac{E_0}{\sqrt{2}} \text{exp}^{-j\omega t} \cos(\omega t) \right) +$$

$$+ \vec{A}_\theta \left( -\frac{E_0}{\sqrt{2}} \text{exp}^{-j\omega t} \cos(\omega t) - \frac{E_0}{\sqrt{2}} \text{exp}^{-j\omega t} \cos(\omega t) \right)$$

$$\text{pogoj: } 0^2 + 2\alpha^2 = k^2 \Rightarrow \alpha = \sqrt{\frac{k^2 - 4\alpha^2}{4}}$$

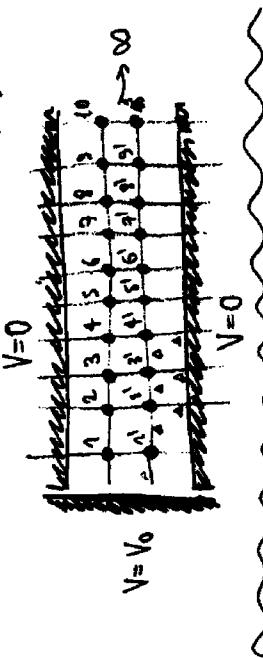


$$\varepsilon_r = 6$$

$$= \frac{g}{36} \cdot 10^{-11} F = \underline{\underline{2.5 \text{ pF}}}$$

(4)

$$V_A = ?$$



$$3V_n = V_{n-1} + V_{n+1}$$

$$V_{n-1} = \alpha V_n$$

$$V_n = \alpha V_{n+1}$$

$$V_0 = V_1$$

$$V_1 = V_2$$

$$V_2 = V_3$$

$$\begin{cases} \varepsilon_0 / \mu_0, g = 0, j = 0 \\ \vec{E} = \vec{E}_0 e^{-j\omega t} \cos(\omega t) \end{cases}$$

$$\begin{cases} \text{div} \vec{E} = 0 = -j\omega E_0 e^{-j\omega t} \cos(\omega t) - \frac{E_0}{\mu_0} \\ \int g = 0, \vec{E} = \vec{E}_0 \end{cases}$$

$$\begin{aligned} & \vec{E}_0 = \frac{1-j\omega}{\mu_0} \vec{E}_0, \quad \frac{\vec{E}_0}{\mu_0} = \frac{1}{2} \frac{\vec{E}_0}{\omega} \frac{\partial}{\partial x} \quad \vec{H} = \frac{1}{\mu_0} \text{rot} \vec{E} = \frac{1}{\mu_0} \frac{\partial \vec{E}}{\partial x} \\ & \vec{H} = \vec{H}_0 + \vec{A}_r \left( \sqrt{2} E_0 \text{exp}^{-j\omega t} \cos(\omega t) + \frac{E_0}{\sqrt{2}} \text{exp}^{-j\omega t} \cos(\omega t) \right) + \\ & + \vec{A}_\theta \left( -\frac{E_0}{\sqrt{2}} \text{exp}^{-j\omega t} \cos(\omega t) - \frac{E_0}{\sqrt{2}} \text{exp}^{-j\omega t} \cos(\omega t) \right) \\ & \text{pogoj: } 0^2 + 2\alpha^2 = k^2 \Rightarrow \alpha = \sqrt{\frac{k^2 - 4\alpha^2}{4}} \end{aligned}$$

$$\text{smer } \vec{E}_0 = ?$$

$$\vec{H} = ?$$



(2)

# Rešitev ELEKTROMAGNETIKA 04.10.2000

**1**  $V = \begin{cases} V_0; r < a \\ V_0 e^{-\alpha r}; r > a \end{cases}$

$\epsilon_r = \epsilon_0; \omega = ?; Q = ?$

$\vec{E} = -\nabla V; \vec{E}_r = -\hat{r}_r V_0 e^{-\alpha r} = \hat{r}_r \times \epsilon_0 e^{-\alpha r}$

$S = \operatorname{div}(\epsilon \vec{E}) + \frac{\partial}{\partial r} \left( \epsilon_0 \vec{E}_r \right) = \epsilon_0 \frac{\partial V_0}{\partial r} e^{-\alpha r} + \epsilon_0 \frac{\partial}{\partial r} \left( \frac{V_0}{\alpha} e^{-\alpha r} \right) = \epsilon_0 V_0 e^{-\alpha r} \left( \frac{1}{\alpha} - 1 \right)$

$G(r=0) = i \cdot (\vec{B}_0 \cdot \vec{d}_0) = \alpha S V_0 e^{-\alpha a}$

$Q = \int \vec{D} \cdot d\vec{A} = 0$  (obzirno)

**2**  $U = C \ln \frac{r}{r_0}$

$\vec{E} = \vec{E}_r \frac{U}{\ln \frac{r}{r_0}} \hat{r}_r$

$\int \vec{E} \cdot d\vec{l} = V_0 \left( \frac{1}{\alpha} - 1 \right) \frac{U}{\ln \frac{r}{r_0}} \frac{1}{2} \int_{r_0}^r \frac{1}{r^2} dr = V_0 \left( \frac{1}{\alpha} - 1 \right) \frac{U}{\ln \frac{r}{r_0}}$

$I = \int \vec{J} \cdot d\vec{A} = \int \vec{J} \cdot \vec{d}\vec{A} = \frac{3}{2} \cdot \sqrt{\pi} d_0 l_0 \frac{U}{\ln \frac{r}{r_0}}$

**3**  $\vec{E}(r) = \vec{E}_0 \left( \frac{1}{2} - \frac{1}{2} \sin \theta \right)$

$d = ?$

**4**  $\vec{E}(r) = \vec{E}_0 \left( \frac{1}{2} - \frac{1}{2} \sin \theta \right)$

$d \rightarrow a; \mu_0 = \bar{B}_0 \frac{3/4\pi}{2+4\pi} = \frac{3}{16\pi} \bar{B}_0$

$d \rightarrow b; \mu_0 = \frac{3}{8\pi} \bar{B}_0$

$\mu_r = ?$

Krogler na koncentričnih poljih  $\vec{B}_N = \bar{B}_0 \frac{3/4\pi}{2+4\pi}$

1.7 radij  $\Rightarrow \frac{9}{16\pi} \bar{B}_0$  (recipročnost!)

$\mu_r = \left( \frac{3/4\pi}{2+4\pi} \right) \left( \frac{3/4\pi}{2+4\pi} \right) \mu_0 = \frac{27/16}{3 \cdot \pi^2} = 1,484$

**5**  $V(r, \theta, \phi) = \sum_n C_n r^{-(n+1)} P_n(\cos \theta)$

$C_n = 0$  zvezni simetrije

$C_0 = 0 \Rightarrow P_0(\cos \theta) = 1$

$D = \int \vec{E} \cdot d\vec{A} = \int \vec{E} \cdot \vec{d}A = \frac{1}{4\pi} \int_{4\pi} d\Omega = \frac{1}{4\pi} \int_{4\pi} \vec{E} \cdot \vec{d}A = \frac{1}{4\pi} \int_{4\pi} \vec{E}_r \cdot \vec{d}A = \frac{1}{4\pi} \int_{4\pi} E_r dA = \frac{1}{4\pi} \int_{4\pi} E_0 dA = 0$

$E(r \gg a) = 0$

$\vec{E}(r \gg a) = \vec{0}$

$\eta = \frac{1-n}{1+n}$

$S = S_N (1-\eta^2) = S_N \frac{4n}{(1+n)^2}$

$NV = \frac{\partial N}{\partial r} = \frac{S_N}{C_0} = \frac{S_N}{C_0} \frac{4n}{(1+n)^2}$

$NV = \frac{S_N}{C_0} \frac{4 \epsilon_r}{(1+\epsilon_r)^2}$

$\mu_r = \frac{S_N}{C_0} \frac{4 \epsilon_r}{(1+\epsilon_r)^2}$

$n = \sqrt{\epsilon_r}$

## Elektromagnetika, kolokvij 12.12.2000, rešitve

1)  $\rho(r, \theta, \phi) = ? \quad \frac{\partial}{\partial \phi} = 0$

$$V(r, \theta, \phi) = V_0 r \sin 3\theta$$

$$\vec{E} = -\underline{\underline{\text{grad } V}} = -\vec{1}_r V_0 \sin 3\theta - \vec{1}_\theta V_0 3 \cos 3\theta$$

$$\rho = \text{div } \vec{D} = \text{div } \epsilon_0 \vec{E} = \epsilon_0 \frac{1}{r^2 \sin \theta} \left[ -\frac{\partial}{\partial r} (r^2 \sin \theta V_0 \sin 3\theta) - \frac{\partial}{\partial \theta} (r \sin \theta V_0 3 \cos 3\theta) \right] =$$

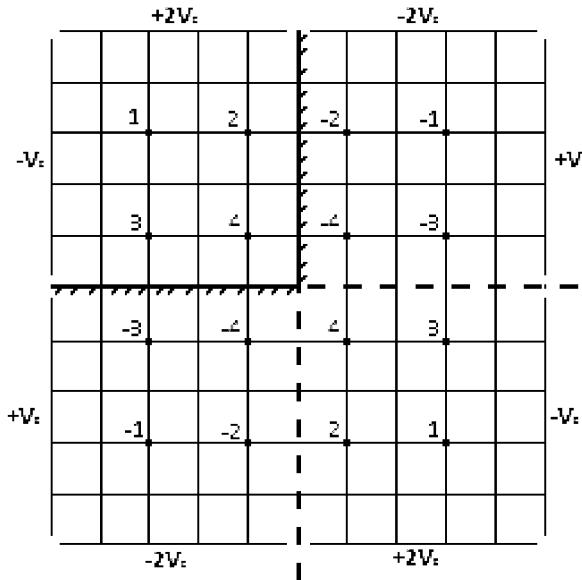
$$= \epsilon_0 \frac{1}{r^2 \sin \theta} \left[ -V_0 2r \sin \theta \sin 3\theta - 3V_0 r (\cos \theta \cos 3\theta + \sin \theta (-3 \sin 3\theta)) \right] =$$

$$= \epsilon_0 \frac{V_0}{r \sin \theta} \left[ -2 \sin \theta \sin 3\theta - 3 \cos \theta \cos 3\theta + 9 \sin \theta \sin 3\theta \right]$$

$$= \underline{\underline{\epsilon_0 \frac{V_0}{r} (7 \sin 3\theta - 3 \operatorname{ctg} \theta \cos 3\theta)}}$$


---

2)



$$4V_1 = -V_0 + 2V_0 + V_2 + V_3 \rightarrow 4V_1 = V_0 + V_2 + V_3$$

$$4V_2 = 2V_0 + V_1 - V_2 + V_4 \rightarrow 5V_2 = 2V_0 + V_1 + V_4$$

$$4V_3 = -V_0 + V_1 - V_3 + V_4 \rightarrow 5V_3 = -V_0 + V_1 + V_4$$

$$4V_4 = V_2 + V_3 - V_4 - V_4 \rightarrow 6V_4 = V_2 + V_3 \rightarrow V_4 = \frac{V_2 + V_3}{6}$$

$$19V_2 = 9V_0 + V_3 + 4V_4 \rightarrow 55V_2 = 27V_0 + 5V_3$$

$$19V_3 = -3V_0 + V_2 + 4V_4 \rightarrow 55V_3 = -9V_0 + 5V_2$$

$$V_2 = \frac{12}{25}V_0$$

$$V_3 = -\frac{3}{25}V_0$$

$$V_4 = \frac{3}{50}V_0$$

$$V_1 = \frac{17}{50}V_0$$


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3)  $V(x, y, z = \frac{c}{2}) = V_0 \sin \left( \frac{\pi}{a} x \right) \quad V(x, y, z = -\frac{c}{2}) = -V_0 \sin \left( \frac{\pi}{a} x \right)$

$$\frac{\partial}{\partial x} \neq 0 \quad \frac{\partial}{\partial y} \neq 0 \quad \frac{\partial}{\partial z} \neq 0 \quad k_x = \frac{\pi}{a}, \quad k_y = \frac{\pi}{b}, \quad k_z = \sqrt{k_x^2 + k_y^2} = \sqrt{\left(\frac{\pi}{a}\right)^2 + \left(\frac{\pi}{b}\right)^2},$$

Nastavek:  $V(x, y, z = \frac{c}{2}) = \sum_m \sum_n C_{mn} \sin \left( \frac{m\pi}{a} x \right) \sin \left( \frac{n\pi}{b} y \right) \sinh \left( \sqrt{\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2} \frac{c}{2} \right) = V_0 \sin \frac{\pi}{a} x$

$\sinh\left(k_z\left(-\frac{c}{2}\right)\right) = -\sinh\left(k_z\frac{c}{2}\right) \rightarrow$  rešitev pri  $z = -\frac{c}{2}$  glede na vzbujanje ( $-V_0 \sin \frac{\pi}{a}x$ ) predstavlja zrcalno sliko glede na rešitev pri  $z = \frac{c}{2}$ , zato je nesmiselna.

Glede na vsiljen potencial ( $\sin \frac{\pi}{a}x$ ) na pokrovih sklepamo:  $m = 1$ ;

$$V_0 = \sum_n C_n \sin\left(\frac{n\pi}{b}y\right) \sinh\left(\sqrt{\left(\frac{\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2} \frac{c}{2}\right)$$

Koefficiente  $C_n$  določimo s Fourierjevo analizo, tako da čim bolje zadostimo pogoju  $V = V_0$  na pokrovu:

$$\begin{aligned} \int_0^b V_0 \left( \sin\left(\frac{l\pi}{b}y\right) \right) dy &= \int_0^b C_l \sin\left(\frac{n\pi}{b}y\right) \sinh\left(\sqrt{\left(\frac{\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2} \frac{c}{2}\right) \sin\left(\frac{l\pi}{b}y\right) dy ; \quad n \rightarrow l \\ \frac{V_0 b}{l\pi} (1 - \cos(l\pi)) &= C_l \sinh\left(\sqrt{\left(\frac{\pi}{a}\right)^2 + \left(\frac{l\pi}{b}\right)^2} \frac{c}{2}\right) \left(\frac{b}{2}\right) \\ C_l &= \frac{2 V_0}{l\pi \sinh\left(\sqrt{\left(\frac{\pi}{a}\right)^2 + \left(\frac{l\pi}{b}\right)^2} \frac{c}{2}\right)} (1 - \cos(l\pi)) \\ V(x, y, z) &= \sum_{l=1}^{\infty} \frac{2 V_0}{l\pi} (1 - \cos(l\pi)) \sin\left(\frac{\pi}{a}x\right) \sin\left(\frac{l\pi}{b}y\right) \frac{\sinh\left(\sqrt{\left(\frac{\pi}{a}\right)^2 + \left(\frac{l\pi}{b}\right)^2} z\right)}{\sinh\left(\sqrt{\left(\frac{\pi}{a}\right)^2 + \left(\frac{l\pi}{b}\right)^2} \frac{c}{2}\right)} \end{aligned}$$


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4)  $\frac{\partial}{\theta r} \neq 0 \quad \frac{\partial}{\theta \theta} \neq 0 \quad \frac{\partial}{\theta \varphi} = 0 \quad \vec{J}_0 = -\vec{1}_z J_0 = -\vec{1}_z \gamma_0 E_0$

$\frac{\partial V}{\partial x} = \frac{\partial V}{\partial y} = 0 \quad \vec{E} = -\text{grad } V = -\vec{1}_z \frac{\partial V}{\partial z} \rightarrow \frac{\partial V_0}{\partial z} = E_0 \int dz$

V prostoru " $\gamma_0$ ": Potencial:  $V_0(r, \theta) = (A_0 r + B_0 r^{-2}) \cos\theta$

Polje:  $\vec{E}_0 = -\text{grad } V = -\vec{1}_r (A_0 - \frac{2B_0}{r^3}) \cos\theta + \vec{1}_\theta (A_0 + \frac{B_0}{r^3}) \sin\theta$

V prostoru " $\gamma_N$ ": Potencial:  $V_N(r, \theta) = (A_N r + B_N r^{-2}) \cos\theta$

Polje:  $\vec{E}_N = -\text{grad } V = -\vec{1}_r (A_N - \frac{2B_N}{r^3}) \cos\theta + \vec{1}_\theta (A_N + \frac{B_N}{r^3}) \sin\theta$

1. Pri  $r \gg b$  je polje nespremenjeno:

$$\vec{E}_0 = -\vec{1}_r (A_0 - \frac{2B_0}{r^3}) \cos\theta + \vec{1}_\theta (A_0 + \frac{B_0}{r^3}) \sin\theta \approx -\vec{1}_r A_0 \cos\theta + \vec{1}_\theta A_0 \sin\theta = -\vec{1}_z A_0 = -\vec{1}_z E_0 \rightarrow \underline{A_0 = E_0}$$

2. Pri  $r = a$  (na površini krogle) je:  $\vec{E}_t = \vec{E}_\theta = 0 \quad ; \quad \vec{1}_\theta E_N(r=a) = 0 = (A_N + \frac{B_N}{r^3}) \sin\theta \rightarrow B_N = -A_N a^3$

3. Pri  $r = b$  je:  $\vec{E}_{tN} = \vec{E}_{t0} \quad ; \quad \vec{J}_{nN} = \vec{J}_{n0}$

$$A_N + \frac{B_N}{b^3} = E_0 + \frac{B_0}{b^3} \quad ; \quad \gamma_N (A_N - \frac{2B_N}{b^3}) = \gamma_0 (E_0 - \frac{2B_0}{b^3})$$

$$A_N (1 - \frac{a^3}{b^3}) = E_0 + \frac{B_0}{b^3} \quad ; \quad A_N \gamma_N (1 + \frac{2a^3}{b^3}) = E_0 \gamma_0 - \frac{2B_0}{b^3} \gamma_0$$

$$A_N (1 - \frac{a^3}{b^3}) = E_0 + \frac{B_0}{b^3} \quad ; \quad E_0 \gamma_N b^3 \left(1 + \frac{2a^3}{b^3}\right) + B_0 \gamma_N \left(1 + \frac{2a^3}{b^3}\right) = E_0 \gamma_0 b^3 \left(1 - \frac{a^3}{b^3}\right) - 2B_0 \gamma_0 \left(1 - \frac{a^3}{b^3}\right)$$

$$A_N = \frac{E_0 b^3 + B_0}{b^3 \left(1 - \frac{a^3}{b^3}\right)} \quad ; \quad B_0 = \frac{E_0 b^3 \left(\gamma_0 \left(1 - \frac{a^3}{b^3}\right) - \gamma_N \left(1 + \frac{2a^3}{b^3}\right)\right)}{2\gamma_0 \left(1 - \frac{a^3}{b^3}\right) + \gamma_N \left(1 + \frac{2a^3}{b^3}\right)}$$


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$$A_N = \frac{3E_0\gamma_0}{2\gamma_0 \left(1 - \frac{a^3}{b^3}\right) + \gamma_N \left(1 + \frac{2a^3}{b^3}\right)} \quad ; \quad B_N = -\frac{3E_0\gamma_0 a^3}{2\gamma_0 \left(1 - \frac{a^3}{b^3}\right) + \gamma_N \left(1 + \frac{2a^3}{b^3}\right)}$$


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$$\vec{E}_0 = -\vec{1}_r E_0 \left( 1 - \frac{b^3 \left( \gamma_0 \left( 1 - \frac{a^3}{b^3} \right) - \gamma_N \left( 1 + \frac{2a^3}{b^3} \right) \right)}{r^3 \gamma_0 \left( 1 - \frac{a^3}{b^3} \right) + \gamma_N \left( 1 + \frac{2a^3}{b^3} \right)} \right) \cos\theta + \vec{1}_\theta E_0 \left( 1 + \frac{b^3 \left( \gamma_0 \left( 1 - \frac{a^3}{b^3} \right) - \gamma_N \left( 1 + \frac{2a^3}{b^3} \right) \right)}{r^3 2 \gamma_0 \left( 1 - \frac{a^3}{b^3} \right) + \gamma_N \left( 1 + \frac{2a^3}{b^3} \right)} \right) \sin\theta$$

$$\vec{E}_N = -\vec{1}_r \frac{\frac{3E_0Y_0}{2} \left(1 + \frac{2a^3}{b^3}\right)}{2Y_0 \left(1 - \frac{a^3}{b^3}\right) + Y_N \left(1 + \frac{2a^3}{b^3}\right)} \left(1 - \frac{2a^3}{r^3}\right) \cos\theta + \vec{1}_\theta \frac{\frac{3E_0Y_0}{2} \left(1 + \frac{2a^3}{b^3}\right)}{2Y_0 \left(1 - \frac{a^3}{b^3}\right) + Y_N \left(1 + \frac{2a^3}{b^3}\right)} \left(1 + \frac{a^3}{r^3}\right) \sin\theta$$

$$5) \quad \vec{F} = \vec{1}_p + \vec{1}_\varphi p + \vec{1}_z p \cos \varphi$$

$$\oint \vec{F} \cdot d\vec{s} = - \int_2^4 \vec{F} \cdot \vec{1}_z \, dz + \int_{\pi/2}^{-\pi} \vec{F} \cdot (-\vec{1}_\varphi) \, \rho(-d\varphi) + \int_2^1 \vec{F} \cdot (-\vec{1}_\rho) \, (-d\rho) + \int_4^2 \vec{F} \cdot (-\vec{1}_z) \, (-dz) + \int_1^2 \vec{F} \cdot \vec{1}_\rho \, d\rho + \\ + \int_{-\pi/2}^{\pi} \vec{F} \cdot \vec{1}_\varphi \, \rho \, d\varphi =$$

$$= \left| \rho \cos \varphi \begin{array}{c} 4 \\ 2 \end{array} z + \left| \begin{array}{c} \rho^2 \\ -\frac{\pi}{2} \end{array} \right. \varphi + \left| \begin{array}{c} 1 \\ 2 \end{array} \rho + \left| \begin{array}{c} \rho \cos \varphi \\ 4 \end{array} \right. z + \left| \begin{array}{c} 2 \\ 1 \end{array} \rho + \left| \begin{array}{c} \rho^2 \\ -\frac{\pi}{2} \end{array} \right. \varphi = \right. \right. \right. \right. \\ \left. \begin{array}{c} \rho=2 \\ \varphi=\pi \end{array} \right. \left. \begin{array}{c} \rho=2 \\ z=4 \end{array} \right. \left. \begin{array}{c} \varphi=-\pi/2 \\ z=4 \end{array} \right. \left. \begin{array}{c} \rho=1 \\ \varphi=-\pi/2 \end{array} \right. \left. \begin{array}{c} \varphi=-\pi/2 \\ z=2 \end{array} \right. \left. \begin{array}{c} \rho=2 \\ z=2 \end{array} \right. \end{array}$$

$$= 2(-1)2 + 4\left(-\frac{\pi}{2} - \pi\right) + (1-2) + 0 + (2-1) + 4\left(\pi + \frac{\pi}{2}\right) = \underline{\underline{-4}}$$

## Elektromagnetika, kolokvij 15.02.2001, rešitve

1)  $\vec{J} = \vec{1}_y J_0$  [A/m],  $r \gg a$

$$\begin{aligned}\vec{A}(\vec{r}) &= \frac{\mu_0}{4\pi} \int_{\nu'} \vec{J}(\vec{r}') \frac{e^{-jk|\vec{r}-\vec{r}'|}}{|\vec{r}-\vec{r}'|} d\nu' = \frac{\mu_0 J_0}{4\pi} \int_{\nu'} \vec{1}_y \frac{e^{-jkr}}{r} d\nu' = \frac{\mu_0 a^3}{4\pi} J_0 \frac{e^{-jkr}}{r} (\vec{1}_r \sin \theta \sin \phi + \vec{1}_\theta \cos \theta \sin \phi + \vec{1}_\phi \cos \phi) \\ \vec{H} &= \frac{1}{\mu} \text{rot } \vec{A} = \frac{a^3}{4\pi} J_0 \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{1}_r & r \vec{1}_\theta & r \sin \theta \vec{1}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ \sin \theta \sin \phi \frac{e^{-jkr}}{r} & r \cos \theta \sin \phi \frac{e^{-jkr}}{r} & r \sin \theta \cos \phi \frac{e^{-jkr}}{r} \end{vmatrix} = \\ &= \frac{a^3}{4\pi} J_0 \frac{1}{r^2 \sin \theta} [\vec{1}_r (\cos \theta \cos \phi e^{-jkr} - \cos \theta \cos \phi e^{-jkr}) + r \vec{1}_\theta (\sin \theta \cos \phi \frac{e^{-jkr}}{r} + (jk) \sin \theta \cos \phi e^{-jkr}) + \\ &\quad + r \sin \theta \vec{1}_\phi ((-jk) \cos \theta \sin \phi e^{-jkr} - \cos \theta \sin \phi \frac{e^{-jkr}}{r})] \\ \vec{H} &= \frac{a^3}{4\pi} J_0 \frac{e^{-jkr}}{r} \left[ \left( \frac{1}{r} + jk \right) (\vec{1}_\theta \cos \phi - \vec{1}_\phi \cos \theta \sin \phi) \right]\end{aligned}$$


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2)  $\vec{K}(z=0) = \vec{1}_\rho K_0 J_0(\alpha\rho)$   $\sigma = ?$

$$\sigma = \frac{j}{\omega} \text{div } \vec{K} = \frac{j}{\omega \rho} \left( \frac{\partial}{\partial \rho} \rho K_0 J_0(\alpha\rho) \right) = \underline{\underline{\frac{j K_0}{\omega \rho} (J_0(\alpha\rho) + \rho \alpha J_0'(\alpha\rho))}}$$


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3)  $a = 4 \text{ cm}, b = 3 \text{ cm}, c = 9 \text{ cm}, \epsilon_r = ? \quad f_{l,m,n} = \frac{c_0}{2} \sqrt{\left(\frac{l}{a}\right)^2 + \left(\frac{m}{b}\right)^2 + \left(\frac{n}{c}\right)^2} \text{ m,n,p} \rightarrow \text{cela števila}$

$$f_{011} - f_{101} = 288,8 \text{ MHz} \quad \frac{c_0}{2\sqrt{\epsilon_r}} \left( \sqrt{\left(\frac{1}{b}\right)^2 + \left(\frac{1}{c}\right)^2} - \sqrt{\left(\frac{1}{a}\right)^2 + \left(\frac{1}{c}\right)^2} \right) = 288,8 \text{ MHz}$$

$$\epsilon_r = \left( \frac{c_0}{2 \times 288,8 \text{ MHz}} \left( \sqrt{\left(\frac{1}{b}\right)^2 + \left(\frac{1}{c}\right)^2} - \sqrt{\left(\frac{1}{a}\right)^2 + \left(\frac{1}{c}\right)^2} \right) \right)^2 = 16,32$$


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4)  $\text{rot } \vec{H} = \gamma \vec{E} + j\omega \epsilon \vec{E} = j\omega \epsilon_0 \underbrace{\left( \frac{\gamma}{j\omega \epsilon_0} + 1 \right)}_{\epsilon_r} \vec{E}$

$k = \omega \sqrt{\mu_0 \epsilon_0 \epsilon_r} = \omega \sqrt{\mu_0 \epsilon_0} \sqrt{\epsilon_r}$

$k = k_0 \sqrt{1 + \frac{\gamma}{j\omega \epsilon_0}} \approx k_0 \left( 1 + \frac{\gamma}{2j\omega \epsilon_0} \right) = \underline{\underline{k_0 \left( 1 - j \frac{\gamma}{2\omega \epsilon_0} \right)}} = \beta_0 - j\alpha \quad \rightarrow \quad \alpha = \frac{\gamma}{2\omega \epsilon_0}$

$l' = l \frac{k}{\beta} = \frac{\sqrt{(\beta)^2 + \left(\frac{\pi}{\beta}\right)^2}}{\beta} \quad \rightarrow \quad \alpha' = \alpha \frac{\sqrt{(\beta)^2 + \left(\frac{\pi}{\beta}\right)^2}}{\beta} \quad \alpha_{dB/m} = \alpha' Np/m \frac{20}{\ln 10}$

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$$5) \quad \vec{1}_{kv} = \vec{1}_z \quad \vec{1}_{ko} = -\vec{1}_z$$

$$\vec{E} = \vec{E}_v + \vec{E}_o = \vec{1}_x A e^{-jk_0 z} + j \vec{1}_y A e^{-jk_0 z} + \vec{1}_x \Gamma A e^{+jk_0 z} + j \vec{1}_y \Gamma A e^{+jk_0 z}$$

$$\vec{H} = \vec{H}_v + \vec{H}_o = \left( \vec{1}_{kv} \times \frac{\vec{E}_v}{Z} \right) + \left( \vec{1}_{ko} \times \frac{\vec{E}_o}{Z} \right) = \vec{1}_y \frac{A}{Z} e^{-jk_0 z} - j \vec{1}_x \frac{A}{Z} e^{-jk_0 z} - \vec{1}_y \frac{\Gamma A}{Z} e^{+jk_0 z} + j \vec{1}_x \frac{\Gamma A}{Z} e^{+jk_0 z}$$

$$S = \frac{1}{2} |\vec{E} \times \vec{H}^*| = \frac{1}{2} \begin{vmatrix} \vec{1}_x & \vec{1}_y & \vec{1}_z \\ Ae^{-jk_0 z} + \Gamma A e^{+jk_0 z} & j Ae^{-jk_0 z} + j \Gamma A e^{+jk_0 z} & 0 \\ j \frac{A^*}{Z} e^{+jk_0 z} - j \frac{\Gamma^* A^*}{Z} e^{-jk_0 z} & \frac{A^*}{Z} e^{+jk_0 z} - \frac{\Gamma^* A^*}{Z} e^{-jk_0 z} & 0 \end{vmatrix} =$$

$$= \vec{1}_z \left( \frac{AA^*}{Z} - \frac{AA^*\Gamma^*}{Z} e^{-2jk_0 z} + \frac{AA^*\Gamma}{Z} e^{+2jk_0 z} - \frac{AA^*\Gamma\Gamma^*}{Z} \right) = \vec{1}_z \frac{AA^*}{Z} (1 - \Gamma^* e^{-2jk_0 z} + \Gamma e^{+2jk_0 z} - \Gamma\Gamma^*) =$$

$$= \vec{1}_z \frac{|A|^2}{Z} (1 - \Gamma 2j \sin 2k_0 z - |\Gamma|^2)$$

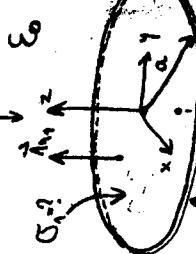
Odbojnosc:

$$E_v + E_o = E_p ; \quad -\frac{1}{Z_0} [E_v - E_o] = -\frac{1}{Z} E_p ; \quad \frac{E_o}{E_v} = \frac{Z - Z_0}{Z + Z_0} = \frac{1 - \sqrt{\epsilon_r}}{1 + \sqrt{\epsilon_r}} = \Gamma ; \quad \Gamma^2 = |\Gamma|^2$$

$$\Gamma = \Gamma^* = -|\Gamma| = \frac{\Gamma A e^{+jk_0 z}}{A e^{-jk_0 z}} = \Gamma e^{+2jk_0 z}$$

①

$$\vec{E}^0 = -\vec{A}_0 |\vec{E}^0|$$



$\sigma_s = ?$

Plaća je pravokutna na polje i mrežu!

$$G_1 = \vec{A}_{m_1} \cdot \epsilon_0 \vec{E}^0 = -\epsilon_0 |\vec{E}^0|$$

$$G_2 = \vec{A}_{m_2} \cdot \epsilon_0 \vec{E}^0 = +\epsilon_0 |\vec{E}^0|$$

③

$$\mu_0 \mu_0 (W_{max}) = ?$$

NOTUJU  
MAGNETNA  
ENERGIJA  
V KROGU

$$H = H_0 \frac{3}{2\pi\mu_0}; B = B_0 \frac{3\pi\mu_0}{2\pi\mu_0}; W = \frac{1}{2} HB\pi r^2.$$

$$W = \frac{1}{2} H_0 B_0 \left( \frac{9\pi\mu_0}{2\pi\mu_0} \right) \pi r^2 = 0 = \frac{1}{2} H_0 \frac{9(\pi\mu_0)^2}{(2\pi\mu_0)^2} \pi r^2$$

$$(2+\mu_0)^2 (2\pi\mu_0)^2 = 0 \rightarrow 2+\mu_0-2\mu_0=0 \rightarrow \mu_0=2$$

$$W_{max} = \frac{1}{2} H_0 B_0 \frac{3\pi}{(2\pi)^2} = \frac{3}{8} W_0; \quad N = \frac{4\pi r^3}{3}$$

$$W_{max} = \frac{3\pi}{4} \mu_0 H_0^2 r_0^3$$

④

$$\vec{E} = \vec{A} \sin(\omega t) e^{-j\beta z}; \alpha^2 + \frac{k^2}{c^2} = k^2$$

$$H = ?; \quad \vec{S} = ?; \quad S = ?; \quad \vec{j} = ?$$

$\vec{A} = \frac{i}{\rho} \nabla \times \vec{E} = \frac{i}{\rho} \frac{\partial}{\partial \rho} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & E_y & E_z \end{vmatrix} = -\frac{i}{\rho} \frac{\partial E_z}{\partial \rho} e^{j\omega t}$

$$\vec{H} = \frac{i}{\rho} \nabla \times \vec{E} = \frac{i}{\rho} \frac{\partial}{\partial \rho} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & E_y & E_z \end{vmatrix} = -\frac{i}{\rho} \frac{\partial E_z}{\partial \rho} e^{j\omega t}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H} = \frac{i}{\rho} \frac{\partial}{\partial \rho} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & E_y & E_z \end{vmatrix} = \frac{i}{\rho} \frac{\partial^2 E_z}{\partial \rho^2} e^{j\omega t}$$

$$\vec{j} = \text{rot} \vec{H} - j\omega \vec{E} = \frac{1}{\rho} \frac{\partial}{\partial \rho} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ H_x & H_y & H_z \end{vmatrix} = -j\omega \rho E_z e^{j\omega t}$$

$$= \vec{i}_x \left[ \frac{i}{\rho} \frac{\partial^2 E_z}{\partial \rho^2} e^{j\omega t} + \frac{i\omega}{\rho} E_z \sin(\omega t) \right] - j\omega E_z \sin(\omega t) = 0$$

⑤

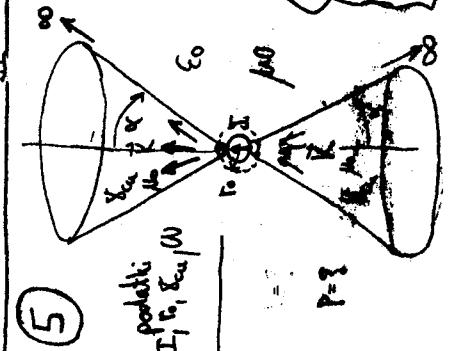
Simetrija:  $V_3 = V_4 = V_5 = 0$

$$\begin{cases} 4V_1 = 2V_6 + V_2 \\ 4V_2 = V_1 + V_6 \\ 4V_6 = 2V_1 + V_2 \end{cases} \quad \begin{cases} 16V_1 = 2V_6 + V_2 \\ 16V_2 = 4V_1 + 2V_6 \\ 16V_6 = 4V_1 + V_2 \end{cases} \quad \begin{cases} V_1 = \frac{2}{3}V_6 \\ V_2 = \frac{2}{3}V_6 \end{cases}$$

$$\begin{cases} V_1 = \frac{1}{4}(2V_6 + V_2) = \frac{1}{3}V_6 \\ V_2 = \frac{1}{4}(2V_6 + V_1) = \frac{1}{3}V_6 \end{cases} \quad \begin{cases} V_3 = -V_4 = -\frac{4}{3}V_6 \\ V_5 = -V_6 = -\frac{2}{3}V_6 \end{cases}$$

$$V_{4-5} = ?$$

②



$$\vec{J} = \int \frac{z}{\rho^2 \epsilon_0} \vec{S} ; \quad dR = \frac{-dr}{\rho \sin \theta}$$

$$R = 2 \int dr ; \quad P = \frac{1}{2} B^2 R$$

$$P = \frac{1}{2} B^2 \int_0^\infty \int_0^\pi \frac{dr}{r \sqrt{\frac{2}{\rho_0 \epsilon_0}} \sin^2 \theta} = \infty$$

Pri raznički učinku je delokat stáčev  
oměřena, když už neplatí vlastnosti

$$\textcircled{1} \quad \oint_A (\text{grad}V) \cdot d\vec{A} = ? \quad (r, \theta, \phi)$$

Akce na pole v kružniční soustavě

$$V = r \sin \theta \cos \phi ; \quad V = r^2 \sin \theta \cos \phi$$

$$\begin{aligned} \oint_A (\text{grad}V) \cdot d\vec{A} &= \int_0^{2\pi} \int_0^{\pi} \int_0^r \left( \frac{\partial V}{\partial r} \hat{r} + \frac{\partial V}{\partial \theta} \hat{\theta} + \frac{\partial V}{\partial \phi} \hat{\phi} \right) \cdot \left( \hat{r} dr \hat{r} + \hat{\theta} d\theta \hat{\theta} + \hat{\phi} d\phi \hat{\phi} \right) dr d\theta d\phi \\ &= - \int_0^{2\pi} \int_0^{\pi} \left( \frac{\partial V}{\partial r} dr + \frac{\partial V}{\partial \theta} d\theta + \frac{\partial V}{\partial \phi} d\phi \right) dr d\theta d\phi \end{aligned}$$

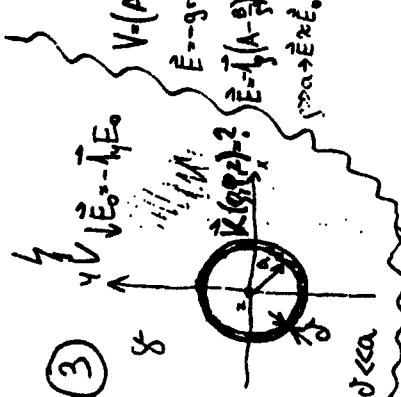
$$V = (E_0 r + \frac{b}{3}) \sin \phi$$

$$V(r, \theta) = 0 \rightarrow B = -E_0 r^2$$

$$\vec{E}(r, \theta) = -\hat{r} \frac{2E_0 r \sin \theta}{3} \hat{r}$$

$$\vec{E}(r, \theta) = \frac{1}{r} \frac{2E_0 \sin \theta}{3} \hat{r} \quad (\text{rot}(\text{grad}V) = \text{rot}(\text{curl}V) = 0)$$

$$\vec{K}(r) = -\hat{r} \frac{2E_0 r \cos \theta}{3} \hat{r}$$



$$\textcircled{3} \quad \vec{E} = E_r \hat{r} - E_\theta \hat{\theta}$$

$$V = (E_0 r + \frac{b}{3}) \sin \phi$$

$$\vec{E} = -\hat{r} \frac{2E_0 r \sin \theta}{3} \hat{r} + \hat{\theta} \frac{2E_0 r \cos \theta}{3} \hat{\theta}$$

$$E_r = -\frac{2E_0 r \sin \theta}{3} ; \quad E_\theta = \frac{2E_0 r \cos \theta}{3}$$

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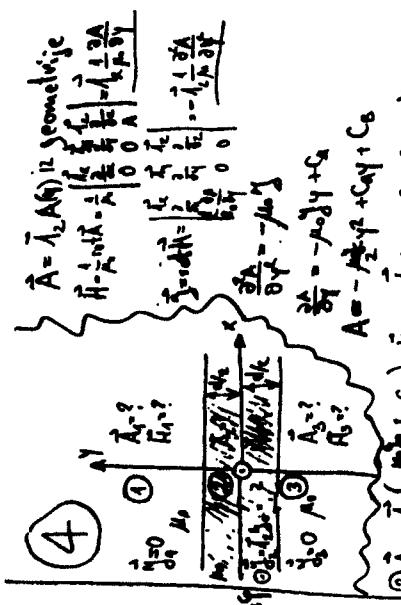
$$E_r = -\frac{2E_0 r \sin \theta}{3} ; \quad E_\theta = \frac{2E_0 r \cos \theta}{3}$$

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$$\textcircled{4} \quad \vec{E} = E_r \hat{r} - E_\theta \hat{\theta}$$

$$E_r = -\frac{2E_0 r \sin \theta}{3} ; \quad E_\theta = \frac{2E_0 r \cos \theta}{3}$$

$$\vec{E} = -\frac{2E_0 r \sin \theta}{3} \hat{r} + \frac{2E_0 r \cos \theta}{3} \hat{\theta}$$

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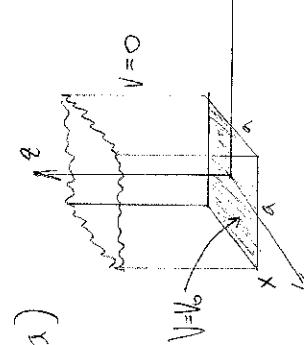
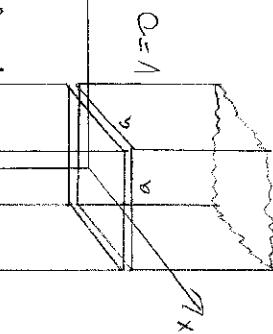
# Analizare ① mărgă

Postoare:

- a) izărâunatoare potențială și  
potențială cu lăsatul prezenă  
potențială  $V_0$  și sursă placită în  
potențială 0 nu stăpână

b) să rezolvăm problema primă

c) rezultat



rezultat

- ①  $V=0, b_0, x=0$
- ②  $V=0, b_0, x=a$
- ③  $V=0, b_0, y=0$
- ④  $V=0, b_0, y=a$
- ⑤  $V=V_0(x,y), b_0, z=0$
- ⑥  $V \rightarrow 0, b_0, z \rightarrow \infty$

$$E(z) = E \frac{e^{-\sqrt{k^2 + \alpha^2} z}}{\sqrt{k^2 + \alpha^2}} + F e^{-\sqrt{k^2 + \alpha^2} z}$$

foliu ② în ④ predată:  
 $\sin k a = 0 \rightarrow k = \frac{n\pi}{a} \quad n = 1, 2, 3, \dots$   
 $\sin k a = 0 \rightarrow k = \frac{n\pi}{a} \quad n = 1, 2, 3, \dots$

rezultat

$$V(x, y, z) = A C F e^{-\pi \sqrt{\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{a}\right)^2} z} \sin\left(\frac{m\pi}{a}x\right) \sin\left(\frac{n\pi}{a}y\right)$$

$$V(x, y, z) = \sum_{m,n=1}^{\infty} C_{m,n} e^{-\pi \sqrt{\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{a}\right)^2} z} \sin\left(\frac{m\pi}{a}x\right) \sin\left(\frac{n\pi}{a}y\right)$$

rezultat  $C_{m,n}$  (ortogonalitate, mări propoziții)

$$V(x, y, 0) = \sum_{m,n=1}^{\infty} C_{m,n} \sin\left(\frac{m\pi}{a}x\right) \sin\left(\frac{n\pi}{a}y\right) = V_0(x, y)$$

$$\sum_{m,n=1}^{\infty} C_{m,n} \int_0^a \sin\left(\frac{m\pi}{a}x\right) \sin\left(\frac{n\pi}{a}y\right) \sin\left(\frac{m\pi}{a}x\right) dx =$$

$$= \iint_0^a V_0(x, y) \sin\left(\frac{m\pi}{a}x\right) \sin\left(\frac{n\pi}{a}y\right) dx dy$$

$$C_{m,n} = \frac{4}{a^2} \iint_0^a V_0(x, y) \sin\left(\frac{m\pi}{a}x\right) \sin\left(\frac{n\pi}{a}y\right) dx dy$$

$$\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = 0$$

$$\underbrace{\frac{1}{X} \frac{\partial^2 X}{\partial x^2} + \frac{1}{Y} \frac{\partial^2 Y}{\partial y^2} + \frac{1}{Z} \frac{\partial^2 Z}{\partial z^2}}_{l^2 + l^2} = 0$$

$$X(x) = A \sin kx + B \cos kx$$

$$Y(y) = C \sin ly + D \cos ly$$

$$Z(z) = E e^{-\sqrt{l^2 + k^2} z} + F e^{-\sqrt{l^2 + k^2} z}$$

$$U = \frac{V_0}{2}$$

$$U = -\frac{V_0}{2}$$



$$U = 0$$

$$U = \begin{cases} V_0 & V(x, y, z) \\ + \frac{V_0}{2} & , z > 0 \\ - \frac{V_0}{2} & , z < 0 \end{cases}$$

$$U = \begin{cases} V_0 - V(x, y, z) & , z > 0 \\ 0 & , z = 0 \\ 0 + V(x, y, -z) & , z < 0 \end{cases}$$

L

maßgebend ① malze

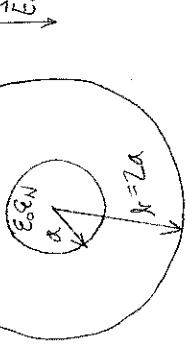
② produziert  $\epsilon_N = \frac{1}{2}$ ,  $A_N = 2a$ ,  $|E_N| = \frac{1}{2} |E_0|$

dialektische Kugel & dielectric shell & alpha

c) resultat

$$V = \begin{cases} V_0 - \frac{16V_0}{\pi^2} \sum_{m,n=1,3,5,\dots}^{\infty} \frac{1}{mn} \sin\left(\frac{m\pi}{a}x\right) \sin\left(\frac{n\pi}{a}y\right) e^{-\sqrt{\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{a}\right)^2}z}, & z > 0 \\ + \frac{V_0}{2}, & z = 0 \end{cases}$$

$$\frac{16V_0}{\pi^2} \sum_{m,n=1,3,5,\dots}^{\infty} \frac{1}{mn} \sin\left(\frac{m\pi}{a}x\right) \sin\left(\frac{n\pi}{a}y\right) e^{+\sqrt{\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{a}\right)^2}z}, & z < 0$$



$$\Delta V = 0 \quad \text{mit } \frac{\partial V}{\partial \phi} = 0; \vec{E} = -\nabla V = -\left(\vec{A}_v \frac{\partial V}{\partial r} + \vec{B}_v \frac{1}{r} \frac{\partial V}{\partial \theta}\right)$$

$$\text{Rohrtyp Kugel: } V_N = A_N r \cos\theta$$

$$\vec{E}_N = -A_N (\vec{r} \cos\theta - \vec{r} \sin\theta)$$

$$\text{Kugeltyp: } V_V = (A_V r + B_V r^{-2}) \cos\theta$$

$$\vec{E}_V = -\left(\vec{r}_N (A_V - \frac{2B_V}{r^3}) \cos\theta - \vec{r}_0 (A_V + \frac{B_V}{r^3} \sin\theta)\right)$$

$$\text{Kugeltyp: } V_Z = (A_Z r + B_Z r^{-2}) \cos\theta$$

$$\vec{E}_Z = -\left(\vec{r}_V (A_Z - \frac{2B_Z}{r^3}) \cos\theta - \vec{r}_0 (A_Z + \frac{B_Z}{r^3} \sin\theta)\right)$$

Möglichkeit zu normalisieren  $\vec{E}$

rechte Kugel - Blätter ①  $A_N = A_V + \frac{B_V}{a^3}$

linke Kugel - Blätter ②  $A_V + \frac{B_V}{a^3} = A_Z + \frac{B_Z}{a^3}$

③  $\epsilon_N A_N = \epsilon_V (A_V - \frac{2B_V}{a^3})$

④  $\epsilon_V (A_V - \frac{2B_V}{a^3}) = A_Z - \frac{2B_Z}{a^3}$

$$2 \times ② + ④: A_V (2 + \epsilon_V) + \frac{2B_V}{a^3} (1 - \epsilon_V) = 3A_Z \quad ⑤ \quad \text{durchline} \quad B_Z$$

$$2 \times \epsilon_V \cdot ① + ③: A_V = \frac{2\epsilon_V + \epsilon_N}{3\epsilon_V} \cdot A_N \quad ⑥ \quad \text{durchline} \quad A_V \quad \text{und} \quad A_N$$

$$\epsilon_V \cdot ① - ③: B_V = \frac{\epsilon_V - \epsilon_N}{3\epsilon_V} a^3 A_N \quad ⑦ \quad \text{durchline} \quad B_V \quad \text{und} \quad A_N$$

② in ⑦ einsetzen & ⑤ in ⑦ einsetzen:

$$A_N \left( \frac{(2\epsilon_V + \epsilon_N)(2 + \epsilon_V)}{3\epsilon_V} - \frac{2a^3(\epsilon_V - \epsilon_N)^2}{a^3 3\epsilon_V} \right) = 3A_Z$$

↳

metodopende (2) mælge

$$\text{produkt: } \frac{|E_0|}{|E_N|} = 2$$

$$\frac{A_2}{A_N} = \frac{E_0}{E_N} = \frac{(2\epsilon_V + \epsilon_N)(2 + \epsilon_V) - \frac{2a^2}{5}(E_V - E_N)^2}{9\epsilon_V} = 2$$

$$b = 2a$$

$$\frac{2\epsilon_V^2 + 8\epsilon_V + 8 - \frac{\epsilon_V^2}{a^2} + 2\epsilon_V - 4}{9\epsilon_V} = 2$$

$$\frac{4}{a^2}\epsilon_V^2 - 8\epsilon_V + 4 = 0$$

$$\epsilon_{V_{1,2}} = \frac{-8 \pm \sqrt{64 - 4a^2}}{2a} = \frac{-8 \pm \sqrt{36}}{2a}$$

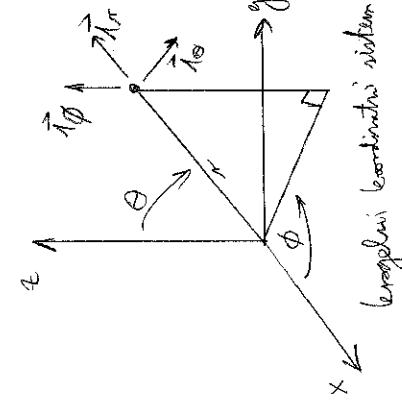
$$\epsilon_1 = \frac{4}{a} \neq$$

$$\epsilon_2 = 4 \quad \underline{\epsilon_V = 4}$$

$$\vec{r}_P = \vec{r}_x \cdot \sin \theta + \vec{r}_y \cos \theta$$

$$\vec{r}_Q = \vec{r}_\phi$$

$$\vec{r}_A = \vec{r}_x \cos \theta - \vec{r}_y \sin \theta$$



Kalibri koordinatni sistem

✓

$V=0$

(1.)

$$\begin{array}{c} V=0 \\ \downarrow \\ \begin{array}{c} +V_0 & -V_0 \\ | & | \\ -V_0 & V_0 \\ | & | \\ V_6 & V_7 \\ | & | \\ V_6 & V_7 & V_8 & V_9 & V_{10} \\ | & | & | & | & | \\ V_1 & V_2 & V_3 & V_4 & V_5 \\ | & | & | & | & | \\ +V_0 & & & & & \end{array} \end{array}$$

$$\begin{array}{c} V=0 \\ \rightarrow \\ \begin{array}{c} -V_0 & +V_0 \\ | & | \\ -V_4 & -V_5 \\ | & | \\ -V_6 & -V_7 \\ | & | \\ -V_1 & -V_2 & -V_3 & -V_4 & -V_5 \\ | & | & | & | & | \\ -V_0 & & & & & \end{array} \end{array}$$

Berechnung +V\_0

symmetrische

① in ②

$$\begin{aligned} ① \quad 4V_1 &= V_2 + V_6 + V_0 - V_5 = V_2 + V_6 \\ ② \quad 4V_2 &= V_0 + V_1 + V_4 \\ ③ \quad 4V_6 &= -V_0 + V_1 - V_4 + V_5 \\ ④ \quad 5V_6 &= -V_0 + V_1 + V_4 \end{aligned}$$

② in ③

$$\begin{aligned} ① \quad 4V_4 &= V_2 + V_6 - V_1 \\ ② \quad 5V_4 &= V_2 + V_6 \\ ③ \quad 4V_2 &= V_0 + V_1 + V_4 \\ ④ \quad 5V_6 - 4V_4 &= -2V_0 \\ ⑤ \quad V_2 &= V_0 + V_1 + V_4 \\ ⑥ \quad 4V_2 &= V_0 + V_1 + V_4 \\ ⑦ \quad 4V_2 &= V_0 + V_1 + V_4 \end{aligned}$$

③ in ④, berechnen  $V_6$

$$\begin{aligned} ④ \quad 5V_6 &= -V_0 + V_1 + V_4 \\ ⑤ \quad 5V_6 - 4V_4 &= V_0 \\ ⑥ \quad V_2 &= \frac{5V_6 + 2V_0}{4} \end{aligned}$$

$$\begin{aligned} ⑦ \quad 5V_6 &= -V_0 + V_1 + V_4 \\ ⑧ \quad 5V_6 &= V_2 + V_0 - V_1 \\ ⑨ \quad 0 &= 2V_4 - 5V_2 + V_0 - V_1 \end{aligned}$$

$$0 = \frac{91}{4}V_4 - 5V_2 + V_0$$

$$\begin{aligned} ⑩ \quad 5V_2 &= \frac{91}{4}V_4 + V_0 \\ ⑪ \quad V_2 &= \frac{91}{20}V_4 + \frac{V_0}{5} \end{aligned}$$

↳

# mathematische Physik ①

Übungsaufgabe V2

$$\frac{91}{5} V_4 + V_0 = \frac{5 V_6 + 2 V_0}{4}$$

$$V_6 = \frac{(91 V_4 + V_0) \cdot 4 - 10 V_0}{25}$$

$$V_6 = \frac{91 V_4 + 41 V_0}{25} - \frac{2 V_0}{5}$$

Bestimmung

$$V_1 = \frac{5}{4} V_4 = \underline{\underline{\frac{5}{319} V_0}}$$

$$V_2 = \frac{91}{20} V_4 + \frac{V_0}{5} = \underline{\underline{\frac{91}{319} V_0 + \frac{V_0}{5}}}$$

$$V_2 = \left( \frac{364}{6380} + \frac{1}{5} \right) V_0 = \frac{410}{1595} V_0 = \underline{\underline{\frac{62}{319} V_0}}$$

$$V_6 = \frac{91}{16} V_4 - \frac{V_0}{4} = \underline{\underline{\frac{91}{319} V_0 - \frac{V_0}{4}}}$$

$$V_6 = \frac{91 - 319}{12 \cdot 46} V_0 = \underline{\underline{-\frac{62}{319} V_0}}$$

letzter Resultat:

$$V_1 = \frac{5}{319} V_0$$

$$V_2 = \frac{62}{319} V_0$$

$$V_3 = 0$$

$$V_4 = -V_2 = -\frac{62}{319} V_0$$

$$V_5 = -V_1 = -\frac{5}{319} V_0$$

Bestimmen  $V_6$

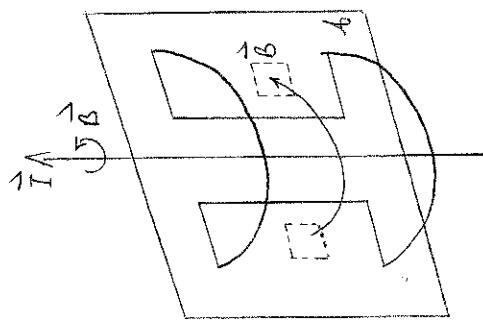
$$\frac{91}{16} V_4 - \frac{V_0}{4} = \frac{91 V_4 + 41 V_0}{25} - \frac{2 V_0}{5}$$

$$\frac{91}{16} V_4 - \frac{V_0}{4} = \frac{21 V_4 + 6 V_0}{25} - \frac{10 V_0}{25}$$

$$\left( \frac{91}{16} - \frac{91}{25} \right) V_4 = \left( \frac{1}{4} - \frac{6}{25} \right) V_0$$

$$\frac{319}{400} V_4 = \underline{\underline{\frac{1}{100} V_0}}$$

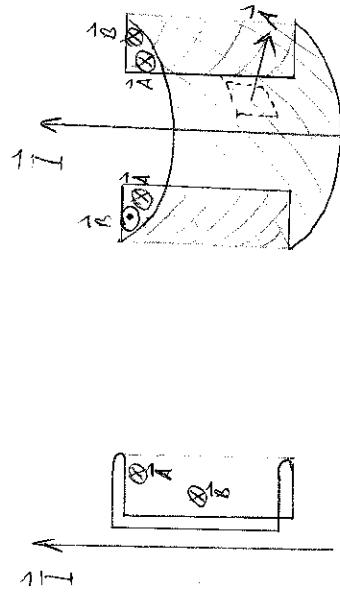
$$V_4 = \underline{\underline{\frac{4}{319} V_0}}$$



5

$$\oint_L \vec{B} \cdot d\vec{A} = 0$$

Mitte eines zentralen Punktes ist  $\vec{B}$  senkrecht zu  $d\vec{A}$ , also ist  $\vec{B}$  Null.



$$\oint_L \vec{B} \cdot d\vec{A} + \int_A B \cdot (-d\vec{A}) = 0$$

$$\text{dabei: } H = \frac{\Phi}{I} = \underline{\underline{0}}$$

(1) Nášme:

- energie rezonátora
- zadátka rezonátora

$$Q = \frac{W}{P}$$

$$W = \frac{1}{2} \epsilon \int_V |E_{\max}|^2 dV$$

energie rezonátora

$$W = \frac{\epsilon E_0^2 \cdot 2\pi R}{2} \int_a^{\infty} J_0^2(\kappa_1 r) r^2 dr$$

$$P = \frac{\epsilon E_0^2 \cdot 2\pi R}{2} \int_a^{\infty} J_0^2(\kappa_1 r) \cdot \kappa_1^2 r^2 dr$$

$$W = \frac{4\pi \epsilon E_0^2 \alpha^2 R}{2} \int_a^{\infty} J_0^2(\kappa_1 r)$$

$$P = \frac{4\pi \epsilon E_0^2 \alpha^2 R}{2} \int_a^{\infty} J_0^2(\kappa_1 r) r^2 dr$$

meč rezonátora

$$P = \frac{1}{2} \int_R^{\infty} |\vec{E}|^2 r^2 dr$$

$$P = \frac{\pi E_0^2 \alpha^2 R}{2} \int_a^{\infty} J_0^2(\kappa_1 r) r^2 dr$$

$$P = \frac{\pi E_0^2 \alpha^2 R}{2} (J_0(\kappa_1 a))^2$$

$$P = \frac{\pi E_0^2 \alpha^2 R}{2} J_0^2(\kappa_1 a)$$

$$U = \vec{T}_Z E_0 J_0(\kappa_1 a); \kappa_1 = \frac{2,405...}{a}$$

našpraní ① nálož

$$\vec{H} = \frac{i}{\omega \mu_0} \text{rot} \vec{E} = \frac{i}{\omega \mu_0 \beta} \begin{vmatrix} \vec{T}_Y & \vec{T}_X & 0 \\ \partial/\partial Y & \partial/\partial X & 0 \\ 0 & 0 & E_0 J_0(\kappa_1 a) \end{vmatrix}$$

$$\vec{H} = \frac{1}{\omega \mu_0} (-j \vec{T}_Y) E_0 J_0(\kappa_1 a)$$

$$\vec{H} = -\vec{T}_Y \frac{j \kappa_1}{\omega \mu_0} E_0 J_0(\kappa_1 a)$$

metra experimentálna

$$J_m(x) = -\frac{m}{x} J_m(x) + J_{m-1}(x)$$

$$J_0'(ax) = -\frac{a}{x} J_0(ax) + J_{-1}(ax)$$

Nálogie pre prednosť:

$$J_m(x) = (-1)^m J_m(x)$$

$$J_{-1}(ax) = (-1)^1 J_1(ax)$$

prednosť:

$$J_0'(ax) = -J_1(ax)$$

$$J_0'(x) = -J_1(x)$$

meč rezonátora

$$P = \frac{1}{2} \int_R^{\infty} |\vec{E}|^2 r^2 dr$$

$$P = \frac{\pi E_0^2 \alpha^2 R}{2} \int_a^{\infty} J_0^2(\kappa_1 r) r^2 dr$$

$$P = \frac{\pi E_0^2 \alpha^2 R}{2} \left( \int_a^{\infty} J_0^2(\kappa_1 r) \frac{dr}{\kappa_1} \right)$$

$$P = \frac{\pi E_0^2 \alpha^2 R}{2} (J_0(\kappa_1 a))^2$$

$$\text{magnetické pole} \quad \begin{vmatrix} \vec{T}_Y & \vec{T}_X & 0 \\ \partial/\partial Y & \partial/\partial X & 0 \\ 0 & 0 & E_0 J_0(\kappa_1 a) \end{vmatrix}$$

$$\vec{H} = \frac{i}{\omega \mu_0} \text{rot} \vec{E} = \frac{i}{\omega \mu_0 \beta} \begin{vmatrix} \vec{T}_Y & \vec{T}_X & 0 \\ \partial/\partial Y & \partial/\partial X & 0 \\ 0 & 0 & E_0 J_0(\kappa_1 a) \end{vmatrix}$$

$$\vec{H} = \frac{1}{\omega \mu_0} (-j \vec{T}_Y) E_0 J_0(\kappa_1 a)$$

$$\vec{H} = -\vec{T}_Y \frac{j \kappa_1}{\omega \mu_0} E_0 J_0(\kappa_1 a)$$

$$\text{resonančný frekvent} \quad \begin{vmatrix} \vec{T}_Y & \vec{T}_X & 0 \\ \partial/\partial Y & \partial/\partial X & 0 \\ 0 & 0 & \vec{P} \delta(\omega - \omega_0) \end{vmatrix} =$$

$$\text{rot} \vec{H} = j \omega \epsilon \vec{E} = \frac{1}{\rho} \begin{vmatrix} \vec{T}_Y & \vec{T}_X & 0 \\ \partial/\partial Y & \partial/\partial X & 0 \\ 0 & 0 & \vec{P} \delta(\omega - \omega_0) \end{vmatrix} =$$

$$= \vec{T}_Y \frac{-1}{\rho} \left( j \frac{\kappa_1}{\omega \mu_0} E_0 J_0(\kappa_1 a) \right)''(\kappa_1 a) + \frac{j \kappa_1}{\omega \mu_0} E_0 J_0(\kappa_1 a) =$$

$$= \vec{T}_Y \frac{j \kappa_1 \epsilon_0}{\omega \mu_0 \beta} (J_0'(\kappa_1 a))^2 + J_0^2(\kappa_1 a) = \vec{T}_Y \frac{j \kappa_1 \epsilon_0}{\omega \mu_0 \beta} \sin^2(\kappa_1 a)$$

$$\text{racionálne:} \quad \vec{A} \vec{t} \vec{H} = j \omega \epsilon \vec{E} \vec{t}$$

$$\vec{A} \vec{t} \frac{j \kappa_1 \epsilon_0}{\omega \mu_0} J_0(\kappa_1 a) = j \omega \epsilon \vec{E} \vec{t} \frac{j \kappa_1 \epsilon_0}{\omega \mu_0} J_0(\kappa_1 a) = \vec{E} \text{ podľa}$$

$$\omega \epsilon = \frac{\kappa_1^2}{\omega \mu_0}$$

$$\omega^2 = \frac{\kappa_1^2}{\omega \epsilon}$$

$$\omega = \frac{W}{P}$$

$$Q = \frac{\alpha_1 \pi \epsilon_0^2 a^2 R J_0^2(\kappa_1 a)^2}{\sqrt{\mu_0 \epsilon_0} E_0^2 \pi a^2 R J_0^2(\kappa_1 a)^2} = \frac{\alpha_1 \epsilon}{\sqrt{\mu_0 \epsilon}} ; \quad Z = \sqrt{\frac{\mu}{\epsilon}} ; \quad Q = \frac{\alpha_1}{\sqrt{\mu \epsilon}}$$

(2) rohlinek rezonančního obvodu

$$f_{\text{reson}} = \frac{C_0}{2} \sqrt{\left(\frac{L}{\alpha}\right)^2 + \left(\frac{m}{L}\right)^2}$$

$$\alpha > L > C \quad f_1 = \frac{C_0}{2} \sqrt{\left(\frac{1}{\alpha}\right)^2 + \left(\frac{1}{L}\right)^2} = 5,229 \text{ GHz}$$

$\Delta X$  optima je  $\alpha$

$$\alpha = 5 \text{ cm}$$

$$\lambda_r = 3,5 \text{ cm}$$

$$C = 3 \text{ nm}$$

$$f_2 = \frac{C_0}{2} \sqrt{\left(\frac{1}{\alpha}\right)^2 + \left(\frac{1}{C}\right)^2} = 5,828 \text{ GHz}$$

$$f_3 = \frac{C_0}{2} \sqrt{\left(\frac{1}{L}\right)^2 + \left(\frac{1}{C}\right)^2} = 6,050 \text{ GHz}$$

$$f_4 = \frac{C_0}{2} \sqrt{\left(\frac{1}{L}\right)^2 + \left(\frac{1}{\alpha}\right)^2} = 6,583 \text{ GHz}$$

$$f_5 = \frac{C_0}{2} \sqrt{\left(\frac{1}{C}\right)^2 + \left(\frac{1}{\alpha}\right)^2} = 7,040 \text{ GHz}$$

opracujeme dimenze  $\alpha$ , maximum je  $\alpha \approx c$ .

$$f_5 - f_2 = 1,242 \text{ GHz}$$

$$\underline{f_5 - f_2 = 1,354 \text{ GHz} = \Delta f_{\text{max}}}$$

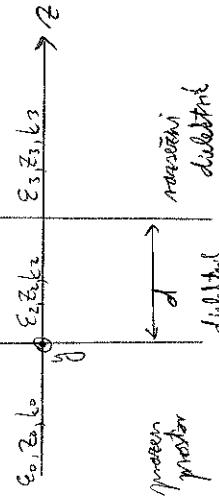
$$\begin{aligned} \Gamma &= \frac{\text{oddinat}}{\text{spodinat}} \\ &= \frac{E_{1+} e^{-j\varphi_{1d}}}{E_{1-} e^{j\varphi_{1d}}} = \frac{E_{2+} e^{-j\varphi_{2d}}}{E_{2-} e^{j\varphi_{2d}}} = \frac{E_{3+} e^{-j\varphi_{3d}}}{E_{3-} e^{j\varphi_{3d}}} \end{aligned}$$

oddinat  $E_3$ :

$$\frac{E_{2-}}{E_{2+}} = \frac{Z_3 - Z_2}{Z_3 + Z_2} e^{-2j\varphi_{2d}}$$

(3) násilně oddinat  $\mu = 0$

$$\Gamma = \frac{\text{oddinat}}{\text{spodinat}}$$



$$\begin{aligned} \vec{E}_1 &= \vec{T}_X (E_{1+} e^{-j\varphi_{1d}} + E_{1-} e^{j\varphi_{1d}}) \\ \vec{H}_1 &= \vec{T}_Y \left( \frac{E_{1+}}{Z_0} e^{-j\varphi_{1d}} - \frac{E_{1-}}{Z_0} e^{j\varphi_{1d}} \right) \end{aligned}$$

$$\begin{aligned} \vec{E}_2 &= \vec{T}_X (E_{2+} e^{-j\varphi_{2d}} + E_{2-} e^{j\varphi_{2d}}) \\ \vec{H}_2 &= \vec{T}_Y \left( \frac{E_{2+}}{Z_0} e^{-j\varphi_{2d}} - \frac{E_{2-}}{Z_0} e^{j\varphi_{2d}} \right) \end{aligned}$$

násilná 2 / 3  
 $Z = d, \vec{E}_2 = \vec{E}_3, \vec{H}_2 = \vec{H}_3$

$$\begin{aligned} \text{násilný oddinat v portu 3, tento je nezávislý} \\ E_{2+} e^{-j\varphi_{2d}} + E_{2-} e^{j\varphi_{2d}} = \frac{E_{1+}}{Z_0} e^{-j\varphi_{1d}} - \frac{E_{1-}}{Z_0} e^{j\varphi_{1d}} \end{aligned}$$

$$\begin{aligned} \frac{E_{1+}}{Z_0} - \frac{E_{1-}}{Z_0} &= \frac{E_{2+}}{Z_0} - \frac{E_{2-}}{Z_0} \\ \Gamma &= \frac{E_{1-}}{E_{1+}} \end{aligned}$$

L

metodický (3) náleží

$$E_{1+}(1+\Gamma) = E_{2+}(1 + \frac{E_{2-}}{E_{2+}})$$

$$\frac{E_{1+}}{Z_0} (1 - \Gamma) = \frac{E_{2+}}{Z_0} \left( 1 - \frac{E_{2-}}{E_{2+}} \right)$$

$$\frac{Z_0}{Z_0} \frac{1 + \Gamma}{1 - \Gamma} = \frac{Z_0}{Z_0} \frac{1 + \frac{E_{2-}}{E_{2+}}}{1 - \frac{E_{2-}}{E_{2+}}} =$$

odvození

$$\Gamma = \frac{\frac{Z_0}{Z_0} \frac{1 + \frac{E_{2-}}{E_{2+}}}{1 - \frac{E_{2-}}{E_{2+}}} - 1}{\frac{Z_0}{Z_0} \frac{1 + \frac{E_{2+}}{E_{2-}}}{1 - \frac{E_{2+}}{E_{2-}}} + 1}$$

$$\text{Nastavíme } \frac{E_{2-}}{E_{2+}} = \frac{Z_3 - Z_2}{Z_3 + Z_2} e^{-2jk_2 d}$$

$$\Gamma = \frac{\frac{Z_2}{Z_0} \frac{1 + \frac{Z_3 - Z_2}{Z_3 + Z_2} e^{-2jk_2 d}}{1 - \frac{Z_3 - Z_2}{Z_3 + Z_2} e^{-2jk_2 d}} - 1}{\frac{Z_2}{Z_0} \frac{1 + \frac{Z_3 - Z_2}{Z_3 + Z_2} e^{-2jk_2 d}}{1 - \frac{Z_3 - Z_2}{Z_3 + Z_2} e^{-2jk_2 d}} + 1}$$

↳

(4)  $\vec{E} = \vec{K}_x E_0 \sin(\frac{\pi}{k} y) e^{-jkz}$

$$P = \int_A \vec{S} \cdot d\vec{A}, \quad \vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^*, \quad P = \frac{1}{2} \int_A |k|^2 R_P dA$$

Magnetické pole

$$H = \frac{i}{\omega \mu} \begin{vmatrix} \vec{K}_x & \vec{T}_y & \vec{T}_z \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ E_0 \sin(\frac{\pi}{k} y) e^{-jkz} & 0 & 0 \end{vmatrix} = \frac{i}{\omega \mu} \begin{pmatrix} (-\vec{T}_y) E_0 \sin(\frac{\pi}{k} y) e^{-jkz} \\ \vec{T}_x \\ -\vec{T}_z E_0 \frac{\pi}{k} \cos(\frac{\pi}{k} y) e^{-jkz} \end{pmatrix}$$

přetík moří

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \vec{K}_x \frac{E_0 \beta}{2 \omega \mu} \sin^2(\frac{\pi}{k} y) - \vec{T}_y \frac{i \frac{E_0^2 \beta}{2 k \omega \mu}}{2 \omega \mu} \sin(\frac{\pi}{k} y) \cos(\frac{\pi}{k} y)$$

prestřík moří

$$P_p = \int_A \vec{S} \cdot d\vec{A} = \iint_D \vec{K}_x \cdot \vec{S} dx dy = \iint_D \frac{E_0^2 \beta}{2 \omega \mu} \sin^2(\frac{\pi}{k} y) - \vec{T}_y \frac{i \frac{E_0^2 \beta}{2 k \omega \mu}}{2 \omega \mu} \sin(\frac{\pi}{k} y) \cos(\frac{\pi}{k} y) dx dy = \frac{E_0^2 \beta \cdot a \cdot b}{4 \omega \mu}$$

plasmon těleso:

$$\vec{K} = \vec{K}_x \times \vec{H}$$

$$\begin{aligned} x=0: \quad \vec{K}_1 &= \vec{K}_x \frac{E_0 \beta}{\omega \mu} \sin(\frac{\pi}{k} y) e^{-jkz} + \vec{T}_y \frac{i \frac{E_0 \pi}{2 k}}{\omega \mu} \cos(\frac{\pi}{k} y) e^{-jkz} \\ x=a: \quad \vec{K}_2 &= -\vec{K}_x \frac{E_0 \beta}{\omega \mu} \sin(\frac{\pi}{k} y) e^{-jkz} - \vec{T}_y \frac{i \frac{E_0 \pi}{2 k}}{\omega \mu} \cos(\frac{\pi}{k} y) e^{-jkz} \\ y=0: \quad \vec{K}_3 &= \vec{K}_x \frac{i \frac{E_0 \pi}{2 k}}{\omega \mu} e^{-jkz} \\ y=b: \quad \vec{K}_4 &= -\vec{K}_x \frac{i \frac{E_0 \pi}{2 k}}{\omega \mu} e^{-jkz} \end{aligned}$$

modellierung ① nähern

negligieren most

$$P_i = \frac{1}{2} \int_A |k|^2 R_p dA ; R_p = \sqrt{\frac{\omega \mu}{2 \beta^2}}$$

$$P_i = P(x=0) + P(y=0) + P(z=0)$$

$$\begin{aligned} P(x=0) &= P(x=a) = \frac{1}{2} \iint_0^L \frac{\epsilon_0^2 R_p}{\omega^2 \mu^2} \left( \beta^2 \sin^2\left(\frac{\pi}{L}y\right) + \left(\frac{\pi}{L}\right)^2 \cos^2\left(\frac{\pi}{L}y\right) \right) R_p dy dz = \\ &= \frac{\epsilon_0^2}{2 \omega^2 \mu^2} \left( \beta^2 \frac{L}{2} \delta + \left(\frac{\pi}{L}\right)^2 \frac{L}{2} \delta \right) R_p = \frac{\epsilon_0^2 R_p \cdot \beta \cdot L}{4 \omega^2 \mu^2} \left( \beta^2 + \left(\frac{\pi}{L}\right)^2 \right) \end{aligned}$$

$$P(y=0) = P(y=b) = \frac{1}{2} \iint_0^b \frac{\epsilon_0^2 \pi^2}{\omega^2 \mu^2 \beta^2} R_p dx dz = \frac{\epsilon_0^2 R_p \cdot \pi^2 a \beta}{2 \omega^2 \mu^2 \beta^2}$$

$$P_z = 2 P(x=0) + 2 P(y=0)$$

$$P_z = \frac{\epsilon_0^2 R_p \beta}{2 \omega^2 \mu^2} \left( \frac{2 \pi \pi^2}{L^2} + \beta^2 + \frac{\pi^2}{L^2} \right) = \frac{\epsilon_0^2 R_p \beta}{2 \omega^2 \mu^2} \left( \beta^2 + \frac{\pi^2}{L^2} (\beta + 2a) \right)$$

Iteration Schleife

$$\frac{dP_z}{d\beta} = - \frac{\epsilon_0^2 R_p}{2 \omega^2 \mu^2} \left( \beta^2 + \frac{\pi^2}{L^2} (\beta + 2a) \right)$$

$$\frac{dP_z}{R_p} = - \frac{\epsilon_0^2 R_p \cdot 4 \omega \mu}{2 \omega^2 \mu^2 \epsilon_0^2 \beta^2} \left( \beta^2 + \frac{\pi^2}{L^2} (\beta + 2a) \right) \cdot d\beta$$

$$\ln \frac{P(O)}{P(O)} = \frac{2 R_p}{\alpha \mu \pi \beta} \left( \beta^2 + \frac{\pi^2}{L^2} (\beta + 2a) \right) \cdot d\beta$$

$$A = 20 \log \frac{P(O)}{P(O)} = 20 \log \frac{2 \sqrt{\frac{\omega \mu}{\beta^2 + \frac{\pi^2}{L^2} (\beta + 2a)}}}{\alpha \mu \beta} \left[ dB/m \right]$$

abgleichen mit obige

$$A/l = 20 \log \frac{\sqrt{\frac{2}{\beta^2 + \frac{\pi^2}{L^2} (\beta + 2a)}}}{\beta} \left[ dB/m \right]$$

# Rešitev 1. kolokvija iz ELEKTROMAGNETIKE 04.12.2002

(1) Votla Kovinska krogle  $\vec{J} = \vec{J}_0 \cos \theta \vec{e}_{\text{out}}$

$$I(\theta) = j\omega 2\pi r \int_0^r r^2 \sin \theta d\theta \delta(\theta) = j\omega 2\pi r^2 \int_0^r \sin \theta d\theta = j\omega \pi r^2 (1 - \cos^2 \theta)$$

$$\vec{I}(\theta) = j\omega \pi r^2 \cos \theta \vec{e}_y$$

$$\vec{I}(\theta) = j\omega \pi r^2 \sin \theta \vec{e}_x$$

$$\vec{K} = ?$$

$$\vec{K} = \int_0^r K_0 r' dr' = \int_0^r \frac{1}{r'} K_0 r' dr' = \int_0^r \frac{1}{r'} \left( \frac{j\omega \pi r^2}{r} \right) r' dr' = j\omega \pi r^2 \int_0^r \frac{1}{r'} dr' = j\omega \pi r^2 \ln r$$

$$\vec{A}(rr\phi) = \frac{\mu_0}{4\pi} \int_0^r \frac{1}{r' r} \vec{e}_r \cdot \vec{e}_{\phi} dr' = \frac{\mu_0}{4\pi} \int_0^r \frac{1}{r' r} \vec{e}_r \cdot \vec{e}_\phi dr' = \frac{\mu_0}{4\pi} \int_0^r \frac{1}{r' r} \vec{e}_r \cdot \vec{e}_\phi dr'$$

$$\vec{A}(rr\phi) = \frac{\mu_0}{4\pi} \int_0^r \frac{1}{r' r} \vec{e}_r \cdot \vec{e}_\phi dr' = \frac{\mu_0}{4\pi} \int_0^r \frac{1}{r' r} \vec{e}_r \cdot \vec{e}_\phi dr' = \frac{\mu_0}{4\pi} \int_0^r \frac{1}{r' r} \vec{e}_r \cdot \vec{e}_\phi dr'$$

$$\vec{A}(rr\phi) = \frac{\mu_0}{4\pi} \int_0^r \frac{1}{r' r} \vec{e}_r \cdot \vec{e}_\phi dr' = \frac{\mu_0}{4\pi} \int_0^r \frac{1}{r' r} \vec{e}_r \cdot \vec{e}_\phi dr'$$

$$V_2 = \frac{V_1 + V_3}{4} = \frac{8}{19} V_0$$

$$V_1 = \frac{12}{13} V_0$$

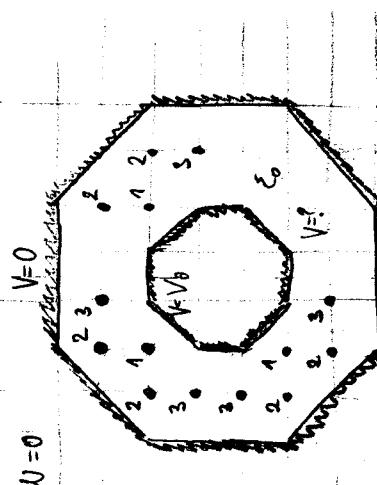
$$V_3 = \frac{48}{19} V_0$$

$$V_1 + 4V_0 = V_1 + 4V_0$$

$$V_3 + 4V_0 = V_3 + 4V_0$$

$$V_1 + 4V_0 = V_1 + 4V_0$$

$$V_1 + 4V_0 = V_1 + 4V_0$$



$$4V_1 = 2V_0 + 2V_2 \quad 8V_1 = 4V_0 + V_1 + V_3 \quad 11V_3 = V_1 + 4V_0$$

$$4V_2 = V_1 + V_3 \quad \rightarrow V_3 = 4V_1 - 4V_0$$

$$4V_3 = V_2 + V_1 + V_0 \quad 16V_3 = V_1 + 5V_3 + 4V_0$$

$$V_1 = \frac{12}{13} V_0$$

$$V_1 + V_3 = \frac{8}{19} V_0$$

$$V_1 = \frac{12}{13} V_0$$

$$V_3 = \frac{48}{19} V_0$$

$$V_1 + 4V_0 = V_1 + 4V_0$$

$$V_3 + 4V_0 = V_3 + 4V_0$$

$$V_1 + 4V_0 = V_1 + 4V_0$$

$$V_1 + 4V_0 = V_1 + 4V_0$$

(4)

$V(x)$

$$V = \sum_n C_n \sin(n \frac{\pi}{a} x) \sinh(n \frac{\pi}{b} y)$$

$$C_n = \frac{2V_0}{\pi n} \left( \cos(n \frac{\pi}{4}) - \cos(n \frac{3\pi}{4}) \right)$$

$$V(x,y) = \begin{cases} 0 & ; 0 < x < a/2 \\ V_0 & ; a/2 < x < a \\ 0 & ; 0 < y < b \\ V_0 & ; b < y < b \\ 0 & ; a < x < a \\ 0 & ; 0 < y < b \end{cases}$$

$$V(x,y) = \sum_n C_n \sin(n \frac{\pi}{a} x) \sinh(n \frac{\pi}{b} y)$$

$$C_n = \frac{2V_0}{\pi n} \left( \cos(n \frac{\pi}{4}) - \cos(n \frac{3\pi}{4}) \right)$$

$$V(x,y) = \frac{2V_0}{\pi} \sum_{n=1}^{\infty} \frac{\cosh(n \frac{\pi}{b}) - \cosh(n \frac{3\pi}{4})}{\sinh(n \frac{\pi}{b})} \sin(n \frac{\pi}{a} x) \sinh(n \frac{\pi}{b} y)$$

(2)

$V(x)$

$$V = \sum_n C_n \sin(n \frac{\pi}{a} x) \sinh(n \frac{\pi}{b} y)$$

$$C_n = \frac{2V_0}{\pi n} \left( \cos(n \frac{\pi}{4}) - \cos(n \frac{3\pi}{4}) \right)$$

$$V(x,y) = \frac{2V_0}{\pi} \sum_{n=1}^{\infty} \frac{\cosh(n \frac{\pi}{b}) - \cosh(n \frac{3\pi}{4})}{\sinh(n \frac{\pi}{b})} \sin(n \frac{\pi}{a} x) \sinh(n \frac{\pi}{b} y)$$

(5)

$V(r\phi)$

$$V(r\phi) = V_0 \int_0^r \int_0^\pi \int_0^{2\pi} \frac{1}{r^2 + r'^2 - r^2} \vec{e}_r \cdot \vec{e}_\phi dr' d\phi =$$

$$\vec{E} = ?$$

$$\vec{E} = -\vec{E}_r V_0 \int_0^r \int_0^\pi \int_0^{2\pi} \frac{1}{r^2 + r'^2} \vec{e}_r \cdot \vec{e}_\phi dr' d\phi$$

$$\vec{E} = -\vec{E}_r V_0 \int_0^r \int_0^\pi \int_0^{2\pi} \frac{1}{r^2 + r'^2} \vec{e}_r \cdot \vec{e}_\phi dr' d\phi$$

$$V(r\phi) = V_0 \int_0^r \int_0^\pi \int_0^{2\pi} \frac{1}{r^2 + r'^2} \vec{e}_r \cdot \vec{e}_\phi dr' d\phi$$

$$\vec{E} = ?$$

$$\vec{E} = -\vec{E}_r V_0 \int_0^r \int_0^\pi \int_0^{2\pi} \frac{1}{r^2 + r'^2} \vec{e}_r \cdot \vec{e}_\phi dr' d\phi$$

$$\vec{E} = -\vec{E}_r V_0 \int_0^r \int_0^\pi \int_0^{2\pi} \frac{1}{r^2 + r'^2} \vec{e}_r \cdot \vec{e}_\phi dr' d\phi$$

$$\vec{E} = -\vec{E}_r V_0 \int_0^r \int_0^\pi \int_0^{2\pi} \frac{1}{r^2 + r'^2} \vec{e}_r \cdot \vec{e}_\phi dr' d\phi$$

$$\vec{E} = -\vec{E}_r V_0 \int_0^r \int_0^\pi \int_0^{2\pi} \frac{1}{r^2 + r'^2} \vec{e}_r \cdot \vec{e}_\phi dr' d\phi$$

(3)

$V(x)$

$$V = \sum_n C_n \sin(n \frac{\pi}{a} x) \sinh(n \frac{\pi}{b} y)$$

$$C_n = \frac{2V_0}{\pi n} \left( \cos(n \frac{\pi}{4}) - \cos(n \frac{3\pi}{4}) \right)$$

$$V(x,y) = \frac{2V_0}{\pi} \sum_{n=1}^{\infty} \frac{\cosh(n \frac{\pi}{b}) - \cosh(n \frac{3\pi}{4})}{\sinh(n \frac{\pi}{b})} \sin(n \frac{\pi}{a} x) \sinh(n \frac{\pi}{b} y)$$

Kadankin zatki v isti yavini, d>a

(3)  $\vec{E} = (\vec{J}_0 + j\vec{H}_0) \left( \frac{e^{jkr}}{r} \sin\theta \right)$   $\mu = \mu_0$   $\epsilon = \epsilon_0$

$r \gg \lambda$  möglich ca. unte redetige!

$\vec{H} = ?$   $S = ?$   $k = ?$

$\vec{H} = \frac{j}{\omega \mu} \text{rot} \vec{E} = \frac{j}{\omega \mu} \frac{1}{r^2 \sin^2 \theta} \begin{vmatrix} \vec{r}_z & \vec{r}_\theta & \vec{r}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \end{vmatrix} \begin{matrix} \text{mehr} \\ \frac{1}{r^2} \\ \frac{1}{r^2} \\ 0 \end{matrix} \begin{matrix} \text{mehr} \\ \frac{1}{r^2} \\ \frac{1}{r^2} \\ 0 \end{matrix} \begin{matrix} \text{mehr} \\ \frac{1}{r^2} \\ \frac{1}{r^2} \\ 0 \end{matrix}$

$\vec{H} = \frac{k}{\omega \mu} (-\vec{J}_0 E_0 + \vec{H}_0 E_0) = (-j\vec{J}_0 + \vec{H}_0) \frac{C}{2r} \frac{e^{jkr}}{r} \sin\theta$

$\vec{S} = -\frac{1}{2} \vec{E} \times \vec{H}^* = \vec{J}_0 \frac{|C|^2}{2r} \frac{\sin^2\theta}{r^2}$

(4) Volumenki resonator  $T_{11110}$   $j_1(3.83) = 0$   $a = 1\text{cm}$

$\vec{E} = \vec{J}_1 E_0 J_1(kr) \cos\theta$

$H = ?$   $f = ?$  + preveri TE!

$ka = 3.83 \rightarrow f = \frac{3.83 \cdot C_0}{2\pi a} = \underline{\underline{18.36 \text{Hz}}}$

$\vec{H} = \frac{j}{\omega \mu} \text{rot} \vec{E} = \frac{j}{\omega \mu} \frac{1}{r^2} \begin{vmatrix} \vec{r}_z & \vec{r}_\theta & \vec{r}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \end{vmatrix} \begin{matrix} \text{mehr} \\ \frac{1}{r^2} \\ \frac{1}{r^2} \\ 0 \end{matrix} \begin{matrix} \text{mehr} \\ \frac{1}{r^2} \\ \frac{1}{r^2} \\ 0 \end{matrix} \begin{matrix} \text{mehr} \\ \frac{1}{r^2} \\ \frac{1}{r^2} \\ 0 \end{matrix}$

$\text{div}(\epsilon_r \vec{E}) = 0$

$\vec{g} = \text{rot} \vec{H} - j\omega \vec{E} = \frac{j}{\omega \mu} \frac{1}{r^2} \begin{vmatrix} \vec{r}_z & \vec{r}_\theta & \vec{r}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \end{vmatrix} \begin{matrix} \text{mehr} \\ \frac{1}{r^2} \\ \frac{1}{r^2} \\ 0 \end{matrix} \begin{matrix} \text{mehr} \\ \frac{1}{r^2} \\ \frac{1}{r^2} \\ 0 \end{matrix} \begin{matrix} \text{mehr} \\ \frac{1}{r^2} \\ \frac{1}{r^2} \\ 0 \end{matrix}$

$= \frac{E_0}{4\pi} \int \left[ \left( -\frac{3}{8} \left( \left( \frac{1}{2} j_1(kr) \right)^2 + \left( \frac{1}{2} j_1(kr) \right)^2 \right) \cos^2\theta + \frac{1}{2} j_1(kr) \cos\theta \right) - j \cos\theta \vec{J}_{1,1,0}(kr) \right] \cos\theta$

$$\begin{aligned}
 &= \frac{j\omega_0}{2} \left( -\frac{\partial}{\partial \zeta} \left[ \frac{1}{\zeta - \zeta_1} \right] (\zeta_1) \cos \varphi + \frac{1}{\zeta_1} \left[ \frac{1}{\zeta - \zeta_1} \right] (\zeta_1) \cos \varphi \right) - j\omega_0 E(\zeta_1) \left[ \frac{1}{\zeta - \zeta_1} \right] (\zeta_1) \cos \varphi = 0 \\
 &= -\frac{j\omega_0}{2} \underbrace{\left[ \frac{1}{\zeta - \zeta_1} \left( \frac{\partial}{\partial \zeta} \left( \frac{1}{\zeta - \zeta_1} \right) (\zeta_1) \right) - \frac{1}{\zeta_1^2} (\zeta_1) + \alpha_0^2 \epsilon \delta_0^2 \left( \frac{1}{\zeta_1} \right) \right]}_{\text{Delen door } \frac{1}{\zeta - \zeta_1} (\zeta_1)} \cos \varphi = 0
 \end{aligned}$$

The diagram illustrates a waveguide system. A rectangular box labeled "P-SMALL Helle LASER" contains a wavelength indicator  $\lambda = 632.8 \text{ nm}$ . An arrow points from this box to a horizontal waveguide. The waveguide has a length of  $2r = 1 \text{ mm}$  and a width of  $2a = 0.2 \text{ mm}$ . The center of the waveguide is at a distance  $a$  from the laser source. The waveguide is characterized by a dielectric constant  $\epsilon_0$  and a magnetic permeability  $\mu_0$ . The wave number  $k$  is defined as  $k = \frac{2\pi}{\lambda}$ . The wave vector  $\vec{k}$  is shown pointing along the waveguide axis, and its magnitude is given as  $k = \sqrt{\frac{1}{\epsilon_0} + \frac{1}{\mu_0}} \cdot k$ . The characteristic impedance  $Z_0$  is given as  $Z_0 = \sqrt{\mu_0 / \epsilon_0} \Omega$ .

$$\begin{aligned}
 \vec{S} &= \vec{I}_2 S = \vec{I}_2 \frac{P}{\pi r^2} = \vec{I}_2 \cdot 37 \text{ kW/m}^2 \\
 S &= \frac{|E|^2}{2 Z_0} \rightarrow \vec{E} = \vec{I}_2 [22.5]^{-1} e^{j\omega t + \varphi} = \vec{I}_2 \cdot 1.55 \text{ V/m } e^{j\omega t + \varphi} \\
 \vec{H} &= \vec{I}_2 \frac{\vec{E}}{Z_0} = \vec{I}_2 \cdot 4.11 \text{ A/m } e^{j\omega t + \varphi} \\
 \vec{k} &= \vec{I}_2 k = \frac{1}{\vec{I}_2} \frac{2\pi}{\lambda} = \frac{1}{\vec{I}_2} 9.93 \cdot 10^6 \text{ m}^{-1} \\
 l &= \lambda/2 = 1 \text{ m} \\
 k &= \frac{2\pi}{\lambda} \\
 P &= \frac{1 \text{ A} \cdot 1 \text{ m}}{8\pi \cdot 0.5 \cdot 10^{-3} \text{ m}} = \underline{\underline{0.259 \text{ W}}} \\
 P_{\text{ridge}} &=? \\
 (\text{top plate} - ?)
 \end{aligned}$$

**Rešitev 2:**  $\text{[okvija je ELEKTROMAGNETIKE} \ 24.01.2003$

Rešitev ELEKTROMAGNETIKA 07.03.2003

$\vec{H}_0 = H_0 \hat{z}$   
 $\vec{K} = ?$   
 $\vec{K} = ? \cdot \frac{\vec{H}}{\sqrt{1 - \sin^2\alpha}}$

$\vec{H} = \vec{H}_0 + \frac{C}{r \sin\theta} \hat{e}_\phi$   
 $\vec{K} = \vec{H}_0 \times \vec{H}$

$S = r \sin\theta$  k.s.  $(r, 0, \theta)$   
 $\vec{H} = \vec{H}_0 + \frac{C}{r \sin\theta} \hat{e}_\phi$

choice:  $\vec{H}_0 = \vec{H}_0 ; \theta = \alpha$   
 $\vec{K} = \vec{H}_0 \times \vec{H}_0 + \frac{C}{r \sin\alpha} = \vec{H}_0 \frac{C}{r \sin\alpha}$

avminax y:  $\vec{r}_n = -\vec{r}_\theta$ ;  $\theta = \frac{\pi}{2}$

$$\vec{F} = -\vec{r}_\theta \times \vec{r}_\phi \frac{c}{r \sin \frac{\pi}{2}} = -\vec{r}_r \frac{c}{r}$$

esist.  $\vec{r}_\theta = \text{rot } \vec{H} = \underline{\underline{0}}$   
aber:

$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|^3} d\vec{r}'$$

$$\text{where } \vec{r}' = r' \sin\theta \hat{\theta} + r' \cos\theta \hat{\phi}$$

$$d\vec{r}' = r'^2 \sin\theta dr' d\theta d\phi$$

$$r' > a$$

$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_0^a \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|^3} d\vec{r}'$$

$$= \frac{1}{4\pi\epsilon_0} \int_0^a \frac{1}{(r^2 + r'^2 - 2r'r \cos(\theta - \phi) + r'^2)^{3/2}} \left( r'^2 \sin\theta \hat{\theta} - r' \sin\theta \hat{\phi} \right) dr'$$

$$= \frac{1}{4\pi\epsilon_0} \int_0^a \frac{1}{(r^2 + r'^2 - 2r'r \cos(\theta - \phi) + r'^2)^{3/2}} \left( r'^2 \sin\theta \cos(\theta - \phi) \hat{x} + r'^2 \sin\theta \sin(\theta - \phi) \hat{y} - r' \sin\theta \cos\theta \hat{z} \right) dr'$$

$$\approx \frac{1}{r^2} \left( 1 + \frac{r'}{r} (\sin\theta \cos\theta \cos(\theta - \phi) + \cos\theta \cos\theta) \right)$$

$$V(\vec{r}) \approx \frac{1}{4\pi\epsilon_0} \frac{1}{r} \left( 1 + \frac{r'}{r} (\sin\theta \sin\theta \cos(\theta - \phi) + \cos\theta \cos\theta) \right)^{-1/2} \sin\theta \cos\theta \hat{x}$$

$$= \frac{A}{4\pi\epsilon_0 r} \left( \cos\theta \left( \frac{a^2}{3} + \frac{a^2}{4r} (\sin\theta \cos\theta \cos(\theta - \phi) + \cos\theta \cos\theta) \right) \right)^{-1/2} \sin\theta \cos\theta \hat{x}$$

$$= \frac{A \cos^4 \theta}{16\pi\epsilon_0 r^2} \left( \frac{a^2}{3} + \frac{a^2}{4r} \cos\theta \cos\theta \right)^{-1/2} \sin\theta \cos\theta \hat{x}$$

$$= \frac{A \cos^4 \theta}{16\pi\epsilon_0 r^2} \left( \frac{a^2}{3} + \frac{a^2}{4r} \right)^{-1/2} \left( \frac{a}{2} + \frac{a \cos\theta}{4r} \right) \sin\theta \cos\theta \hat{x}$$

$$= \frac{A \cos^4 \theta}{16\pi\epsilon_0 r^2} \frac{\cos\theta}{\sqrt{\left( \frac{a^2}{3} + \frac{a^2}{4r} \right)}} \sin\theta \cos\theta \hat{x}$$

$$\boxed{5} \quad \begin{aligned} \epsilon_r &= 80; \quad \delta = 55/\text{m} \\ f &= 10\text{kHz}; \quad \alpha = 60\text{dB} \end{aligned} \quad h = ?$$

$$\frac{w \cdot \varepsilon_0 \cdot \varepsilon_r}{\lambda} = \frac{2 \pi \cdot 10^9 / s \cdot A \cdot 80}{5.57 \cdot 10^{-12} \cdot 4 \pi \cdot 9 \cdot 10^9 \cdot 1 m} = 2.3 \cdot 10^{-6} \ll 1$$

$$\alpha = 20 \log_{10} \left( \frac{E(0)}{E(h)} \right) ; \quad \frac{E(h)}{E(0)} = e^{-\frac{h}{\lambda}} ; \quad \alpha = 20 \frac{\ln \left( \frac{E(0)}{E(h)} \right)}{\lambda} = \frac{20 h}{\lambda}$$

Diagram for Problem 3: A bridge circuit with four resistors \$R\_1, R\_2, R\_3, R\_4\$ and two dependent voltage sources \$E\_q = k\_q V\_{pq}\$ and \$E\_g = k\_g V\_{pg}\$. The circuit is powered by a current source \$I\_0\$ and has output terminals \$o\$ and \$w\$. The dependent sources are controlled by voltages \$V\_{pq}\$ and \$V\_{pg}\$ across nodes \$q\$ and \$g\$ respectively.

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} \left( \vec{A}_x A_{k_y} \cos(k_x y) + \vec{A}_y A_{k_y} \sin(k_x y) \right) \times \left( \vec{A}_{k_y} \frac{\cos(k_x x)}{2\pi k_y} \right)$$

$$\vec{S} = \frac{i|A|^2 k_0}{2\pi k_y} \left( -\vec{A}_x \frac{k_x}{k_y} \sin(k_x x) \sin^2 k_y y + \vec{A}_y \cos^2 k_y y \cos(k_x x) \right)$$

# Rešitev 1. kolokvija iz ELEKTROMAGNETIKE 28.11.2003

(1)  $\operatorname{div} \vec{F} = ?$  v elipsoidnih koordinatah ( $\eta, \psi, \phi$ )

$$\left[ \begin{array}{l} x = \alpha \sin \psi \cos \phi, y = \alpha \sin \psi \sin \phi, z = \alpha \cos \psi \end{array} \right]$$

$$h_\eta = \sqrt{\alpha^2 \sin^2 \psi \cos^2 \phi + \alpha^2 \sin^2 \psi \sin^2 \phi + \alpha^2 \cos^2 \psi} = \alpha \sqrt{\sin^2 \psi + \cos^2 \psi} = \alpha$$

$$h_\psi = \sqrt{\alpha^2 \sin^2 \psi \cos^2 \phi + \alpha^2 \sin^2 \psi \sin^2 \phi + \alpha^2 \cos^2 \psi} = \alpha \sqrt{\sin^2 \psi + \cos^2 \psi} = \alpha$$

$$h_\phi = \sqrt{\alpha^2 \sin^2 \psi \sin^2 \phi + \alpha^2 \sin^2 \psi \cos^2 \phi + \alpha^2 \cos^2 \psi} = \alpha \sqrt{\sin^2 \psi + \cos^2 \psi} = \alpha$$

$$\operatorname{div} \vec{F} = \frac{1}{h_\eta h_\psi h_\phi} \left[ \frac{\partial}{\partial \eta} \left( h_\psi h_\phi F_\eta \right) + \frac{\partial}{\partial \psi} \left( h_\eta h_\phi F_\psi \right) + \frac{\partial}{\partial \phi} \left( h_\eta h_\psi F_\phi \right) \right] =$$

$$= \frac{1}{\alpha (\sin \psi \cos \phi) \sin \psi \sin \phi} \left[ \frac{\partial}{\partial \eta} \left( \sin \psi \cos \phi \sin \psi \sin \phi F_\eta \right) + \right.$$

$$+ \frac{\partial}{\partial \psi} \left( \sin \psi \cos \phi \sin \psi \sin \phi F_\psi \right) +$$

$$+ \frac{1}{\alpha \sin \psi \cos \phi} \frac{\partial F_\phi}{\partial \phi}$$

(3) Prozen prostor  $\omega \neq 0$

$$\vec{H} = \vec{J}_\phi \left( C \frac{e^{i\omega t}}{r \sin \theta} \right)$$

$$\vec{S} = ? \quad \vec{J}_{\text{zvor}} = ?$$

$$\vec{E} = \frac{1}{j\omega r} (\operatorname{rot} \vec{H} - \vec{J}) = \frac{1}{j\omega r} \left[ \begin{array}{c|cc} 1 & \frac{1}{r} & 0 \\ \frac{1}{r} & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] =$$

$$= \frac{1}{j\omega r} \left[ \vec{J}_\phi \left( C \frac{e^{i\omega t}}{r \sin \theta} \right) - \vec{J} \right] = \vec{J}_\phi \left( \frac{C}{r \sin \theta} e^{i\omega t} \right) - \frac{\vec{J}}{j\omega r}$$

$$\vec{H} = \frac{j}{\omega r} \operatorname{rot} \vec{E} = \frac{j}{\omega r} \left[ \begin{array}{c|cc} 1 & \frac{1}{r} & 0 \\ \frac{1}{r} & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] = -\frac{1}{\omega r} \operatorname{rot} \vec{J} = \vec{H} - \frac{1}{\omega r} \operatorname{rot} \vec{J}$$

$$\mathcal{G} = \operatorname{div} (\epsilon_0 \vec{E}) = \frac{\epsilon_0}{r^2} \frac{\partial}{\partial r} \left[ r^2 \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} \vec{E} \right) \right] = 0$$

Singularnost na osi  $z$ :  $I = \oint d\vec{s} \cdot \vec{d}s = \int_0^\pi \vec{H} \cdot \vec{r} r \sin \theta d\phi = C e^{i\omega t}$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} \int_0^\pi \frac{1}{r} \frac{1}{\theta} \frac{1}{r \sin \theta} \times \vec{J}_\phi C^* e^{i\omega t} \frac{r \sin \theta}{r \sin \theta} =$$

$$= \vec{J}_r \frac{k}{2 \omega \epsilon_0} |C|^2 \frac{1}{r^2 \sin^2 \theta} = \vec{J}_r \frac{|C|^2}{2 r^2 \sin^2 \theta}$$

(4)  $\omega = 0$

$$V = V_0$$

$$4V_1 = V_0 + V_2$$

$$4V_2 = V_1 + V_3$$

$$4V_3 = V_2 + V_4$$

$$4V_4 = V_3 + V_5$$

$$\vdots$$

$$4V_N = V_{N-1} + V_{N+1}$$

$$\vdots$$

$$V_0 = C \alpha^0 \rightarrow C = V_0$$

$$4C \alpha^N = C \alpha^{N-1} + C \alpha^{N+1}$$

$$0 = \alpha^2 - 4\alpha + 1$$

$$\alpha = \frac{4 \pm \sqrt{16-4}}{2} = 2 \pm \sqrt{3}$$

Potencial uporedi z izberemo  $\alpha < 1$

$$V_N = V_0 (2 - \sqrt{3})^N$$

(5)  $\omega = 0$

$$V = V_0$$

$$\sum_{n=0}^{\infty} C_n \sin^n \varphi = \sum_n C_n \sin^n \varphi \sin n \varphi \int_0^{2\pi} \sin^m \varphi \sin^n \varphi d\varphi = +V_0 \left[ \sum_n C_n \sin^n \varphi \int_0^{2\pi} \sin^m \varphi d\varphi + \sum_n C_n \sin^n \varphi \int_0^{2\pi} \sin^m \varphi \sin^n \varphi d\varphi \right]$$

$$C_m \alpha^m T = \frac{V_0}{m} \left[ \cos 0 - \cos m \frac{\pi}{2} - \cos \frac{\pi}{2} + \cos m \pi - \cos m \frac{3\pi}{2} - \cos m \frac{5\pi}{2} \right]$$

$$C_m = \frac{2V_0}{m \alpha^m} \left[ (-\cos \frac{\pi}{2} + \cos m \pi) - (\cos \frac{3\pi}{2} + \cos m \frac{5\pi}{2}) \right]$$

$$V(\varphi, r, z) = ?$$

$$V = V_0 + A \frac{\sin 4\varphi}{4^4} \rightarrow A = 0$$

$$\Delta V = -\frac{\alpha^2}{\epsilon_0} \sin 4\varphi$$

$$\mathcal{G} = ?$$

obdelavimo singularnost?

$$\mathcal{G} = 0$$

$$V(\varphi, r, z) = \sum_{k=0}^{\infty} \frac{8V_0}{(4k+2)\pi} \left( \frac{\alpha}{4^k} \right)^{1/2} \sin(4k+2)\varphi$$

(2)  $\omega = 0$

$$V(\varphi, r, z) = V_0 \sin 4\varphi$$

$$\epsilon_0 / \mu_0$$

$$\vec{E} = -\vec{J}_\phi \frac{1}{r} \frac{\partial V}{\partial \varphi} - \vec{J}_\phi \frac{1}{r} \frac{\partial V}{\partial z} =$$

$$= -\vec{J}_\phi 0 - \vec{J}_\phi \frac{4V_0}{r} \cos 4\varphi - \vec{J}_\phi 0 = -\vec{J}_\phi \frac{4V_0}{r} \cos 4\varphi$$

$$\mathcal{G} = \operatorname{div} (\epsilon_0 \vec{E}) = \frac{\epsilon_0}{r} \left[ \frac{\partial}{\partial \varphi} \left( -\frac{4V_0}{r} \cos 4\varphi \right) \right] =$$

$$= \frac{16V_0 \epsilon_0}{r^2} \sin 4\varphi$$

$$\Delta V = -\frac{\alpha^2}{\epsilon_0} \sin 4\varphi$$

$$\mathcal{G} = 0$$

obdelavimo singularnost?

$$\mathcal{G} = 0$$

$$V(\varphi, r, z) = ?$$

(1) 3D závorka

$$\vec{H}(r, \theta, \phi) = ?$$

(3)  $\mu_0, \epsilon_0, \vec{J} = 0, \vec{S} = 0$

**PLÁN VZ. V PŘAZNEH PROSTORU**

$$f = 1 \text{ GHz}$$

$$|\vec{E}| = 100 \frac{\text{Veff}}{\text{m}}$$

$$\vec{E} = (\vec{k}_x + \vec{k}_y) f(x, y, z)$$

$$\vec{H} = (\vec{k}_x - \vec{k}_y) \frac{f(x, y, z)}{2\pi}$$

$$\vec{k} = ? ; \vec{S} = ?$$

(4) stene  $y \rightarrow \infty$

**VOTLINSKI REZONANCI**

$$\vec{E} = \vec{k}_z \frac{10\text{V}}{\text{m}} \sin \frac{\pi}{a} x \sin b y$$

$$\alpha = 2c; b = 3c; f = 16 \text{ GHz}$$

$$a = ?; b = ?; c = ?; W = ?$$

$\vec{k} = \vec{k}_x \cdot k$

$$k = \frac{W}{C_0} = \frac{2\pi \cdot 10^9 \cdot \text{rad/s}}{3 \cdot 10^8 \text{ m/s}} = \frac{20.9 \text{ rad/m}}{}$$

$$\vec{k}_x = \vec{k}_z = \frac{\vec{E} \times \vec{H}^*}{|\vec{E} \times \vec{H}^*|} = \frac{(\vec{k}_x + \vec{k}_y) \times (\vec{k}_x - \vec{k}_y)}{|(\vec{k}_x + \vec{k}_y) \times (\vec{k}_x - \vec{k}_y)|} = \frac{-\vec{k}_z \cdot 2}{2} = -\vec{k}_z$$

$$\vec{k} = -\vec{k}_z \cdot 20.9 \text{ rad/m}$$

$$\vec{S} = \vec{E}_{\text{eff}} \times \vec{H}_{\text{eff}}^* = -\vec{k}_z \cdot 2 \cdot \frac{|\vec{E}|^2}{2\pi} = -\vec{k}_z \cdot 5.3 \frac{\text{W}}{\text{m}^2}$$

zaměření vzhledem  
polje dipola!

dipol  $\vec{k}_z$

$$A = a^2$$

$$A = \frac{\mu_0 I A}{4\pi r^2} \sin \theta = \vec{k}_z \frac{\mu_0 I a^2}{4\pi r^2} \sin \theta$$

$$\vec{A} = \frac{1}{\mu_0} \text{rot} \vec{A} = \frac{I a^2}{4\pi r^2} \left( \vec{k}_z 2 \cos \theta + \vec{k}_\theta \sin \theta \right)$$

$$\vec{H} = \frac{1}{\mu_0} \text{rot} \vec{A} = 4 \frac{I a^2}{\mu_0 \pi r^2} \left( \vec{k}_z 2 \cos \theta + \vec{k}_\theta \sin \theta \right)$$

**TANCOELASTICKÝ UPRO**

(2) **NOC PŘAZNEH TOKA**

$$\vec{k}_0 = -\vec{k}_y \frac{I_0}{W}; \vec{E}_0 = R \vec{k}_0 = -\vec{k}_y \frac{I_0}{W}; |E_0| = \frac{I_0 \pi}{W}$$

$$\Delta V = 0 \rightarrow V = (E_0 y + C_0 y^2) \sin \varphi = E_0 \left( y + \frac{I_0^2}{3} \right) \sin \varphi$$

$$y = r_0 \rightarrow K_g = 0, E_\varphi = 0 \rightarrow C = E_0 r_0^2$$

$$\vec{E} = -\text{grad} V = -\vec{k}_y \left( E_0 - \frac{C}{3} \right) \sin \varphi - \vec{k}_y \left( E_0 + \frac{C}{3} \right) \cos \varphi$$

$$U_y = V(r_0, \frac{\pi}{2}) - V(r_0, \frac{3\pi}{2}) = 2E_0 r_0 - (-2E_0 r_0) = 4E_0 r_0 = 4 \frac{I_0 \pi}{W} r_0$$

(5) **NOC PŘAZNEH COKA**

$$\vec{k} = \vec{k}_0 ( \sin \theta )$$

$$P = \int \frac{2}{\omega_0 \partial \varphi} dA = \frac{1}{2} |\vec{k}|^2 \frac{1}{\partial \varphi} r_0^2 \sin \theta d\theta d\varphi =$$

$$= \pi \frac{1}{\partial \varphi} r_0^2 \int_0^{2\pi} \int_0^\pi |C|^2 \sin^2 \theta \sin \theta d\theta d\varphi = \frac{\pi r_0^2 |C|^2}{\partial \varphi} \int_0^\pi (1 - \cos \theta) \sin \theta d\theta =$$

$$= \frac{\pi r_0^2 |C|^2}{\partial \varphi} \int_0^\pi (1 - u^2) du = \frac{4\pi r_0^2 |C|^2}{3 \partial \varphi} = \frac{4\pi r_0^2 |C|^2}{3 \partial \varphi} \frac{\sqrt{\omega_0}}{2\pi}$$

①  $\phi = 14^\circ \quad \text{Zemlja} = \text{kroga}$   
 $\alpha = 46^\circ \quad R_2 = 6378 \text{ km}$

$\lambda = ? \quad (\text{najbrža})$

$\vec{A} = \vec{I}_k R_2$

$\vec{B} = \vec{I}_k R_2 \cos \alpha \hat{\phi} + \vec{I}_k R_2 \sin \alpha \hat{r}$

$\vec{A} \cdot \vec{B} = R_2^2 \cos \alpha \cos \phi$

$\lambda = R_2 \arccos \left( \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} \right) = R_2 \arccos (\cos \alpha \cos \phi)$

$\lambda = 6378 \text{ km } \arccos (\cos 46^\circ \cos 14^\circ)$

$\lambda = 5301 \text{ km}$

②  $\omega = 0 \quad V(x_1, z_2) = ?$

Problem:  $\nabla V = 0$

$\alpha = \arctg \frac{z_2 - z_1}{x_2 - x_1} = \arctg \frac{x}{\sqrt{x^2 + (y_2 - y_1)^2}}$

$\alpha = \pi \rightarrow C_1 = -\frac{2V_0}{\pi}$

$V = -\frac{2V_0}{\pi} \arccos \frac{x}{\sqrt{x^2 + (y_2 - y_1)^2}} + V_0$

$V = +V_0 \quad V = -V_0$

Spodnji dve elektrodi nimate vpliva!

③  $U_{AB} = ?$

$\vec{E}_0 = -\vec{I}_2 \frac{I}{\pi a^2 \gamma} \vec{e}_r \quad E_0 = \frac{I}{\pi a^2 \gamma}$

$\Delta V = 0 \rightarrow V = (Ar + Br^{-2}) \cos \theta$

$V(r_\infty) = V_0 \rightarrow A = E_0$

$\vec{j} = -\vec{S} \text{ grad} V = \vec{I}_r \gamma \left( -A + \frac{2B}{r^2} \right) \cos \theta +$

$\vec{j} \cdot \vec{B} = 0 \rightarrow -A + \frac{2B}{r^2} \sin \theta = 0$

$B = \frac{A r^3}{2}$

$V = E_0 \left( r + \frac{r_0^3}{2r^2} \right) \cos \theta$

$U = V(r=r_0, \theta=0) - V(r=r_0, \theta=\pi) = 2E_0 \left( r_0 + \frac{r_0^3}{2r_0} \right) =$

$= 2 \frac{I}{\pi a^2 \gamma} \frac{3}{2} r_0 = \frac{3 I r_0}{\pi a^2 \gamma} = \frac{3 \cdot 1 \text{ A} \cdot 10^{-3}}{\pi \cdot 5 \cdot 10^{-2} \text{ m} \cdot 10 \text{ S/m}} =$

$= 0.106 \text{ mV}$

④  $\vec{E} = ? \quad \vec{H} = ?$

$\omega \neq 0 \quad r \gg a$

$\mu_0 / \epsilon_0$

$\beta = 0 \rightarrow V = 0$

$\vec{I}_\alpha$

$d\vec{I}_\alpha$

$I$

$\vec{A} = \vec{I}_\phi \frac{\mu_0}{4\pi} IA \frac{\vec{e}_r}{r} \left( jk + \frac{1}{r} \right) \sin \theta$

$\vec{A} = \vec{I}_\phi \frac{\mu_0}{4\pi} I \frac{a^2}{2} \frac{\vec{e}_r}{r} \left( jk + \frac{1}{r} \right) \sin \theta$

$\vec{A} = \vec{I}_\phi \frac{\mu_0}{4\pi} I \frac{a^2}{2} \frac{\vec{e}_r}{r} \left( jk + \frac{1}{r} \right) \sin \theta$

$\vec{H} = \frac{1}{\mu_0} \text{ rot} \vec{A} = \frac{1}{4\pi} \frac{a^2}{2} \frac{1}{r^2} \sin \theta$

$\vec{H} = \frac{1}{\mu_0} \text{ rot} \vec{A} = \frac{1}{4\pi} \frac{a^2}{2} \frac{1}{r^2} \sin \theta$

$\vec{E} = -j\omega \vec{A} = -\vec{I}_\phi \frac{j\omega \mu_0}{4\pi} I \frac{a^2}{2} \frac{\vec{e}_r}{r} \left( jk + \frac{1}{r} \right) \sin \theta$

$\vec{E} = -j\omega \vec{A} = -\vec{I}_\phi \frac{j\omega \mu_0}{4\pi} I \frac{a^2}{2} \frac{\vec{e}_r}{r} \left( jk + \frac{1}{r} \right) \sin \theta$

$\vec{H} = \frac{i}{\omega \mu} \text{ rot} \vec{E} = -\vec{I}_\phi \frac{k}{\omega \mu} E_0 e^{-jkY}$

$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \vec{I}_\phi \frac{k}{\omega \mu} |E_0|^2 = \vec{I}_\phi \frac{|E_0|^2}{2|H_0|}$

$P = \oint \vec{S} \cdot d\vec{A} = 0 \text{ W}$

(pleskev  $y=0$  in plodov  $y=a$   
 se učita, ostale imajo  
 skalarni produkt 0)

⑤  $\vec{E} = ? \quad \vec{P} = ?$

$\epsilon_r = 2 \quad \epsilon_r = \epsilon_0 \epsilon_s$

$E = \epsilon_r \epsilon_0 \quad \mu = \mu_0$

$P = ?$

$\alpha = \pi \text{ rad}$

$\omega = 1 \text{ rad/s}$

$E_0 = 10 \text{ V/m}$

$f = 1 \text{ GHz}$

$k = \omega \sqrt{\mu \epsilon}$

$P = ?$

⑥  $V(x_1, z_2) = ?$

Problem:  $\nabla V = 0$

$\alpha = \arctg \frac{z_2 - z_1}{x_2 - x_1} = \arctg \frac{x}{\sqrt{x^2 + (y_2 - y_1)^2}}$

$\alpha = 0 \rightarrow C_2 = +V_0$

$\alpha = \pi \rightarrow C_1 = -\frac{2V_0}{\pi}$

$V = -\frac{2V_0}{\pi} \arccos \frac{x}{\sqrt{x^2 + (y_2 - y_1)^2}} + V_0$

⑦  $\omega = 0 \quad V(x_1, z_2) = ?$

$\epsilon_0$

$V = +V_0$

$V = -V_0$

$V = +V_0$

$V = -V_0$

$V = +V_0$

$E_0$

$E_0 = 10 \text{ V/m}$

$f = 1 \text{ GHz}$

$k = \omega \sqrt{\mu \epsilon}$

## ELEKTROMAGNETIKA 9/7/2004

① Zemljopisni koordinatni sistem ( $\lambda, \varphi, h$ )

$$\lambda = 20^\circ \text{E}, \varphi = 20^\circ \text{N}, h = \text{vedem. višina}$$

$$g_2 = 63780 \text{ m}$$

$$h_1, h_2, h_n = ?$$

$$r = h + R_2$$

$$x = r \cos \lambda \cos \varphi = \cos \lambda \cos (\lambda + R_2)$$

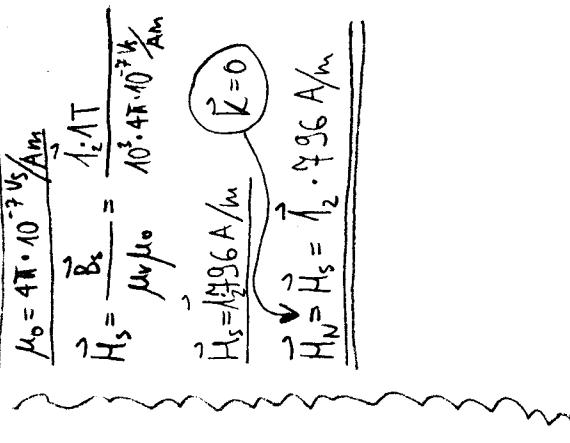
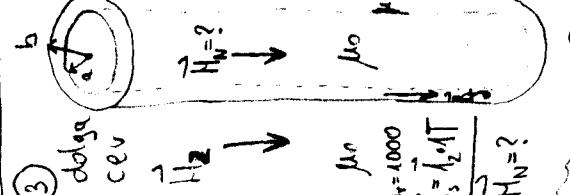
$$y = r \sin \lambda \cos \varphi = \sin \lambda \cos (\lambda + R_2)$$

$$z = r \sin \varphi = \sin \varphi (\lambda + R_2)$$

$$h_1 = \sqrt{\left(\frac{\partial x}{\partial \lambda}\right)^2 + \left(\frac{\partial y}{\partial \lambda}\right)^2} + \left(\frac{\partial z}{\partial \lambda}\right)^2 = \cos \varphi (\lambda + R_2)$$

$$h_2 = \sqrt{\left(\frac{\partial x}{\partial \varphi}\right)^2 + \left(\frac{\partial y}{\partial \varphi}\right)^2 + \left(\frac{\partial z}{\partial \varphi}\right)^2} = (\lambda + R_2)$$

$$h_n = \sqrt{\left(\frac{\partial x}{\partial \alpha}\right)^2 + \left(\frac{\partial y}{\partial \alpha}\right)^2 + \left(\frac{\partial z}{\partial \alpha}\right)^2} = 1$$



$$\boxed{3} \quad \begin{aligned} \mu_0 &= 4\pi \cdot 10^{-7} \text{ Vs/A.m} \\ \vec{H}_s &= \frac{\vec{B}_s}{\mu_0 \mu_0} = \frac{1}{2} \cdot 1 \text{ T} \\ \mu_0 \mu_0 &= 10^3 \cdot 4\pi \cdot 10^{-7} \text{ Am} \end{aligned}$$

$$\boxed{4} \quad \begin{aligned} \vec{E} &= (\vec{k}_y + \vec{j}_z) E_0 e^{j\omega t} \\ E_0 &= 100 \text{ V/m}; k = \omega/c_0 \\ \vec{E}(t) &=? \quad \vec{H}(t) = ? \quad \vec{S}(t) = ? \end{aligned}$$

$$\begin{aligned} \vec{E}(t) &= \operatorname{Re} [\vec{k}_y (\vec{k}_y + \vec{j}_z) E_0 e^{j(\omega t - kx)}] = \vec{k}_y E_0 \cos(\omega t - kx) - \vec{j}_z E_0 \sin(\omega t - kx) = \\ &= \vec{k}_y 100 \text{ V/m} \cos[\omega(t - \frac{x}{c_0})] - \vec{j}_z 100 \text{ V/m} \sin[\omega(t - \frac{x}{c_0})] = \\ \vec{H} &= \vec{j}_z \mu_0 \operatorname{rot} \vec{E} = \frac{\partial \vec{E}}{\partial x} = \begin{vmatrix} \vec{i}_x & \vec{i}_y & \vec{i}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \vec{E}_0 e^{j\omega t} & 0 & \vec{E}_0 e^{j\omega t} \end{vmatrix} = (\vec{j}_y + \vec{i}_z) \frac{E_0}{2\omega} e^{-j\omega t} \end{aligned}$$

$$\begin{aligned} \vec{H}(t) &= \operatorname{Re} [(\vec{j}_y + \vec{i}_z) \frac{E_0}{2\omega} e^{-j\omega t}] = \vec{k}_x 0.265 \text{ A/m} \sin[\omega(t - \frac{x}{c_0})] + \vec{k}_y 0.265 \text{ A/m} \cos[\omega(t - \frac{x}{c_0})] = \\ &= \vec{k}_x 26.5 \text{ A/m}^2 \cos^2[\omega(t - \frac{x}{c_0})] + \vec{k}_y 26.5 \text{ A/m}^2 \sin^2[\omega(t - \frac{x}{c_0})] = \\ &= \vec{k}_x 26.5 \text{ W/m}^2 \end{aligned}$$

$$\begin{aligned} \vec{S}(t) &= \vec{E}(t) \times \vec{H}(t) = \left( \vec{k}_y 100 \text{ V/m} \cos[\omega(t - \frac{x}{c_0})] - \vec{k}_z 100 \text{ V/m} \sin[\omega(t - \frac{x}{c_0})] \right) \times \\ &\times \left( \vec{k}_x 0.265 \text{ A/m} \sin[\omega(t - \frac{x}{c_0})] + \vec{k}_y 0.265 \text{ A/m} \cos[\omega(t - \frac{x}{c_0})] \right) = \\ &= \vec{k}_x 26.5 \text{ W/m}^2 \cos^2[\omega(t - \frac{x}{c_0})] + \vec{k}_y 26.5 \text{ W/m}^2 \sin^2[\omega(t - \frac{x}{c_0})] = \\ &= \vec{k}_x 26.5 \text{ W/m}^2 \end{aligned}$$

$$\boxed{5} \quad \begin{aligned} f_{1, \min} &= \frac{C_0}{2} \sqrt{\left(\frac{1}{a}\right)^2 + \left(\frac{1}{b}\right)^2} + \left(\frac{n}{c}\right)^2 \\ f_{1, 10} &= \frac{C_0}{2} \sqrt{\left(\frac{1}{a}\right)^2 + \left(\frac{1}{b}\right)^2} = 9014.2878 \text{ MHz} \end{aligned}$$

$$\alpha < b \rightarrow f_{\text{min}} < f_{1, 10}$$

$$f_{\text{min}} = f_{1, 10} + \Delta f = 9014.848 \text{ MHz}$$

$$f_{\text{min}} = \frac{C_0}{2} \sqrt{\left(\frac{1}{b}\right)^2 + \left(\frac{1}{c}\right)^2} \rightarrow C = \frac{1}{\sqrt{\left(\frac{2 f_{\text{min}}}{C_0}\right)^2 - \left(\frac{1}{b}\right)^2}}$$

$$C = ?$$

$$C_0 = 2 \cdot 10^9 \text{ W/s}$$

$$a = 2 \text{ cm}; b = 3 \text{ cm}; c < a < b$$

$$\Delta f = 1 \text{ MHz} \quad \text{zadani vrijednost rezonancije}$$

$$V_1, \dots, V_5 = ?$$

$$4V_1 = V_0 + V_2$$

$$4V_2 = V_1 + V_3$$

$$4V_3 = V_2$$

$$15V_2 = 4V_1 + V_2 \rightarrow V_2 = \frac{1}{14}V_0, V_3 = -\frac{1}{14}V_0$$

$$15V_2 = 4V_1 \rightarrow V_0 + V_2 \rightarrow V_0 = \frac{1}{14}V_0$$



A. k. 2009 in EM 2.12.2009

(2) element planar dA = r^2 sin θ dθ dφ

$$\text{① } \vec{F} = \vec{i}_x y + \vec{i}_y x$$

$$\text{primitiva in der A} = \int_0^{2\pi} \int_0^h r^2 \sin \theta d\theta d\phi = 2\pi r^2 (\cos \phi - \cos 0)$$

ko ∵ δ = 0 in β = π ∵ A = hπr^2 abtreten

$$\phi = \frac{A}{h\pi r^2} Q = \frac{Q}{2} (\cos \phi - \cos 0)$$

ko ∵ δ = 0 in β = π/2 immer parallel zu z  
entw. ie preis  $\phi_{\text{preis}} = \frac{Q}{2}$

$$\text{div } \vec{F} = \frac{\partial \vec{F}}{\partial x} + \frac{\partial \vec{F}}{\partial y} = 0 \Rightarrow \text{NI DIVORON}$$

$$\text{rot } \vec{F} = \begin{vmatrix} \frac{\partial}{\partial x} & \vec{i}_x \\ \frac{\partial}{\partial y} & \vec{i}_y \\ 0 & 0 \end{vmatrix} = \vec{i}_x \left( \frac{\partial}{\partial y} 0 + \vec{i}_y \cdot 0 + \vec{i}_z (1-1) \right) = 0$$

diverticev

$$\text{③ } \vec{H} = \frac{1}{\mu_0 q} \text{ rot } \vec{A} = \frac{1}{\mu_0 q} \frac{1}{r} \begin{vmatrix} \vec{i}_x & \vec{i}_y & \vec{i}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & A_0 \cos \phi \end{vmatrix} =$$

$$= \frac{1}{\mu_0 q} \left( -\vec{i}_y A_0 \frac{\sin \phi}{r} + \vec{i}_y \vec{i}_z A_0 \frac{\cos \phi}{r} \right) =$$

$$= \frac{A_0}{\mu_0 q} \left( -\vec{i}_y \frac{\sin \phi}{r} + \vec{i}_y \frac{\cos \phi}{r} \right) =$$

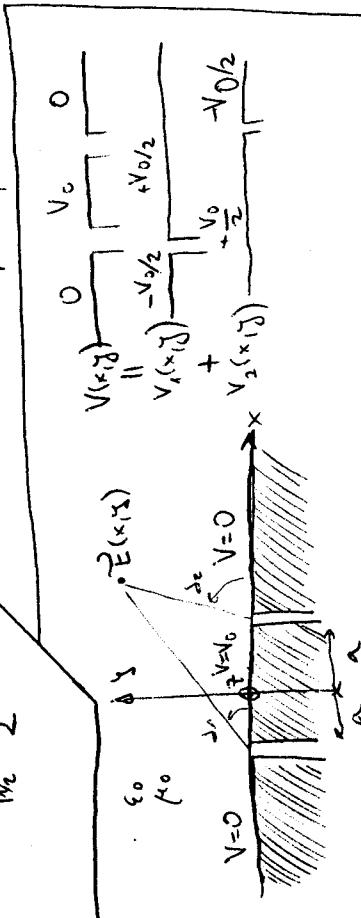
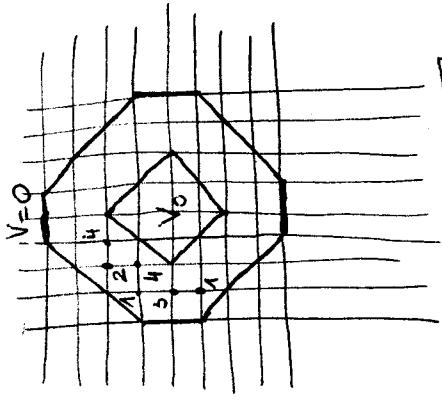
$$\vec{j} = \text{rot } \vec{H} = \frac{1}{q} \begin{vmatrix} \vec{i}_x & \vec{i}_y & \vec{i}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -A_0 \sin \phi & A_0 \cos \phi & 0 \end{vmatrix} = 0$$

zu zeigen konstant!

$$\vec{E} = -\vec{g} \text{ grad } V = \dots$$

$$I = \int \vec{H} d\sigma = \frac{A_0}{\mu_0} \int_0^{2\pi} \int_0^h \left( -\vec{i}_y \frac{\sin \phi}{r} + \vec{i}_y \frac{\cos \phi}{r} \right) \vec{i}_z q r d\phi = 0$$

$$\int_0^{2\pi} \int_0^h \cos \phi d\phi = \frac{A_0}{\mu_0} \left[ \sin \phi \right]_0^{2\pi} = 0$$



$$\begin{aligned} V_1(x,y) &= +\frac{V_0}{2} - \frac{V_0}{\pi} \arctan \frac{y}{x+\alpha} \\ V_2(x,y) &= -\frac{V_0}{2} + \frac{V_0}{\pi} \arctan \frac{y}{x-\alpha} = -\frac{V_0}{2} + \frac{V_0}{\pi} \arctan \frac{y}{x-\alpha} \\ V(x,y) &= \frac{V_0}{\pi} \left[ \arctan \frac{y}{x-\alpha} - \arctan \frac{y}{x+\alpha} \right] \end{aligned}$$

zu zeigen konstant!

$$\begin{aligned} V_1 &= 7V_2 - 2V_0 = \frac{23}{30} V_0 = V_1 \\ V_2 &= \frac{29}{30} V_0 \end{aligned}$$

$$\begin{aligned} V_3 &= hV_1 - 2V_2 = \frac{23}{30} hV_0 \\ V_4 &= \frac{58}{30} V_0 \end{aligned}$$

2. voldsmj EH 17.1.2005

$$\textcircled{1} \quad H_0 = \alpha^2$$

$$H_0 = \frac{\pi}{\alpha^2}$$

$$H = \frac{1}{\sqrt{1 - r^2}} \frac{\mu_0 I A}{r^2} \sin \theta$$

$$H = \frac{I A}{\sqrt{1 - r^2}} (\vec{A}_r 2 \cos \theta + \vec{A}_\theta \sin \theta) \text{ gauge choice}$$

$$H = \frac{I A}{\sqrt{1 - r^2}} \left( \vec{A}_r \left( \frac{A_3}{Y_3} + \frac{2}{r^3} \right) \cos \theta + \vec{A}_\theta \left( -\frac{1}{Y_3} + \frac{1}{r^3} \right) \sin \theta \right)$$

$$\textcircled{2} \quad M_{00} = \frac{\pi \mu_0 \alpha^2}{2 d^3}$$

$$M_{00} = \frac{1}{I} \oint_S \vec{H} \cdot d\vec{l} = \frac{\mu_0 \alpha^2}{d} \lambda_\phi \text{ add } \oint$$

$$M_{00} = \frac{\mu_0 \alpha^2}{2 d^3}$$

$$H_{00} = H_{00}$$

$$\frac{\pi \mu_0 \alpha^2}{2 d^3} = \frac{\mu_0 \alpha^2 \alpha^2}{2 d^3}$$

$\pi \alpha^2 = x^2$  position must satisfy into

$$x = \alpha \sqrt{\pi}$$

$$\textcircled{5} \quad f = \frac{1}{2 \sqrt{\mu_0 \epsilon_0 c_0}} \sqrt{\left(\frac{m}{c}\right)^2 + \left(\frac{n}{b}\right)^2 + \left(\frac{p}{c}\right)^2}$$

$m, n, p$  no cela stvar  
naj duva da vrijednost od 0!  
 $m=1, n=0, p=1$

$$f^2 = \frac{1}{4 \mu_0 \epsilon_0 c_0} \left[ \left( \frac{1}{\alpha} \right)^2 + \left( \frac{1}{c} \right)^2 \right] \Rightarrow \epsilon_r = \frac{c_0^2}{4 \mu_0^2} \left( \frac{1}{\alpha^2} + \frac{1}{c^2} \right) = 3,25$$

$$\textcircled{1} \quad \vec{H} = \frac{i}{\omega c_0} \text{ rot } \vec{E} = \frac{i}{\omega c_0} \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{A}_r & \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{\partial}{\partial \phi} \\ 0 & 0 & 0 & \frac{\partial}{\partial \theta} \end{vmatrix} = -i \frac{1}{\theta} \frac{E_0}{Z_0} \frac{e^{-i\omega t}}{\sin \theta}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} \begin{vmatrix} \vec{A}_r & \vec{A}_\theta & \vec{A}_\phi \\ 0 & 0 & -\frac{E_0}{Z_0} \frac{e^{i\omega t}}{\sin \theta} \\ 0 & -\frac{E_0}{Z_0} \frac{e^{i\omega t}}{\sin \theta} & 0 \end{vmatrix} = \frac{1}{2} \lambda_r \frac{E_0 E_0^*}{Z_0} \frac{1}{r^2 \sin^2 \theta}$$

$$\vec{S} = \text{rot } H - i \omega \epsilon \vec{E}^2 = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{A}_r & \vec{A}_\theta & \vec{A}_\phi \\ 0 & 0 & 0 \\ 0 & 0 & \frac{\partial}{\partial \phi} \end{vmatrix} - i \omega \epsilon \lambda_\phi E_0 \frac{e^{-i\omega t}}{\sin \theta} = 0$$

$$\textcircled{1} \quad I \vec{H} d\vec{l} = \int_0^{2\pi} \lambda_\phi H \vec{l} \cdot d\vec{l} = H_0 2\pi$$

$$\text{rot } H = \frac{1}{r^2 \sin^2 \theta} \vec{E} = \frac{1}{i \omega \epsilon} \text{ rot } H = \frac{1}{i \omega \epsilon} \frac{1}{\sin \theta} \begin{vmatrix} \vec{A}_r & \vec{A}_\theta & \vec{A}_\phi \\ 0 & 0 & 0 \\ 0 & 0 & \frac{\partial}{\partial \theta} \end{vmatrix} = \frac{1}{i \omega \epsilon} \frac{1}{\sin \theta} \begin{vmatrix} \vec{A}_r & \vec{A}_\theta & \vec{A}_\phi \\ 0 & 0 & 0 \\ 0 & 0 & \frac{\partial}{\partial \theta} \end{vmatrix} = 0$$

$$\vec{E} = \lambda_\phi \frac{I}{2 \pi \eta c_0} \vec{z}_0 e^{-i\omega t}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} \begin{vmatrix} \vec{A}_r & \vec{A}_\theta & \vec{A}_\phi \\ \vec{A}_{\theta 0} e^{-i\omega t} & 0 & \frac{I}{2 \pi \eta} \frac{e^{-i\omega t}}{c} \\ 0 & 0 & 0 \end{vmatrix} = \frac{1}{2} \frac{I}{c} \frac{I^*}{Z_0} \frac{e^{-i\omega t}}{c}$$

$$\textcircled{1} \quad V = \frac{C}{r_2} \sin\theta \sin\phi = \frac{C}{r_2} \sin\theta \sin\phi$$

$$V = \frac{C}{r_2} \sin\theta \sin\phi \Rightarrow \Delta V = 0 \quad \underline{\underline{Q = 0}}$$

$$\int \vec{E} \cdot d\vec{l} = 0 \Rightarrow Qd = 0$$

$$\vec{E} = -\frac{Q}{2\pi r^2 \epsilon_0} \hat{r}$$

$$Qd = 4\pi \epsilon_0 C$$

$$\textcircled{2} \quad V = \frac{C}{r_2} \sin\theta \sin\phi \quad \underline{\underline{Q = 0}}$$

$$V = \frac{C}{r_2} \sin\theta \sin\phi \quad \underline{\underline{Q = 0}}$$

$$\textcircled{3} \quad \omega = 0 \quad \left\{ \begin{array}{l} \vec{H} = \vec{H}_0 \sin\theta \sin\phi \\ \vec{H}_0 = \vec{k}_x + \vec{k}_y + \vec{k}_z \\ \vec{k}_x = \vec{k}_y = \vec{k}_z = ? \end{array} \right.$$

$$\textcircled{4} \quad \vec{k}_x = (\vec{k}_x + \vec{k}_y + \vec{k}_z)rd/m$$

$$\vec{k}_y = (\vec{k}_x - \vec{k}_y + \vec{k}_z)rd/m$$

$$\vec{E}(0,0,0) = 0 \quad ; \quad \mu_0, \epsilon_0$$

$$f = ? \quad ; \quad \vec{T}_E = ?$$

$$k = \frac{\omega_0}{c_0} = \frac{2\pi f}{c_0} \rightarrow f = \frac{\omega_0}{2\pi} |\vec{k}_x| = 82.4 \text{ MHz}$$

$$\vec{E}_1 = \vec{E}_{10} e^{-j\vec{k}_x \cdot \vec{r}}$$

$$\vec{E} = \vec{E}_1 + \vec{E}_2 = \vec{E}_{10} e^{-j\vec{k}_x \cdot \vec{r}} + \vec{E}_{20} e^{j\vec{k}_x \cdot \vec{r}}$$

$$\vec{E}_2 = \vec{E}_{20} e^{-j\vec{k}_x \cdot \vec{r}}$$

$$\vec{E}(0,0,0) = \vec{E}_{10} e^{j\vec{k}_x \cdot \vec{r}} \rightarrow \vec{E}_{10} = -\vec{E}_{10}$$

$$\vec{E}_{10} \cdot \vec{k}_x = 0 \quad \left\{ \begin{array}{l} \vec{k}_x = \frac{\vec{k}_x \times \vec{k}_2}{|\vec{k}_x \times \vec{k}_2|} = \frac{2(\vec{k}_x - \vec{k}_2)}{|2(\vec{k}_x - \vec{k}_2)|} + \vec{k}_x - \vec{k}_2 \\ \vec{E}_{10} \cdot \vec{k}_2 = 0 \end{array} \right.$$

$$k = \frac{\omega_0}{c_0} = \frac{2\pi f}{c_0} \rightarrow f = \frac{\omega_0}{2\pi} |\vec{k}_x| = \frac{82.4 \text{ MHz}}{\sqrt{2}}$$

$$\textcircled{5} \quad \text{Plättchenantenne}$$

$$Z_u = \frac{2\pi}{2\pi \sqrt{\epsilon_r}} \ln \frac{a}{d} = 46.6 \Omega$$

$$\text{Plättchen: } K_{eff} = \frac{I_{eff}}{2\pi b} = \frac{1}{2\pi b} \sqrt{\frac{a}{d}} = \frac{4.47 \text{ A/m}}{d}$$

$$R_p = \frac{1}{J_0 a d} = \frac{0.84 \text{ m}\Omega}{J_0 a d} = 21.27 \text{ mm}$$

$$E_n = K_{eff} \cdot R_p = \frac{6.52 \text{ mV/m}}{E_2}$$

$$E_n = \frac{d}{\delta} \rightarrow d = \delta \ln \frac{E_n}{E_2} = 18.7 \text{ mm}$$

$$Z_0 = 120 \Omega$$

$$\mu_0 = 4\pi \cdot 10^{-7} \text{ Vs/A}$$

$$\textcircled{2} \quad V = V_0 \sin \frac{\pi}{a} x \sin \frac{\pi}{a} y \sin \frac{\pi}{a} z \quad \underline{\underline{C = \frac{V_0}{\sin \frac{\pi}{a} \frac{\pi}{a} h}}}$$

$$\vec{E} = -j\omega \vec{d} \vec{V} \quad ; \quad Q_{d0} = \frac{\int \vec{E} \cdot \vec{d} dA}{A_{d0}} \quad ; \quad Q = \frac{\int \vec{E} \cdot (-\vec{d}) dA}{A_{d0}}$$

$$E_2 = -C \sin \frac{\pi}{a} x \sin \frac{\pi}{a} y \sin \frac{\pi}{a} z \sin \frac{\pi}{a} z$$

$$\left| \frac{Q}{Q_{d0}} \right| = 100 = \text{ch} \frac{\pi z}{a} h \rightarrow h = \frac{a}{\pi z} \text{ arch} 100$$

$$\text{ch} u = \frac{1}{2} (\text{e}^u + \text{e}^{-u})$$

$$(C')^2 - 2 \text{ch} u \text{ e}^u + 1 = 0$$

$$C' = \frac{2 \text{ch} u + \sqrt{4 \text{ch} u - 4}}{2}$$

$$C' = 1.193 \text{ m}$$

$$h = 1.193 \text{ m}$$

$$Q_{d0} = V_0 \cdot A \quad ; \quad$$

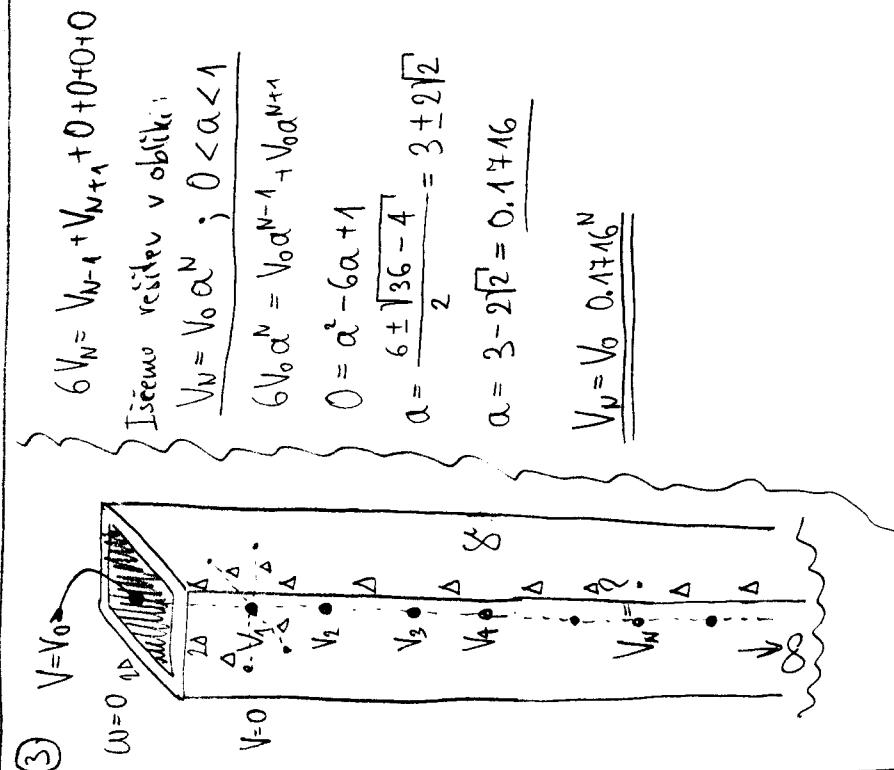
$$\text{① } \vec{A}(r\theta, \phi) = (\vec{A}_r \cos \theta - \vec{A}_\phi \sin \theta) C(\ln(r \sin \theta))$$

$$\vec{A} = \vec{A}_z C \ln \varrho$$

$$\vec{H} = \frac{1}{\mu_0} \operatorname{rot} \vec{A} = \frac{1}{\varrho} \begin{vmatrix} \vec{A}_r & \vec{A}_\theta & \vec{A}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ 0 & 0 & \operatorname{cosec} \theta \end{vmatrix} = -\frac{\vec{A}_\theta}{\varrho \operatorname{cosec} \theta}$$

$$\vec{B} = \operatorname{rot} \vec{H} = \frac{1}{\varrho} \begin{vmatrix} \vec{A}_r & \vec{A}_\theta & \vec{A}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ 0 & 0 & 0 \end{vmatrix} = 0$$

$\int \vec{B} \cdot d\vec{s} = \int_0^R -\vec{A}_\theta \frac{C}{\varrho} \cdot \vec{d}\varrho \varphi = -2\pi C f_m$



4)  $\epsilon_r = 80, f = 100 \text{ MHz}, \mu = \mu_0, \sigma = \frac{1}{4\pi \cdot 9 \cdot 10^9} \frac{As}{Vm}$

$I = ?$  ( $|I_{\text{total}}| = |I_{\text{produženja}}$ )

 $\vec{H} + \vec{J} = (\delta + j\omega \epsilon_r) \vec{E}$ 
 $J = \omega \epsilon_0 \epsilon_r$ 
 $\delta = \frac{1}{2\pi f \epsilon_0 \epsilon_r} = \frac{4\pi \cdot 9 \cdot 10^9 V_m}{2\pi \cdot 10^8 \cdot 1 As \cdot 80} = 2.25 \Omega \text{m}$

$$6V_N = V_{N-1} + V_{N+1} + 0 + 0 + \dots + V_0$$

Tiskovo rezistor v obliku:

 $V_N = V_0 \alpha^N ; 0 < \alpha < 1$ 
 $6V_0 \alpha^N = V_0 \alpha^{N-1} + V_0 \alpha^{N+1}$ 
 $0 = \alpha^2 - 6\alpha + 1$ 
 $\alpha = \frac{6 \pm \sqrt{36 - 4}}{2} = 3 \pm 2\sqrt{2}$ 
 $\alpha = 3 - 2\sqrt{2} = 0.1416$ 
 $V_N = V_0 \quad 0.1416^N$

5)  $\omega \neq 0$

 $\omega_1 = \frac{\pi C_0}{L_1} \sqrt{\left(\frac{1}{a}\right)^2 + \left(\frac{1}{c}\right)^2} = 1.01\omega_1$ 
 $\left(\frac{1}{a}\right)^2 + \left(\frac{1}{c}\right)^2 = 1.01^2 \left[\left(\frac{1}{b}\right)^2 + \left(\frac{1}{c}\right)^2\right]$ 
 $b = \frac{1}{\sqrt{\frac{\left(\frac{1}{b}\right)^2 + \left(\frac{1}{c}\right)^2}{1.01^2} - \left(\frac{1}{c}\right)^2}} = 3.041 \text{ cm}$

2)  $V(r, \phi) = \sum_{k=1}^{\infty} C_k r^{\frac{2}{3}k} \sin \frac{2}{3}k\phi ; k=1, 2, 3, 4, \dots ; V(a, \phi) = V_0$

 $\int_0^R \vec{A} \cdot d\vec{s} = \sum_{k=1}^{\infty} C_k \frac{2}{3}k \sin \frac{2}{3}k\phi \int_0^R r^{\frac{2}{3}k-1} dr = \sum_{k=1}^{\infty} C_k \frac{2}{3}k \sin \frac{2}{3}k\phi \int_0^R r^{\frac{2}{3}k-2} dr$ 
 $\frac{1}{2} C_1 \left( \frac{2}{3} \right)^2 \frac{3\pi}{2} = V_0 \frac{2}{3} \left( -\cos \frac{2}{3}k\phi \right)_0 = \frac{3V_0}{2} \left( 1 - \cos \frac{2}{3}\pi \right)$ 
 $C_1 = \frac{2V_0}{\pi} - \frac{2}{3} \left( 1 - \cos \frac{2}{3}\pi \right)$ 

sodi  $\varphi$ :  $\int_0^R \vec{A} \cdot d\vec{s} = 0$

 $V(r, \phi) = \sum_{k=1}^{\infty} \frac{2V_0(1 - \cos \frac{2}{3}\pi)}{\pi k} \left( \frac{r}{a} \right)^{\frac{2}{3}k} \sin \frac{2}{3}k\phi$

$$V(r, \phi) = \sum_{m=1}^{\infty} C_m r^m \sin m\phi$$
 $m = \frac{2}{3}, 1, \frac{4}{3}, 1, \frac{6}{3}, 1, \frac{8}{3}, \dots$



## 2. izloženje EM 17. 4. 2006 (resistor)

$$\textcircled{2} \quad \vec{A} = \vec{A}_0 \frac{\sin \theta}{y} \frac{\sin \theta}{r^2}$$

$$\textcircled{1} \quad V_3 = V_7 = V_{gj} = 0$$

$$\begin{cases} 4V_1 = 0 + V_0 + V_2 + 0 \\ 4V_2 = V_1 + V_0 + 0 + V_6 \\ 4V_6 = 0 + V_2 + 0 + 0 \end{cases} \quad \begin{cases} V_1 = V_0 + V_2 \\ V_2 = V_1 + \frac{V_0}{4} + V_6 \\ V_6 = 4V_2 \end{cases}$$

$$V_6 = \frac{1}{4} V_0 + \frac{1}{4} V_2 \quad V_2 = \frac{5}{4} V_0 \quad V_6 = \frac{5}{4} V_0$$

$$V_6 = \frac{5}{4} V_0 \quad V_0 = -V_8$$

$$\vec{E}_1 = \vec{A}_x E_v \vec{e}^{j\omega t} + \vec{A}_y E_v \vec{e}^{j\omega t}$$

$$\vec{H}_1 = \vec{A}_y \frac{E_v}{Z_0} \vec{e}^{-j\omega t} - \vec{A}_x \frac{E_v}{Z_0} \vec{e}^{j\omega t}$$

$$\textcircled{5} \quad \gamma = \frac{1 - \sqrt{\epsilon_r}}{1 + \sqrt{\epsilon_r}} = -\frac{1}{3}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} \begin{vmatrix} \vec{A}_x & \vec{A}_y & \vec{A}_z \\ E_x & 0 & 0 \\ H_y & 0 & 0 \end{vmatrix}$$

$$= \vec{A}_z \frac{1}{2} \left( E_x \cdot H_y^* \right)$$

$$= \vec{A}_z \frac{1}{2} \left( \frac{E_v E_v^*}{Z_0} \vec{e}^{-j\omega t} - \frac{E_v E_v^*}{Z_0} \vec{e}^{j\omega t} \right) \quad \text{1}$$

$$= \vec{A}_z \frac{1}{2} \frac{E_v E_v^*}{Z_0} \left( 1 + \Gamma 2 \sin(\omega t) - \Gamma^2 \right)$$

$$\textcircled{2} \quad \vec{A} = \vec{A}_0 \frac{\sin \theta}{y} \frac{\sin \theta}{r^2}$$

$$\theta = \frac{\pi}{2} \Rightarrow \sin \theta = 1$$

$$H = \frac{1}{I_a} \oint \vec{A} \cdot d\vec{s} = \frac{I}{I_a} \int_A \vec{A}_0 \frac{\mu_0 I_a \alpha^2}{h} \frac{1}{6} \vec{b} d\phi$$

$$H = \frac{\mu_0 \alpha^2}{2b}$$

$$\textcircled{4} \quad \text{pravouhlý rezonátor} \quad \delta_d = \frac{c_0}{2} \sqrt{\frac{2}{\alpha^2}}$$

validní rezonátor

$$\delta_d = \frac{2.405}{2\pi} c_0$$

$$\delta_d = \frac{2.405 c_0}{2\pi r}$$

$$\delta_d = \frac{2.405 c_0}{2\pi r} = 5.4 \text{ cm}$$

$$V_2 = \frac{5}{4} V_0 = -V_4$$

$$V_1 = \frac{19}{56} V_0 = -V_5$$

$$V_1 = \frac{19}{56} V_0 = -V_5$$

$$\textcircled{5} \quad \gamma = \frac{1 - \sqrt{\epsilon_r}}{1 + \sqrt{\epsilon_r}} = -\frac{1}{3}$$

$$\vec{H}_1 = \vec{A}_y \frac{E_v}{Z_0} \vec{e}^{-j\omega t} - \vec{A}_x \frac{E_v}{Z_0} \vec{e}^{j\omega t}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} \begin{vmatrix} \vec{A}_x & \vec{A}_y & \vec{A}_z \\ E_x & 0 & 0 \\ H_y & 0 & 0 \end{vmatrix}$$

$$= \vec{A}_z \frac{1}{2} \left( E_x \cdot H_y^* \right)$$

$$= \vec{A}_z \frac{1}{2} \left( \frac{E_v E_v^*}{Z_0} \vec{e}^{-j\omega t} - \frac{E_v E_v^*}{Z_0} \vec{e}^{j\omega t} \right) \quad \text{1}$$

$$\vec{V}_{\text{resonátor}} = \vec{A}_x \frac{\delta_d \pi}{\omega \mu a} \cos\left(\frac{\pi}{\alpha} x\right) e^{-j\omega t}$$

$$\vec{V}_{\text{resonátor}} = -\vec{V}_{\text{resonátor}}$$

$$\vec{V}_{\text{resonátor}} = \vec{A}_x \frac{\delta_d \pi}{\omega \mu a} \cos\left(\frac{\pi}{\alpha} x\right) e^{-j\omega t}$$

$$\vec{V}_{\text{resonátor}} = -\vec{V}_{\text{resonátor}}$$

$$\vec{V}_{\text{resonátor}} = -\vec{V}_{\text{resonátor}}$$

$$\begin{aligned} \textcircled{1} \quad V(\mu, \eta, z) &= C \sin \mu \cos \eta \\ x = f \sin \mu \cos \eta & \\ y = f \sin \mu \sin \eta & \\ z = z & \\ g = ? \quad \zeta = ? \quad Q = ? & \end{aligned}$$

$$\begin{aligned} h_2 &= 1 & \mu_0, \epsilon_0 \\ \omega &= 0 & \\ h = hu &= f \sqrt{s^2 u^2 + v^2} \\ \omega &= hu \cdot \frac{\partial^2 V}{\partial u^2} + \frac{\partial^2 V}{\partial v^2} = 0 \end{aligned}$$

$$g = \epsilon_0 \Delta V = \epsilon_0 \left[ \frac{\partial^2 V}{\partial u^2} + \frac{\partial^2 V}{\partial v^2} + \frac{\partial^2 V}{\partial z^2} \right] = 0$$

$$\vec{D} = -\epsilon_0 \operatorname{grad} V = -\int \frac{\epsilon_0}{u} du \cos \eta + \int \frac{\epsilon_0}{v} dv \sin \eta$$

$$\begin{aligned} \text{Na tvaru } \vec{D} &= \vec{D}_n + \vec{D}_s \quad (-f < x < f, \eta = 0) \rightarrow u = 0 \\ \zeta(-f < x < f, \eta = 0) &= 2 \vec{D}_n \cdot \vec{D}_s = \frac{\sin \eta}{\sin \eta + \sqrt{1 - (\eta/f)^2}} \\ &= -2 \frac{\epsilon_0}{hu} \cdot \frac{x}{f} = -2 \frac{x \epsilon_0}{f \sin \eta} = \frac{-2 \epsilon_0 x}{\sqrt{f^2 - x^2}} \end{aligned}$$

$$\begin{cases} q = 0 \\ Q = 0 \end{cases} \quad \begin{cases} \text{ni drugih} \\ \text{singularnosti} \end{cases}$$

$$V_2 = \frac{\sum V_0 = 10V}{2} ; V_4 = 12V ; V_6 = \frac{V_0}{4} = \underline{\underline{2V}} ; V_8 = \underline{\underline{4V}}$$

$$V_3 = V_4 = \frac{V_0}{2} = \underline{\underline{V}}$$

$$4V_1 = V_0 + V_1 + V_2 + V_3 = 2V_6 + 2V_2$$

$$4V_2 = V_0 + V_1 + V_4 + V_5 = 2V_6 + V_1$$

$$4V_3 = V_3 + V_4 + V_6 + 0 = V_0 + V_6$$

$$4V_4 = V_5 + V_5 + 0 + 0 = 2V_5$$

$$4V_5 = V_0 + V_2$$

$$4V_6 = V_0 + V_6$$

$$2V_7 = 2V_0 + V_1$$

$$2V_8 = V_0 + V_8$$

$$4V_9 = V_0 + V_9$$

$$2V_{10} = V_0 + V_{10}$$

$$4V_{11} = V_0 + V_{11}$$

$$2V_{12} = V_0 + V_{12}$$

$$4V_{13} = V_0 + V_{13}$$

$$2V_{14} = V_0 + V_{14}$$

$$4V_{15} = V_0 + V_{15}$$

$$2V_{16} = V_0 + V_{16}$$

$$4V_{17} = V_0 + V_{17}$$

$$2V_{18} = V_0 + V_{18}$$

$$4V_{19} = V_0 + V_{19}$$

$$2V_{20} = V_0 + V_{20}$$

$$4V_{21} = V_0 + V_{21}$$

$$2V_{22} = V_0 + V_{22}$$

$$4V_{23} = V_0 + V_{23}$$

$$2V_{24} = V_0 + V_{24}$$

$$4V_{25} = V_0 + V_{25}$$

$$2V_{26} = V_0 + V_{26}$$

$$4V_{27} = V_0 + V_{27}$$

$$2V_{28} = V_0 + V_{28}$$

$$4V_{29} = V_0 + V_{29}$$

$$2V_{30} = V_0 + V_{30}$$

$$4V_{31} = V_0 + V_{31}$$

$$2V_{32} = V_0 + V_{32}$$

$$4V_{33} = V_0 + V_{33}$$

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$$2V_{40} = V_0 + V_{40}$$

$$4V_{41} = V_0 + V_{41}$$

$$2V_{42} = V_0 + V_{42}$$

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$$4V_{103} = V_0 + V_{103}$$

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$$4V_{105} = V_0 + V_{105}$$

$$2V_{106} = V_0 + V_{106}$$

$$4V_{107} = V_0 + V_{107}$$

$$2V_{108} = V_0 + V_{108}$$

$$4V_{109} = V_0 + V_{109}$$

$$2V_{110} = V_0 + V_{110}$$

$$4V_{111} = V_0 + V_{111}$$

$$2V_{112} = V_0 + V_{112}$$

$$4V_{113} = V_0 + V_{113}$$

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$$4V_{121} = V_0 + V_{121}$$

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$$2V_{124} = V_0 + V_{124}$$

$$4V_{125} = V_0 + V_{125}$$

$$2V_{126} = V_0 + V_{126}$$

$$4V_{127} = V_0 + V_{127}$$

$$2V_{128} = V_0 + V_{128}$$

$$4V_{129} = V_0 + V_{129}$$

$$2V_{130} = V_0 + V_{130}$$

$$4V_{131} = V_0 + V_{131}$$

$$2V_{132} = V_0 + V_{132}$$

$$4V_{133} = V_0 + V_{133}$$

$$2V_{134} = V_0 + V_{134}$$

$$4V_{135} = V_0 + V_{135}$$

$$2V_{136} = V_0 + V_{136}$$

$$4V_{137} = V_0 + V_{137}$$

$$2V_{138} = V_0 + V_{138}$$

$$4V_{139} = V_0 + V_{139}$$

$$2V_{140} = V_0 + V_{140}$$

$$4V_{141} = V_0 + V_{141}$$

$$2V_{142} = V_0 + V_{142}$$

$$4V_{143} = V_0 + V_{143}$$

$$2V_{144} = V_0 + V_{144}$$

$$4V_{145} = V_0 + V_{145}$$

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$$2V_{148} = V_0 + V_{148}$$

$$4V_{149} = V_0 + V_{149}$$

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$$4V_{151} = V_0 + V_{151}$$

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$$4V_{163} = V_0 + V_{163}$$

$$2V_{164} = V_0 + V_{164}$$

$$4V_{165} = V_0 + V_{165}$$

$$2V_{166} = V_0 + V_{166}$$

$$4V_{167} = V_0 + V_{167}$$

$$2V_{168} = V_0 + V_{168}$$

$$4V_{169} = V_0 + V_{169}$$

$$2V_{170} = V_0 + V_{170}$$

$$4V_{171} = V_0 + V_{171}$$

$$2V_{172} = V_0 + V_{172}$$

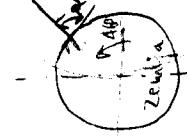
$$4V_{173} = V_0 + V_{173}$$

$$2V_{174} = V_0 + V_{174}$$

$$4V_{175} = V_0 + V_{175}$$

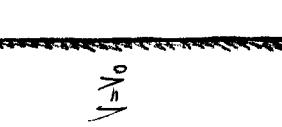
$$2V_{176} = V_0 + V_{176}$$

$$\vec{H} = C \left( \hat{i}_r \frac{2 \cos \theta}{r_3} + \hat{i}_\theta \frac{\sin \theta}{r_3} \right)$$



$$\begin{aligned} \alpha &= \arctan \frac{H_r}{H_\theta} = \\ &= \arctan \frac{2 \cos \theta}{\sin \theta} = \arctan \left( \frac{2}{t_0 \theta} \right) \\ &= 64.227^\circ = 1.12 \text{ rad} \end{aligned}$$

(3)



$$V(i,j) = ?$$

$\epsilon_0$

$z_{\text{welia}}$

$$\theta = \frac{\pi}{2} - 46^\circ = 44^\circ$$

$$\begin{aligned} V &= V_0 \frac{2}{\pi} \varphi \quad \varphi = \arctan \frac{1}{x} \quad x = j \Delta \\ &\qquad \qquad \qquad y = i \Delta \\ &\qquad \qquad \qquad \varphi = \arctan \frac{i}{j} \end{aligned}$$

$$V(i,j) = V_0 \frac{2}{\pi} \arctan \left( \frac{j}{i} \right)$$

(4)



$$b = ? \quad f = ?$$

$$f = \frac{C_0}{2} \sqrt{\left(\frac{m}{a}\right)^2 + \left(\frac{n}{b}\right)^2} = \frac{C_0}{2} \sqrt{\left(\frac{1}{a}\right)^2 + \left(\frac{3}{b}\right)^2} = \frac{C_0}{2} \sqrt{\left(\frac{1}{a}\right)^2 + \left(\frac{1}{b}\right)^2}$$

$$\frac{1}{a^2} + \frac{9}{b^2} = \frac{4}{a^2} + \frac{1}{b^2} \rightarrow \frac{8}{b^2} = \frac{3}{a^2}$$

$$b = \sqrt{\frac{8}{3}} a = 16.33 \text{ cm}$$

$$f = \frac{C_0}{2} \sqrt{\left(\frac{1}{a}\right)^2 + \left(\frac{3}{b}\right)^2} = 3.1386 \text{ Hz}$$

$$a = 10 \text{ cm}$$

$$\vec{E} = C \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y$$

$$f(m=1, n=3) = f(m=2, n=1)$$

(5)



$$V(i,j) = ?$$

$\epsilon_0$

$z_{\text{welia}}$

$$V = V_0 \frac{2}{\pi} \varphi \quad \varphi = \arctan \frac{1}{x} \quad x = j \Delta$$

$$y = i \Delta$$

$$\varphi = \arctan \frac{i}{j}$$

$$V(i,j) = V_0 \frac{2}{\pi} \arctan \left( \frac{j}{i} \right)$$

(6)

$$\vec{E} = C \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y$$

$$f(m=1, n=3) = f(m=2, n=1)$$

(7)

$$\vec{E} = C \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y$$

$$f(m=1, n=3) = f(m=2, n=1)$$

(8)

$$\vec{E} = C \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y$$

$$f(m=1, n=3) = f(m=2, n=1)$$

(9)

$$\vec{E} = C \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y$$

$$f(m=1, n=3) = f(m=2, n=1)$$

(10)

$$\vec{E} = C \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y$$

$$f(m=1, n=3) = f(m=2, n=1)$$

(11)

$$\vec{E} = C \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y$$

$$f(m=1, n=3) = f(m=2, n=1)$$

(12)

$$\vec{E} = C \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y$$

$$f(m=1, n=3) = f(m=2, n=1)$$

(13)

$$\vec{E} = C \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y$$

$$f(m=1, n=3) = f(m=2, n=1)$$

(14)

$$\vec{E} = C \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y$$

$$f(m=1, n=3) = f(m=2, n=1)$$

(15)

$$\vec{E} = C \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y$$

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(1) dani vektori  $\vec{A}, \vec{B}, \vec{C}$   
 $\vec{A} \times \vec{B} \neq 0 ; \vec{B} \times \vec{C} \neq 0 ; \vec{C} \times \vec{A} \neq 0$   
 poiskuti  $\vec{D} = ?$  da velja  $\vec{D} \cdot \vec{A} = \vec{D} \cdot \vec{B} = \vec{D} \cdot \vec{C} = 0$

$$\begin{cases} \vec{D} \cdot \vec{A} = 0 \\ \vec{D} \cdot \vec{B} = 0 \\ \vec{D} \cdot \vec{C} = 0 \end{cases} \rightarrow \vec{D} \parallel \vec{A} \times \vec{B}$$

$$\begin{cases} \vec{D} = 0 \text{ ali } \vec{A} \parallel \vec{C} \\ \vec{D} \parallel \vec{B} \times \vec{C} \end{cases}$$

$$\vec{C} \times \vec{A} \neq 0$$

ni mogoče za radi

$$\vec{D} = 0$$

(3)  $U=0$

$$\begin{aligned} V_1 &= V_5 \\ V_3 &= V_7 \\ 4V_1 &= V_2 + V_4 \quad \{120 \text{ cm}\} \\ 4V_2 &= 2V_0 + 2V_4 \\ 4V_4 &= 2V_1 + 2V_3 \\ 4V_3 &= V_4 + V_6 \quad \{120 \text{ cm}\} \\ 4V_6 &= 2V_3 \end{aligned}$$

$$\begin{aligned} 8V_3 &= 2V_4 + V_2 \rightarrow V_3 = 2V_4 \\ 14V_4 &= 4V_1 + 2V_4 \rightarrow 12V_4 = 4V_1 \\ 12V_4 &= V_0 + 2V_4 \rightarrow 10V_4 = V_0 \quad V_1 = \frac{2}{3}V_4 \\ V_4 &= \frac{1}{10}V_0 \quad V_1 = V_5 = \frac{6}{35}V_0 \\ V_3 &= \frac{2}{7}V_4 \quad V_6 = \frac{1}{2}V_2 \\ V_3 &= V_4 = \frac{1}{35}V_4 \quad V_6 = -\frac{1}{30}V_0 \end{aligned}$$

(4)  $\omega \neq 0 \quad z \quad \varepsilon_0 \quad T(0, \phi)$

$$\vec{K} = (\vec{A}_r \sin \phi + \vec{A}_\theta \cos \phi) \left( \cos \frac{\pi r}{2a} \right)$$

$$\vec{A}_r \sin \phi + \vec{A}_\theta \cos \phi = \vec{A}_r$$

$$r = \sqrt{x^2 + y^2}$$

$$\sigma \approx 95$$

$\vec{K} =?$

(1. ME)  $\operatorname{rot} \vec{H} = \vec{g} + j\omega \varepsilon_0 \vec{E}$  / div

$$\begin{aligned} 0 &= \operatorname{div} (\operatorname{rot} \vec{H}) = \operatorname{div} \vec{g} + j\omega \operatorname{div} (\varepsilon_0 \vec{E}) \\ 0 &= \operatorname{div} \vec{g} + j\omega \operatorname{div} (\varepsilon_0 \vec{E}) = 0 \end{aligned}$$

(2. ME)  $\operatorname{div} \vec{K} = \frac{\partial}{\partial r} \left( C \cos \frac{\pi r}{2a} \right)$

$$\begin{aligned} 0 &= \operatorname{div} \vec{K} = -C \sin \left( \frac{\pi r}{2a} \right) \frac{\pi}{2a} \frac{\partial r}{\partial r} = -\frac{C}{4} = \sin \phi \\ C &= -\frac{j\pi C}{2a \sin \left( \frac{\pi r}{2a} \right)} \end{aligned}$$

(3. ME)  $\operatorname{div} \vec{E} = 0$

$$\begin{aligned} 0 &= \operatorname{div} \vec{E} = \frac{\partial}{\partial r} \left( C \cos \frac{\pi r}{2a} \right) = 0 \\ 0 &= \frac{-1}{j\pi} \operatorname{div} \vec{g} \\ G &= \frac{j}{\pi} \operatorname{div} (\vec{K} \vec{g}) \\ G &= \frac{j}{\pi} \operatorname{div} \vec{K} \end{aligned}$$

(4. ME)  $\operatorname{rot} \vec{H} = \vec{g} + j\omega \varepsilon_0 \vec{E} = (8 + j\omega \varepsilon_0) \vec{E} = j\omega \varepsilon_0 \left( \frac{K}{\mu_0 + 1} \right) \vec{E}$

$$\Delta \vec{E} + k^2 \vec{E} = 0$$

$$k^2 = (\omega^2 \mu_0 \varepsilon_0)^2 = (\omega^2 \mu_0 \varepsilon_0) \left( \frac{8}{\mu_0 + 1} \right) \rightarrow k = (\omega \mu_0 \varepsilon_0)^{1/2} \sqrt{1 + \frac{8}{\mu_0 + 1}}$$

$$\frac{8}{\mu_0 + 1} \rightarrow \sqrt{1 - j \frac{8}{\mu_0 + 1}} \approx 1 - j \frac{8}{2\mu_0} \rightarrow k \approx \omega \sqrt{\mu_0} - j \frac{4}{2\mu_0} \frac{8}{\mu_0 + 1} =$$

$$s = l_0 - j \frac{8}{2\mu_0}$$

$$\vec{E} = \vec{E}(0) e^{-jkz} = \vec{E}_0 e^{-jkz} e^{-j\frac{s}{2\mu_0}}$$

$$|\vec{E}| = |\vec{E}(0)| e^{-\alpha z} \quad \alpha = \frac{20}{l_0 \mu_0} \quad \alpha = \frac{10}{l_0 \mu_0} \quad \alpha = \frac{10}{l_0 \mu_0}$$

$$g = \frac{\alpha l_0 \mu_0}{10 Z_0} = \frac{0.014 \text{ m}^{-1} \text{ N/A}}{10 \cdot 120 \pi \Omega} = \underline{8.55 \cdot 10^{-6} \text{ S/m} = 8.55 \mu \text{S/m}}$$

(5) molekula O<sub>2</sub>

$$f = 606 \text{ Hz}$$

$$\mu \approx 1 \rightarrow \mu = \mu_0$$

$$\varepsilon \approx \varepsilon_0$$

$$\alpha = 14 \text{ dB/km}$$

$$g = ?$$

$$\alpha = 14 \text{ dB/km} = 0.04 \text{ dB/m}$$

$$C = 83.33 \text{ pF}$$

(2)  $U=0$

$$dU = Q \frac{d\varphi}{2\pi l g \varepsilon}$$

$$U = \int_a^b dU = \frac{Q}{2\pi l} \int_a^b \frac{d\varphi}{\varepsilon_0 \frac{\varphi}{a}} = \frac{Qa}{2\pi l \varepsilon_0} \int_a^b \frac{d\varphi}{\varphi} = \frac{Qa}{2\pi l \varepsilon_0} \ln \frac{b}{a}$$

$$U = \frac{Qa}{2\pi l \varepsilon_0} \left( \frac{1}{a} - \frac{1}{b} \right) = \frac{Q(b-a)}{2\pi l \varepsilon_0 b}$$

$$C = \frac{Q}{U} = \frac{2\pi l \varepsilon_0 b}{b-a} = \frac{2\pi l \text{ As} \cdot 1 \text{ m} \cdot 0.03 \text{ m}}{4\pi l \cdot 9 \cdot 10^9 \text{ N} \cdot 0.02 \text{ m}} = \frac{1}{10^{10}} \text{ F}$$

$$\alpha = \frac{l_0 \mu_0}{b-a}$$

$$C = \frac{83.33 \text{ pF}}{b-a}$$

$$\alpha = \mu_0 \frac{\partial}{\partial x}$$

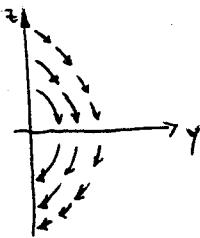
$$b = 3 \text{ cm} \quad l = 1 \text{ m} \quad C = ?$$

Rješitev 1. koločvija EM - 30/11/2006

$$\textcircled{1} \quad \vec{F}(r, \theta, \phi) = \vec{l}_\theta \frac{1}{r}$$

$$\operatorname{div} \vec{F} = \frac{1}{r^2 \sin \theta} \left( \frac{\partial}{\partial \theta} \left( \frac{1}{r} r \sin \theta \right) \right) = \frac{1}{r^2} \frac{\cos \theta}{\sin \theta} \quad \text{IZVORI SO!}$$

$$\phi = \frac{\pi}{2}$$



$$\operatorname{rot} \vec{F} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{i}_r & \vec{i}_\theta & \vec{i}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & \frac{1}{r} & 0 \end{vmatrix} = \vec{l}_\phi r \sin \theta \frac{\partial}{\partial r} (1) - \vec{l}_r \frac{\partial}{\partial \phi} (1) = 0$$

$$\oint \vec{F} d\vec{l} = \int_{r=a}^{2\pi} \vec{l}_\theta \frac{1}{r} \vec{l}_\phi r \sin \theta d\phi = 0 \quad \text{NI VRTINČEV!}$$

$$\text{ali} \quad \oint \vec{F} d\vec{l} = \int_0^{\pi} \vec{l}_\theta \frac{1}{r} \vec{l}_\theta r^2 \sin \theta d\theta + \int_{\pi}^{2\pi} \vec{l}_\theta \frac{1}{r} \vec{l}_\theta r^2 \sin \theta d\theta = r \int_0^{\pi} \sin \theta d\theta + r \int_{\pi}^{2\pi} \sin \theta d\theta = r [-\cos \theta]_0^{\pi} + r [-\cos \theta]_{\pi}^{2\pi} = 2r - 2r = 0$$

$$\textcircled{2} \quad (\vec{D}_1 - \vec{D}_2) \cdot \vec{l}_n = 0 \quad \vec{l}_n = \vec{l}_x$$

$$\begin{array}{c|c|c} \leftarrow & \rightarrow & G \\ \leftarrow & \leftarrow & \leftarrow \\ \leftarrow & \rightarrow & \rightarrow \\ E_1 & E_2, E_3 & \end{array} \quad \begin{array}{l} (\vec{E}_1 - \vec{E}_2) \cdot \vec{l}_x = \frac{G}{\epsilon_0} \\ E_{1x} - E_{2x} = \frac{G}{\epsilon_0} \\ E_{2x} - E_{3x} = \frac{G}{\epsilon_0} \end{array} \quad \left. \begin{array}{l} \text{sostjevamo } E_{1x} - E_{3x} = \frac{2G}{\epsilon_0} \\ \text{odštejemo } E_{1x} - 2E_{2x} + E_{3x} = 0 \end{array} \right\} \begin{array}{l} \text{ic simetrije } |E_{1x}| = |E_{3x}| \\ E_{1x} = -E_{3x} = -\frac{G}{\epsilon_0} \\ E_{2x} = 0 \end{array}$$

$$\vec{E}_1 = -\vec{l}_x \frac{G}{\epsilon_0}$$

$$\vec{E}_2 = 0$$

$$\vec{E}_3 = +\vec{l}_x \frac{G}{\epsilon_0}$$

$$\textcircled{3} \quad \vec{A}(r, \theta, \phi) = \vec{l}_\phi \frac{\sin \theta}{r}$$

$$\vec{H} = \frac{1}{\mu_0} \operatorname{rot} \vec{A} = \frac{1}{\mu_0} \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{i}_r & \vec{i}_\theta & \vec{i}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & 0 & r \sin \theta A_\phi \end{vmatrix} = \vec{l}_r \frac{2 \cos \theta}{\mu_0 r^2}$$

$$\vec{j} = \operatorname{rot} \vec{H} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{i}_r & \vec{i}_\theta & \vec{i}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ H_r & 0 & 0 \end{vmatrix} = \frac{1}{r^2 \sin \theta} \left( -\vec{l}_\phi r \sin \theta \frac{\partial}{\partial \theta} H_r \right) = \vec{l}_\phi \frac{2 \sin \theta}{\mu_0 r^3}$$

$$\textcircled{4} \quad V = -V_0 \sin^2 \left( \frac{\pi}{a} x \right) = -V_0 \left( \cos \left( \frac{2\pi}{a} x \right) - 1 \right) = +V_0 - V_0 \cos \left( \frac{2\pi}{a} x \right) = V_1 + V_2$$

$$V_2(x, y) = AC \cos \left( \frac{2\pi}{a} x \right) \operatorname{ch} \left( \frac{2\pi}{a} y \right) \Rightarrow AC = -\frac{V_0}{\operatorname{ch} \left( \frac{2\pi}{a} b \right)}$$

$$V_1(x, y) = \sum_{n=1}^{\infty} \frac{2V_0(1-\cos(n\pi))}{n\pi \operatorname{nh}(n\pi/b)} \sin \left( n \frac{\pi}{a} x \right) \operatorname{sh} \left( n \frac{\pi}{a} y \right)$$

$$\textcircled{5} \quad V_1 = V_2 = V_3 = V_4$$

$$\text{L} V_1 = V_5 + V_6$$

$$\text{L} V_5 = V_1$$

$$16V_5 = V_5 + V_6$$

$$\boxed{V_5 = \frac{V_0}{15}}$$

$$6V_1 = V_5 + V_2 + V_3 + V_4$$

$$6V_5 = V_1 + V_6 + V_7$$

$$6V_1 = V_5 + 2V_4 + V_6$$

$$6V_5 = V_1 + 2V_5$$

$$\boxed{V_1 = \frac{h}{15} V_0}$$

$$\textcircled{1} \quad \vec{E} = \vec{1}_x E_0 \sin(k_y y) e^{-ik_z z} \quad k_y^2 + k_z^2 = k_0^2 = \omega^2 \mu_0 \epsilon_0$$

$$\vec{H} = \frac{\partial}{\omega \mu_0} \operatorname{rot} \vec{E} = \frac{\partial}{\omega \mu_0} \left[ \vec{1}_y \frac{\partial}{\partial z} (E_x) - \vec{1}_z \frac{\partial}{\partial y} (E_x) \right] = \vec{1}_y \frac{E_0 k_z}{\omega \mu_0} \sin(k_y y) e^{-ik_z z} - \vec{1}_z \frac{\partial k_z}{\omega \mu_0} E_0 \cos(k_y y) e^{-ik_z z}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} \left[ \vec{1}_z E_x H_y^* - \vec{1}_y E_x H_z^* \right] = \vec{1}_y \frac{E_0 E_0^* k_y}{2 \omega \mu_0} \cos(k_y y) \sin(k_y y) + \vec{1}_z \frac{E_0 E_0^* k_z}{2 \omega \mu_0} \sin^2(k_y y)$$

$$\operatorname{rot} \vec{H} = \vec{1}_x \frac{\partial H_z}{\partial y} + \vec{1}_z \frac{\partial H_y}{\partial x} - \vec{1}_y \frac{\partial H_x}{\partial z} = \vec{1}_x \frac{ik_z^2 E_0}{\omega \mu_0} \sin(k_y y) e^{-ik_z z} + \vec{1}_z \frac{jk_z^2 E_0}{\omega \mu_0} \sin(k_y y) e^{-ik_z z}$$

$$\vec{J} = \operatorname{rot} \vec{H} - j \omega \epsilon_0 \vec{E} = \vec{1}_x \frac{\partial E_0 k_0}{\omega \mu_0} \sin(k_y y) e^{-ik_z z} - j \omega \epsilon_0 \vec{1}_x \sin(k_y y) \cdot \vec{e}^{ik_z z} = \vec{1}_x E_0 \sin(k_y y) e^{-ik_z z} \left[ \frac{j \omega^2 \mu_0 \epsilon_0}{\omega \mu_0} - j \omega \epsilon_0 \right] = 0$$

$$g = \epsilon \operatorname{div} \vec{E} = 0$$

$$\textcircled{2} \quad \vec{E} = \vec{1}_y E_0 \sin\left(\frac{n\pi}{a} x\right) \quad \vec{H} = \frac{\partial}{\omega \mu_0} \operatorname{rot} \vec{E} = \frac{\partial}{\omega \mu_0} \vec{1}_z \frac{\partial E_y}{\partial x} = \vec{1}_z \frac{j E_0 n\pi}{\omega \mu_0 a} \cos\left(\frac{n\pi}{a} x\right)$$

$$\vec{J} = \operatorname{rot} \vec{H} - j \omega \epsilon_0 \vec{E} = 0 \quad \operatorname{rot} \vec{H} = -\vec{1}_y \frac{\partial}{\partial x} (H_z) = \vec{1}_y \frac{j E_0}{\omega \mu_0} \left(\frac{n\pi}{a}\right)^2 \sin\left(\frac{n\pi}{a} x\right)$$

$$\vec{J} = \vec{1}_y j E_0 \sin\left(\frac{n\pi}{a} x\right) \left[ \frac{1}{\omega \mu_0} \left(\frac{n\pi}{a}\right)^2 - \omega \epsilon_0 \right] = 0$$

$$\left(\frac{n\pi}{a}\right)^2 = \omega^2 \epsilon_0 \mu_0$$

$$\omega = \frac{n\pi}{a} \cdot \frac{1}{\sqrt{\mu_0 \epsilon_0}} = \frac{n\pi}{a} c_0$$

$$n=1 \quad f_1 = \frac{c_0}{2a} = \frac{3 \cdot 10^8 \text{ m/s}}{2 \cdot 0,01 \text{ m}} = 15 \text{ GHz}$$

$$\textcircled{3} \quad \vec{E} = \vec{1}_y \frac{I}{2\pi\beta} \cdot \vec{z}_0 e^{-ik_z z}$$

$$\vec{H} = \frac{\partial}{\omega \mu_0} \operatorname{rot} \vec{E} = \frac{\partial}{\omega \mu_0} \frac{1}{\beta} \vec{1}_y \frac{\partial}{\partial z} \left( \frac{I}{2\pi\beta} \vec{z}_0 e^{-ik_z z} \right) = \vec{1}_y \frac{I}{2\pi\beta} \frac{k \vec{z}_0}{\omega \mu_0} \vec{e}^{-ik_z z} = \vec{1}_y \frac{I}{2\pi\beta} \vec{e}^{-ik_z z}$$

$$\vec{S} = \vec{E} \times \vec{H}^* = \begin{vmatrix} \vec{1}_y & \vec{1}_y & \vec{1}_z \\ E_y & 0 & 0 \\ 0 & H_y & 0 \end{vmatrix} = \vec{1}_z \frac{II^* \vec{z}_0}{(2\pi\beta)^2}$$

$$\textcircled{4} \quad \vec{B} = \vec{1}_y \frac{\mu_0 I}{2\pi\beta} \quad \vec{A} = -\vec{1}_z \left( \frac{\mu_0 I}{2\pi} \ln \beta + C \right)$$

$$M = \frac{1}{I} \oint \vec{A} d\vec{a} = 0 \quad \text{ker } j \in \vec{1}_z \cdot \vec{1}_y = 0$$

ali

$$M = \frac{1}{I} \int_A \vec{B} d\vec{A} = 0 \quad d\vec{A} = \vec{1}_z dA \quad \vec{1}_y \cdot \vec{1}_z = 0$$

$$\textcircled{5} \quad \vec{E} = -\operatorname{grad} V = -\vec{1}_y E_0 e^{j\omega t} \left( 1 + \frac{a^2}{\beta^2} \right) \sin \varphi - \vec{1}_y E_0 e^{j\omega t} \left( 1 - \frac{a^2}{\beta^2} \right) \cos \varphi$$

$$\vec{G} = \vec{1}_n \cdot \vec{D}(\beta=a) = \vec{1}_n \cdot \epsilon_0 \vec{E} \Big|_{\beta=a} = \vec{1}_y \cdot \epsilon_0 \vec{E} \Big|_{\beta=a} = -2 \epsilon_0 E_0 \sin \varphi e^{j\omega t}$$

$$\operatorname{div} \vec{K} + j \omega \vec{G} = 0 \quad \vec{K} = \vec{1}_y K(\varphi)$$

$$\operatorname{div} \vec{K} = \frac{1}{a} \frac{\partial K(\varphi)}{\partial \varphi} = -j \omega G$$

$$\frac{\partial K}{\partial \varphi} = a 2 j \omega \epsilon_0 E_0 e^{j\omega t} \sin \varphi \rightarrow \vec{K} = -\vec{1}_y \left( 2 j \omega \epsilon_0 E_0 a e^{j\omega t} \cos \varphi + C \right)$$





1. Elektrostatik EM 4.12. 2007

$$\text{1) } \vec{F} = \vec{i}_z \frac{1}{r} \sin \varphi \quad \text{div } \vec{F} = \frac{1}{r^2} \left( \frac{\partial}{\partial r} \left( \frac{1}{r} \sin \varphi \right) + 0 + 0 \right) = 0$$

$\vec{F}$  singulärer Punkt  $r \gg 0$

$$\text{2) } \vec{B} = \text{rot } \vec{A} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{i}_r & \vec{i}_{\theta} & \vec{i}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ \vec{A}_r & \vec{A}_{\theta} & \vec{A}_z \end{vmatrix} = \frac{1}{r^2 \sin \theta} \left( \vec{i}_r \sin \theta \frac{1}{r \sin \theta} 2r \right) = \vec{i}_r \frac{2}{r \sin \theta}$$

$$\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{j} = \text{rot } \vec{H} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{i}_r & \vec{i}_{\theta} & \vec{i}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ \vec{H}_r & \vec{H}_{\theta} & \vec{H}_z \end{vmatrix} = \frac{1}{r^2 \sin \theta} \left( -\vec{i}_\theta r \frac{\partial}{\partial r} \left( \frac{2r}{\mu_0} \right) \right) = -\vec{i}_\theta \frac{2}{\mu_0 \sin \theta}$$

$\oint_A \vec{F} d\vec{A} = \iint_D \vec{F} \cdot (\vec{i}_z) \alpha d\varphi dz = 0$  NIUVERBÖRN!

$$\text{3) } \text{rot } \vec{F} = \frac{1}{r} \begin{vmatrix} \vec{i}_r & \vec{i}_{\theta} & \vec{i}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ \frac{1}{r} \sin \varphi & 0 & 0 \end{vmatrix} = -\vec{i}_z \frac{1}{r^2} \cos \varphi$$

so VERTRETEN!

$$\text{4) } \Delta V = 0 \quad \frac{\partial^2 V}{\partial z^2} = 0$$

$$\Delta V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2}$$

$$V(x_1, y_1, z) = X(x_1) \cdot Y(y_1)$$

$$\frac{X''}{X} + \frac{Y''}{Y} = 0$$

$$\frac{1}{L_x} \frac{d^2 X}{dx^2} + \frac{1}{L_y} \frac{d^2 Y}{dy^2} = 0$$

$$V = (A e^{k_x x} + B e^{-k_x x}) (C \cos k_y y + D \sin k_y y)$$

Neini gosgo!

$$\begin{cases} V(y=0) = 0 \\ V(y=L_y) = 0 \end{cases} \Rightarrow C = 0 ; \quad k_x = k_y = n \frac{\pi}{a}$$

$$V(x \rightarrow \infty) = 0 \Rightarrow A = 0$$

$$V(x_1, y_1) = B D e^{-k_x x_1} \sin \frac{n\pi}{a} y_1 \quad D = 1$$

$$V(x_1, y_1) = \sum_{n=1}^{\infty} B_n e^{-k_x x_1} \sin \frac{n\pi}{a} y_1$$

$$V(x=0) = V_0 = \sum_{n=1}^{\infty} B_n \sin \frac{n\pi}{a} y_1 / \int_0^a \sin \frac{n\pi}{a} dy$$

$$\frac{9V_0}{4\pi L} (1 - \cos \pi k) = B_n \frac{q}{2}$$

$$m \rightarrow n \quad B_n = \frac{2V_0}{n\pi L} (1 - \cos \pi k)$$

$\vec{B}_0 = 4 \vec{B} = 4 \vec{i}_z \frac{\mu \cdot I}{4\pi L} \cdot \frac{4}{\pi L}$

$\vec{B}_0 = \vec{i}_z \frac{2\mu_0 \mu \cdot I}{\pi L}$



$$\textcircled{1} \quad \vec{H}(g < a) = \begin{cases} \vec{J}_g \frac{c}{g} & ; g < a \\ 0 & ; g > a \end{cases} \quad \alpha = 0 \quad \mu = \mu_0$$

$$\vec{J}_g = ? \quad | \quad \vec{K} = ? \quad | \quad I = ?$$

$$\vec{H}(g < a) = \text{rot} \vec{H}(g < a) = 0$$

$$\vec{H}(g > a) - \text{rot} \vec{H}(g > a) = 0$$

$$\vec{K}(g = a) = \vec{J}_g \times (\vec{H}(g > a) - \vec{H}(g < a)) =$$

$$= \vec{J}_g \times (0 - \vec{J}_g \frac{c}{a}) = 0$$

$$I(g = 0) = \oint \vec{H}(g < a) \cdot \vec{l}_g g d\varphi = 0$$

(takšno polje posamežjo magnetino...)

$$\textcircled{4} \quad f = 16 \text{ Hz} \quad \text{stresanje} \quad U = Ed \quad Z = 37 \Omega$$

$$\rho_{\text{stres}} = 50 \text{ S/m} \quad \text{zanesljivo}$$

$$w = 10 \text{ mm} \quad \epsilon_0$$

$$d = 1 \text{ mm} \quad \mu_0 \quad C_w$$

$$\alpha (\text{AB/m}^2) = ?$$

$$\left( Z_w = 37.7 \Omega \right)$$

$$Z_w = \frac{U}{I} = \frac{Ed}{N} \neq \frac{d}{w} Z_0$$

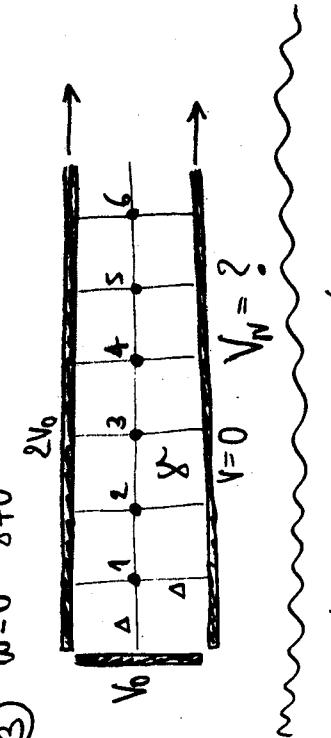
$$dR = \frac{2dl}{8w\sigma} \quad \sigma = \sqrt{\frac{2}{\rho/\mu_0}} = (24 \Omega)$$

$$dR = \frac{2dl}{w} \sqrt{\frac{\mu_0}{2\sigma}}$$

$$\ln \frac{P_b}{P_0} = \frac{dl}{Z_w} = \frac{2dl}{dZ_0} \sqrt{\frac{\mu_0}{2\sigma}} \quad \int dl$$

$$\alpha = \frac{10 \ln \frac{P_b}{P_0}}{d} = \frac{10}{dZ_0} \ln \frac{P_b}{P_0}$$

$$\alpha = \frac{10}{w d Z_0} \frac{2}{dZ_0} \sqrt{\frac{\mu_0}{2\sigma}} = 0.193 \text{ dB/m}$$



$$V_N = V_0 \text{ za poljuben N (SIMETRIČNA)}$$

$$\mu_0 = 4\pi \cdot 10^{-7} \text{ Vs/A}$$

$$\textcircled{5} \quad \vec{S}_V = \frac{1}{2} \vec{E} \times \vec{H}_V = \vec{I}_s \frac{|E|}{2Z_0} = \vec{I}_s \frac{W^2 Z_0}{2} = |I_s| \sqrt{\frac{2\pi\mu_0}{Z_0}} = 0.0133 A/m$$

$$U_i = -\frac{d\Phi}{dt} = -\text{ind}$$

$$|U_i| = \omega \mu_0 / 2 |I_s| Z_0 = -j \omega \mu_0 / 2 |I_s| A = -j \omega \mu_0 / 2 H_A = -j \omega \mu_0 / 2 H_A$$

$$\textcircled{5} \quad \vec{S}_V = \frac{1}{2} \vec{E} \times \vec{H}_V = \vec{I}_s \frac{|E|}{2Z_0} = \vec{I}_s \frac{W^2 Z_0}{2} = |I_s| \sqrt{\frac{2\pi\mu_0}{Z_0}} = 0.0133 A/m$$

$$A = \lambda \cdot h^2$$

$$\lambda = 300 \text{ m}$$

$$\mu_0 = \mu_0 \cdot \epsilon_0$$

$$(H = H_V + H_0 = 2H_V \text{ ob končni steni})$$

$$\textcircled{2} \quad \vec{E}^2(r, \theta) = ?$$

$$E^2 = \frac{Qh}{4\pi\epsilon_0} \left[ \vec{J}_r \frac{2\cos\theta}{r^3} + \vec{J}_\theta \frac{\sin\theta}{r^3} \right]$$

$$Q = 5a^2$$

$$\vec{E} = \frac{Qah}{4\pi\epsilon_0} \left[ \vec{J}_r \frac{2\cos\theta}{r^3} + \vec{J}_\theta \frac{\sin\theta}{r^3} \right]$$

# ELEKTROMAGNETIKA

10.07.2008

$$\textcircled{1} \quad \mu = \mu_0; \omega = 0 \quad \vec{A}_2(\rho, \varphi, z) = \begin{cases} 0 & ; \rho \leq a \\ \vec{A}_2(0, \varphi, z) = \begin{cases} 0 & ; z \geq a \\ \vec{A}_2(0, \varphi, 0) = \vec{A}_2(0, \varphi, z) = 0 & ; z < a \end{cases} \end{cases}$$

$$\vec{H}(r, \varphi) = \frac{1}{\mu_0} \operatorname{rot} \vec{A} = \frac{1}{\mu_0} \frac{1}{z} \begin{vmatrix} \vec{A}_2 & \vec{A}_2 \\ \frac{\partial}{\partial z} & \frac{\partial}{\partial \varphi} \end{vmatrix} = -\frac{1}{\mu_0} \frac{C}{z} \frac{1}{\rho} \frac{1}{a}$$

$$\vec{H}(r, \varphi, z) = \underline{\underline{0}} \quad \vec{J}(r, \varphi, z) = \underline{\underline{0}} \quad \vec{J}(r, \varphi, z) = 0$$

$$\textcircled{2} \quad \vec{H}(r, \varphi, z) \cdot d\vec{s} = \int_0^r \vec{A}_2 \frac{C}{\rho} \frac{1}{z} \cdot \vec{N}_S d\rho = -\frac{2\pi C}{\mu_0 a}$$

$$I(r=0) = \int_0^r \vec{H}(r, \varphi, z) \cdot d\vec{s} = \int_0^r \vec{A}_2 \frac{C}{\rho} \frac{1}{z} \cdot \vec{N}_S d\rho = \underline{\underline{0}}$$

$$V(r=0) = -E_0 r \cos \theta = -E_0 r \cos \theta + \frac{Qd}{4\pi\epsilon_0} \frac{\cos \theta}{r^2} \quad ; \quad 2 = r \cos \theta$$

$$V(r=a) = 0 = -E_0 a \cos \theta + \frac{Qd}{4\pi\epsilon_0} \frac{\cos \theta}{a^2}$$

$$E_0 = \frac{Qd}{4\pi\epsilon_0 a^3} = \frac{10^{-9} \text{ As}}{4\pi \cdot 9 \cdot 10^9 \cdot \frac{1}{4\pi \cdot 8.85 \cdot 10^{-12}}} \frac{As}{Vm} \cdot \frac{1}{Vm} \cdot \frac{1}{Vm^2}$$

$$E_0 = \frac{9 V/m}{\pi \cdot 10^{-9} \text{ Asm}} = \underline{\underline{E_0 = 10^9 V/m}}$$

$$\frac{a}{\epsilon_0} = ? \quad \frac{Qd}{\epsilon_0} = 10^{-9} \text{ Asm} \quad \frac{1}{\epsilon_0} = ?$$

$$\textcircled{3} \quad \omega = 0 \quad \left\{ \begin{array}{l} \text{Symetria} \quad V_1 = V_2 = V_3 = V_{13} \\ V_2 = V_4 = V_6 = V_8 = V_{10} = V_{12} = V_{14} = V_{15} \\ V_3 = V_7 = V_{11} = V_{15} \end{array} \right.$$

$$4V_1 = 2V_2 + 2V_6 \rightarrow 2V_1 = V_2 + V_6$$

$$4V_2 = V_1 + V_3$$

$$4V_3 = 2V_2 + V_6$$

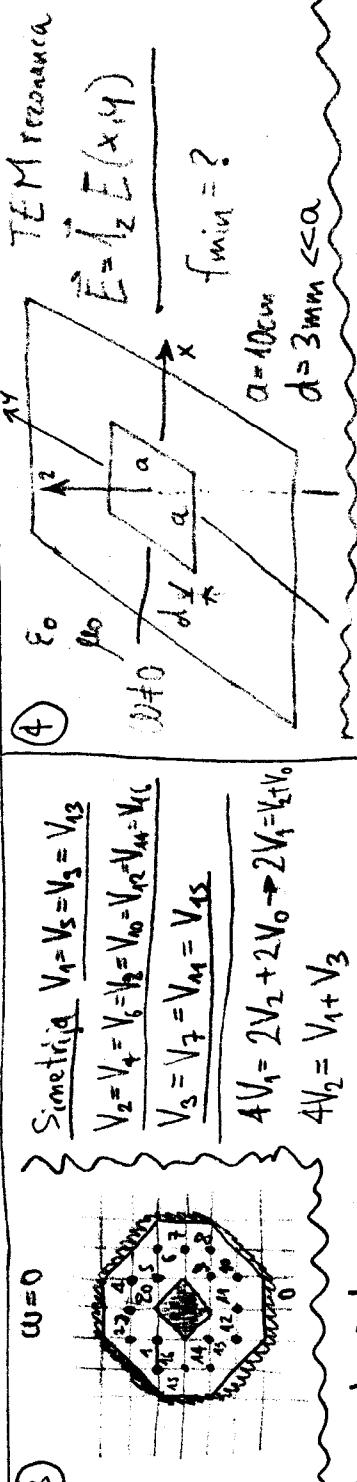
$$8V_2 = V_1 + V_6 + 2V_3 \rightarrow 7V_2 = V_0 + 2V_3$$

$$4V_3 = V_0 + 2V_2$$

$$28V_3 = 7V_0 + 2V_6 + 4V_3 \rightarrow 24V_3 = 9V_0 \rightarrow V_3 = \frac{3}{8}V_0$$

$$V_2 = \frac{1}{7}(V_0 + 2V_3) = \frac{2}{7}V_0$$

$$V_1 = \frac{1}{2}(V_0 + V_2) = \frac{5}{7}V_0$$



$$\textcircled{4} \quad \left\{ \begin{array}{l} E_0 = \vec{E}_2(x, y) \\ \vec{E} = \vec{E}_2(x, y) \end{array} \right. \quad f_{\min} = ?$$

$$a = 10 \text{ cm} \quad d = 3 \text{ mm} \ll a$$

$$\vec{E} = \vec{E}_2(A \cos k_x x + B \sin k_x x)(C \cos k_y y + D \sin k_y y); k_x^2 + k_y^2 = k^2$$

$$\text{resonance: } k_x = k = \omega / \sqrt{\mu_0 \epsilon_0}; k_y = 0$$

$$\vec{E} = \vec{E}_2 B \sin \frac{\pi}{a} x \rightarrow k = \frac{\pi}{a}$$

$$\frac{\pi}{a} = \omega \sqrt{\mu_0 \epsilon_0} = \frac{2\pi f_{\min}}{C_0} \rightarrow f_{\min} = \frac{C_0}{2a} = \underline{\underline{1.56 \text{ Hz}}}$$

$$f = ?$$

$$\textcircled{5} \quad R_n = \frac{R}{g A_n} = \frac{l}{g \pi r^2}$$

$$R_n = \frac{R}{g A_n} = \frac{l}{8 \pi r^2}$$

$$\frac{R_n}{R_e} = 10 = \frac{r}{2\delta} \rightarrow \delta = \frac{r}{20} = \underline{\underline{2.5 \text{ pm}}}$$

$$f = \frac{\omega}{2\pi} = \frac{1}{\pi \mu_0 \epsilon_0 \delta^2} = \frac{1 \text{ fm}}{\pi \cdot 4\pi \cdot 10^{-7} \text{ Vs} \cdot 8.85 \cdot 10^{-12} \text{ F/Vs} \cdot 10^{-6} \text{ m}^2}$$

$$f = \underline{\underline{4.24 \text{ GHz}}}$$



1. kolovrh 12. EM 25. 11. 2008

$$\text{② } \vec{A}(r, \theta, \phi) = \vec{r}_\theta \frac{1}{r} \cdot \sin \theta \cdot \vec{t}_\phi$$

polje

$$h_\eta = \alpha \sqrt{\cos^2 \psi + \sin^2 \eta}$$

$$h_\psi = \alpha \sqrt{\cos^2 \psi + \sin^2 \eta}$$

$$\operatorname{div} \vec{F} = \frac{1}{h_\eta h_\psi h_\phi} \left( \frac{\partial (F_\phi h_\eta h_\psi)}{\partial \phi} \right) =$$

$$= \frac{1}{\alpha^3 (\cos^2 \psi + \sin^2 \eta)} \frac{\partial (\ln \phi \alpha^2 (\cos^2 \psi + \sin^2 \eta))}{\partial \phi} =$$

$$= \frac{1}{\alpha \sin \psi} \frac{\partial (\ln \phi)}{\partial \phi} = \frac{1}{\alpha \phi \sin \eta \sin \psi} \quad \text{SO VRTRNC}$$

$$\operatorname{rot} \vec{F} = \frac{1}{h_\eta h_\psi h_\phi} \begin{vmatrix} \vec{r}_\eta & \vec{r}_\psi & \vec{r}_\phi \\ \frac{\partial}{\partial \eta} & \frac{\partial}{\partial \psi} & \frac{\partial}{\partial \phi} \\ h_\eta h_\psi h_\phi & h_\eta h_\psi h_\phi & h_\eta h_\psi h_\phi \end{vmatrix}$$

$$= \frac{1}{\mu_0 r^2 \sin \theta} \begin{bmatrix} \vec{r}_\theta \vec{s} \frac{\partial}{\partial \phi} \\ -\vec{r}_\phi \vec{s} \frac{\partial}{\partial \theta} \\ \vec{r}_\theta \vec{s} \frac{\partial}{\partial r} \end{bmatrix} =$$

$$= \frac{1}{\mu_0 r^2 \sin \theta} \begin{bmatrix} \vec{r}_\theta \vec{s} \frac{\partial}{\partial \phi} \\ -\vec{r}_\phi \vec{s} \frac{\partial}{\partial \theta} \\ \vec{r}_\theta \vec{s} \frac{\partial}{\partial r} \end{bmatrix} =$$

$$= \frac{1}{\mu_0 r^2 \sin \theta} \begin{bmatrix} \vec{r}_\theta \vec{s} \frac{\partial}{\partial \phi} \\ -\vec{r}_\phi \vec{s} \frac{\partial}{\partial \theta} \\ \vec{r}_\theta \vec{s} \frac{\partial}{\partial r} \end{bmatrix} =$$

$$= \frac{1}{\mu_0 r^2 \sin \theta} \begin{bmatrix} \vec{r}_\theta \vec{s} \frac{\partial}{\partial \phi} \\ -\vec{r}_\phi \vec{s} \frac{\partial}{\partial \theta} \\ \vec{r}_\theta \vec{s} \frac{\partial}{\partial r} \end{bmatrix} =$$

$$= \frac{1}{\mu_0 r^2 \sin \theta} \begin{bmatrix} \vec{r}_\theta \vec{s} \frac{\partial}{\partial \phi} \\ -\vec{r}_\phi \vec{s} \frac{\partial}{\partial \theta} \\ \vec{r}_\theta \vec{s} \frac{\partial}{\partial r} \end{bmatrix} =$$



$$\text{resumen = resumen 2 \Delta}$$

$$\boxed{V_1 = V_2} \\ \boxed{V_3 = V_4}$$

$$\boxed{V_5 = \frac{1}{2} V_0}$$

$$\begin{aligned} 4V_1 &= 2V_0 + V_3 + V_2 \\ 4V_3 &= -2V_0 + V_1 + V_4 \\ 3V_1 &= 2V_0 + V_3 \Rightarrow V_3 = 3V_1 - 2V_0 \Rightarrow \boxed{V_3 = \frac{1}{2} V_0} \\ 3V_3 &= -2V_0 + V_1 \uparrow \\ 9V_1 - 6V_0 &= -2V_0 + V_1 \Rightarrow \boxed{V_1 = \frac{1}{2} V_0} \end{aligned}$$

$$\text{③ } \vec{E} = \frac{1}{h\pi\epsilon} \frac{Q}{r^2} \quad W = \frac{\epsilon}{2} \int_V |\vec{E}|^2 dV$$

$$W = \frac{\epsilon}{2} \int_V |\vec{E}|^2 r^2 \sin \theta dr d\theta d\phi =$$

$$= \frac{\epsilon}{2} \int_0^\infty \int_0^\pi \int_0^{2\pi} \left( \frac{Q}{h\pi\epsilon r^2} \right)^2 r^2 \sin \theta dr d\theta d\phi =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 2\pi \int_0^\infty \frac{1}{r^2} [-\cos \theta] dr =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 2\pi \cdot 2 \int_0^\infty \frac{1}{r^2} dr =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 \frac{2\pi}{\epsilon} = \frac{Q^2}{8\pi\epsilon} \frac{1}{\epsilon} =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 2\pi \int_0^\infty \frac{1}{r^2} [-\cos \theta] dr =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 2\pi \cdot 2 \int_0^\infty \frac{1}{r^2} dr =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 \frac{2\pi}{\epsilon} = \frac{Q^2}{8\pi\epsilon} \frac{1}{\epsilon} =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 2\pi \int_0^\infty \frac{1}{r^2} [-\cos \theta] dr =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 2\pi \cdot 2 \int_0^\infty \frac{1}{r^2} dr =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 \frac{2\pi}{\epsilon} = \frac{Q^2}{8\pi\epsilon} \frac{1}{\epsilon} =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 2\pi \int_0^\infty \frac{1}{r^2} [-\cos \theta] dr =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 2\pi \cdot 2 \int_0^\infty \frac{1}{r^2} dr =$$

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$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 2\pi \int_0^\infty \frac{1}{r^2} [-\cos \theta] dr =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 2\pi \cdot 2 \int_0^\infty \frac{1}{r^2} dr =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 \frac{2\pi}{\epsilon} = \frac{Q^2}{8\pi\epsilon} \frac{1}{\epsilon} =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 2\pi \int_0^\infty \frac{1}{r^2} [-\cos \theta] dr =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 2\pi \cdot 2 \int_0^\infty \frac{1}{r^2} dr =$$

$$= \frac{\epsilon}{2} \left( \frac{Q}{h\pi\epsilon} \right)^2 \frac{2\pi}{\epsilon} = \frac{Q^2}{8\pi\epsilon} \frac{1}{\epsilon} =$$

2. Lekcji: iz EM - 26. 1. 2009

$$\textcircled{2} M_1 = \frac{\pi \mu_0 \alpha^2 N_1 N_2}{2 d_1^3} = \frac{\pi \mu_0 \alpha^4 N_1 N_2}{2 d_1^2}$$

$$M_2 = \left( \frac{3 \mu_0}{2 + \mu_0} \right)^2 \frac{\pi \mu_0 \alpha^4 N_1 N_2}{2 d_2^3}$$

$$H_1 = H_2$$

$$\frac{1}{d_1^3} = \left( \frac{3 \mu_0}{2 + \mu_0} \right)^2 \frac{1}{d_2^3} = \left( \frac{3 \cdot 2}{2+2} \right)^2 \frac{1}{d_2^3}$$

$$d_2 = \sqrt[3]{\frac{3}{2}} d_1$$

$$d_2 = 1,31 \cdot d_1$$

$$\vec{H} = \vec{H}_1 \frac{2 \alpha^2}{\mu_0}$$

$$\vec{J} = \vec{v} \vec{d} \vec{H} - i \omega \epsilon_0 \vec{E}$$

$$\vec{E} = -i \omega \vec{A}$$

$$\vec{rot} \vec{H} = \frac{1}{\mu_0} \begin{vmatrix} \vec{\lambda}_x & \vec{\lambda}_y & \vec{\lambda}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{2 \alpha^2}{\mu_0} & 0 & 0 \end{vmatrix} = \frac{1}{\mu_0} \begin{vmatrix} \vec{\lambda}_x & \vec{\lambda}_y & \vec{\lambda}_z \\ \frac{1}{2} \frac{\partial}{\partial y} & \frac{1}{2} \frac{\partial}{\partial z} & \frac{1}{2} \frac{\partial}{\partial x} \\ \frac{2 \alpha^2}{\mu_0} & 0 & 0 \end{vmatrix} =$$

$$= \frac{1}{\mu_0} \frac{1}{2} \left[ -\vec{\lambda}_x \vec{\lambda}_y \frac{\partial}{\partial y} (-\vec{\lambda}_z \vec{\lambda}_y) \right] = \frac{1}{\mu_0} \frac{1}{2} \left[ \vec{\lambda}_x \vec{\lambda}_y \vec{\lambda}_y \vec{\lambda}_z \right]$$

$$\textcircled{3} \vec{A}(\varrho, \varphi, z) = -\vec{\lambda}_x \vec{\lambda}_y \vec{\lambda}_z$$

$$\vec{H} = \frac{1}{\mu_0} \vec{rot} \vec{A} = \frac{1}{\mu_0} \frac{1}{\varrho} \begin{vmatrix} \vec{\lambda}_x & \vec{\lambda}_y & \vec{\lambda}_z \\ \frac{1}{\varrho} & 0 & 0 \\ 0 & 0 & 0 \end{vmatrix} = -\vec{\lambda}_x \vec{\lambda}_y \vec{\lambda}_z$$

$$= \frac{1}{\mu_0} \frac{1}{2} \left[ -\vec{\lambda}_x \vec{\lambda}_y \frac{\partial}{\partial y} (-\vec{\lambda}_z \vec{\lambda}_y) \right] = \frac{1}{\mu_0} \frac{1}{2} \left[ \vec{\lambda}_x \vec{\lambda}_y \vec{\lambda}_y \vec{\lambda}_z \right]$$

$$\vec{J} = \vec{v} \vec{d} \vec{H} - i \omega \epsilon_0 \vec{E}$$

$$\vec{J} = -i \omega \vec{A}$$

$$\vec{rot} \vec{H} = \frac{1}{\mu_0} \begin{vmatrix} \vec{\lambda}_x & \vec{\lambda}_y & \vec{\lambda}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{2 \alpha^2}{\mu_0} & 0 & 0 \end{vmatrix} = \frac{1}{\mu_0} \begin{vmatrix} \vec{\lambda}_x & \vec{\lambda}_y & \vec{\lambda}_z \\ \frac{1}{2} \frac{\partial}{\partial y} & \frac{1}{2} \frac{\partial}{\partial z} & \frac{1}{2} \frac{\partial}{\partial x} \\ \frac{2 \alpha^2}{\mu_0} & 0 & 0 \end{vmatrix} =$$

$$= \frac{2}{\mu_0} \left( \vec{\lambda}_x \vec{\lambda}_y \frac{\partial}{\partial y} - \vec{\lambda}_y \vec{\lambda}_z \frac{\partial}{\partial z} \right) = -\vec{\lambda}_y \frac{\vec{\lambda}_z \vec{\lambda}_y}{\mu_0} + \vec{\lambda}_z \frac{\vec{\lambda}_x \vec{\lambda}_z}{\mu_0}$$

$$\vec{J} = -i \vec{\lambda}_y \frac{\mu_0}{\mu_0} \left[ \frac{\vec{\lambda}_z \vec{\lambda}_y}{\mu_0} + \omega^2 \epsilon_0 \vec{\lambda}_z \vec{\lambda}_y \right]$$

$$\textcircled{4} \vec{E} = \vec{\lambda}_x E_0 \sin\left(\frac{\pi}{6} y\right) e^{-j \frac{\omega}{2} z}$$

$$\vec{H} = \frac{i}{\omega \mu_0} \vec{rot} \vec{E} = \frac{i}{\omega \mu_0} \begin{vmatrix} \vec{\lambda}_x & \vec{\lambda}_y & \vec{\lambda}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_0 \sin\left(\frac{\pi}{6} y\right) e^{-j \frac{\omega}{2} z} & 0 & 0 \end{vmatrix}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H} = \frac{1}{2} \begin{vmatrix} \vec{\lambda}_x & \vec{\lambda}_y & \vec{\lambda}_z \\ E_x & E_y & E_z \\ H_x^* & H_y^* & H_z^* \end{vmatrix}$$

$$\vec{E} = \vec{\lambda}_x E_0 \sin\left(\frac{\pi}{6} y\right) e^{-j \frac{\omega}{2} z}$$

$$\vec{H} = \frac{i}{\omega \mu_0} \begin{vmatrix} \vec{\lambda}_x & \vec{\lambda}_y & \vec{\lambda}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_0 \sin\left(\frac{\pi}{6} y\right) e^{-j \frac{\omega}{2} z} & 0 & 0 \end{vmatrix} = \frac{i}{\omega \mu_0} \left[ \vec{\lambda}_y E_0 \sin\left(\frac{\pi}{6} y\right) e^{-j \frac{\omega}{2} z} - \vec{\lambda}_z E_0 \sin\left(\frac{\pi}{6} y\right) e^{-j \frac{\omega}{2} z} \right]$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H} = \frac{1}{2} \begin{vmatrix} \vec{\lambda}_x & \vec{\lambda}_y & \vec{\lambda}_z \\ E_x & E_y & E_z \\ H_x^* & H_y^* & H_z^* \end{vmatrix}$$

$$P = \int_A \vec{S} \cdot d\vec{A} = \frac{1}{2} \int_A \left\{ \frac{E E_0^* \epsilon_0}{\omega \mu_0} \sin^2\left(\frac{\pi}{6} y\right) \right\} dxdy$$

$$P = \frac{|E_0|^2 \epsilon_0}{\omega \mu_0} \frac{ab}{l} = \frac{|E_0|^2 ab}{2 \cdot l}$$

$$b = \sqrt{\frac{g}{3}} \alpha = \sqrt{\frac{11}{300}} = 19,1 \text{ cm}$$

$$\alpha = \sqrt{\frac{11}{800}} = 11,7 \text{ cm}$$

$$\textcircled{5} \vec{E} = (\vec{\lambda}_x \vec{\lambda}_z - \vec{\lambda}_y \vec{\lambda}_z + \vec{\lambda}_x \vec{\lambda}_z) \frac{v}{m}$$

$$\vec{H} = \vec{\lambda}_x \cdot \frac{v}{E}$$

$$\vec{H} = \vec{\lambda}_x \times \vec{\lambda}_z$$

$$\vec{H} = \vec{\lambda}_x \cdot \frac{v}{\vec{E} \times \vec{\lambda}_z}$$

$$\vec{H} = \vec{\lambda}_x \cdot \frac{v}{\sqrt{1^2 + 3^2}}$$

$$\vec{H} = \vec{\lambda}_x \cdot \frac{v}{\sqrt{10}}$$

$$\vec{H} = \vec{\lambda}_x \cdot \frac{v}{\sqrt{10} \cdot 120\pi} \frac{A}{m}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H} = \begin{vmatrix} \vec{\lambda}_x & \vec{\lambda}_y & \vec{\lambda}_z \\ 3 & -1 & 2 \\ 6 & -2 & -10 \end{vmatrix} =$$

$$\vec{S} = \frac{1}{2} \left( \vec{\lambda}_x \lambda_4 + \vec{\lambda}_y \lambda_2 \right) \left( \pm \frac{1}{\sqrt{10} \cdot 240\pi} \right)$$

$$\vec{S} = \pm \left( \vec{\lambda}_x + \vec{\lambda}_y \vec{3} \right) \left( \pm \frac{7}{\sqrt{10} \cdot 120\pi} \right) \frac{W}{m^2}$$

$$\textcircled{5} f = \frac{\epsilon_0}{2} \sqrt{\left( \frac{m}{\omega} \right)^2 + \left( \frac{v}{\omega} \right)^2}$$

$$f_{1,1} = \frac{\epsilon_0}{2} \sqrt{\left( \frac{1}{\omega} \right)^2 + \left( \frac{1}{\omega} \right)^2} = 15 \cdot 10^9 \text{ Hz}$$

$$\frac{1}{\omega^2} + \frac{1}{b^2} = 100$$

$$f_{1,3} = f_{2,1}$$

$$\frac{8}{b} = \frac{3}{\alpha} \Rightarrow$$

$$\frac{1}{\alpha^2} + \frac{8^2}{b^2} = 100$$

$$\alpha = \sqrt{\frac{11}{800}} = 11,7 \text{ cm}$$

1. Zolobrvi iz EM 2. 12. 2009

$$\begin{aligned}
 \text{① } \vec{F}(q_1, q_2) &= \vec{i} q_1 \frac{1}{q_1^3} \sin(2q) & q = 0 & q = \frac{\pi}{2} \Rightarrow \sin 2q = 0 \\
 &= \vec{i} q_1 \left( \frac{1}{q_1^3} \left( \frac{1}{2} \sin 2q \right) \right) & \vec{B} = \text{rot } \vec{A} = \frac{1}{\zeta} \begin{vmatrix} \vec{i} q_1 & \vec{j} q_2 & \vec{k} \\ \frac{\partial}{\partial q_1} & \frac{\partial}{\partial q_2} & \frac{\partial}{\partial q} \\ 0 & 0 & \frac{1}{q_1^2} \sin q \end{vmatrix} = \\
 &= \frac{1}{q_1^2} \left[ \vec{i} q_1 \frac{\partial}{\partial q} \left( \frac{1}{q_1^3} \sin q \right) - \vec{j} q_1 \cdot \vec{j} q_2 \cdot \frac{\partial}{\partial q} \left( \frac{1}{q_1^3} \sin q \right) \right] = \\
 &= \frac{1}{q_1^2} \left[ \vec{i} q_1 \frac{\partial}{\partial q} \left( \frac{1}{q_1^3} \cos q \right) - \vec{j} q_1 \left( -\frac{1}{q_1^2} \right) \sin q \right] = \\
 &= \vec{i} q_1 \frac{\vec{B}}{q_1^2} = \vec{i} q_1 \frac{2}{q_1^2} \cos q + \vec{j} q_1 \frac{2}{q_1^2} \sin q + \vec{k} q_1 \frac{2}{q_1^2} \cos q + \vec{k} q_1 \frac{2}{q_1^2} \sin q \\
 &\text{rot } \vec{F} = \frac{1}{\zeta} \begin{vmatrix} \vec{i} q_1 & \vec{j} q_2 & \vec{k} \\ \frac{\partial}{\partial q_1} & \frac{\partial}{\partial q_2} & \frac{\partial}{\partial q} \\ 0 & 0 & 0 \end{vmatrix} = \text{② } \vec{A}(q_1, q_2, t) = \vec{i} q_2 \frac{t^2}{q_1^2} \sin q
 \end{aligned}$$

$$\begin{aligned}
 \text{distr } \vec{F}(q_1, q_2, t) &= \frac{1}{q_1} \left( \frac{1}{q_1^3} \left( \frac{1}{2} \sin 2q \right) \right) = \\
 &= \frac{1}{q_1^2} 2 \cdot \cos 2q \Rightarrow \text{polje } \vec{F} \text{ ima izvor} \\
 &= \vec{i} q_1 \frac{2}{q_1^2} \sin 2q & \text{rot } \vec{F} = \frac{1}{\zeta} \begin{vmatrix} \vec{i} q_1 & \vec{j} q_2 & \vec{k} \\ \frac{\partial}{\partial q_1} & \frac{\partial}{\partial q_2} & \frac{\partial}{\partial q} \\ 0 & 0 & 0 \end{vmatrix} = -\vec{i} q_2 \frac{2}{q_1^2} \sin 2q
 \end{aligned}$$

$$\text{③ } \Delta V = 0 \quad V = \sum_{n=0}^{\infty} (A_n \cos(ny) + B_n \sin(ny)) (C_n \sin(nx) + D_n \cos(nx))$$

polje  $\vec{F}$  ima vrstice

$$\begin{aligned}
 V(x, y=0) &= 0 \Rightarrow A_n = 0 \\
 V(x, y=\alpha) &= 0 \Rightarrow n\alpha = \frac{\pi}{2} \Rightarrow n = \frac{\pi}{2\alpha} \\
 V &= \sum_{k=1}^{\infty} \sin\left(\frac{\pi k}{2\alpha} y\right) (C_n \sin\left(\frac{\pi k}{2\alpha} x\right) + D_n \cos\left(\frac{\pi k}{2\alpha} x\right))
 \end{aligned}$$

$$\begin{aligned}
 V(x=0, y) &= V_1 = \sum_{k=1}^{\infty} \sin\left(\frac{\pi k}{2\alpha} y\right) D_n \\
 D_n &= \frac{2}{\alpha} \int_0^\alpha \sin\left(\frac{\pi k}{2\alpha} y\right) dy = \frac{2V_1}{\alpha} \left( -\frac{\cos\left(\frac{\pi k}{2\alpha} y\right)}{\frac{\pi k}{2\alpha}} \right)_0 = \frac{2V_1}{\alpha} \left( -\frac{(-1)^k}{\frac{\pi k}{2\alpha}} \alpha + \frac{\alpha}{\frac{\pi k}{2\alpha}} \right) = \frac{2V_1}{\alpha} \left( 1 - (-1)^k \right)
 \end{aligned}$$

$$\begin{aligned}
 \vec{E} &= -\vec{g} \text{ grad } V = -\left( \vec{i} x 2 + \vec{j} y \frac{\partial V}{\partial x} \right) = -\left( \vec{i} x 2 + \vec{j} y h + 0 \right) \\
 |\vec{E}| &= \sqrt{2^2 + h^2} = \sqrt{20} \frac{V}{m}
 \end{aligned}$$

$$W = \frac{1}{2} \int \epsilon_0 |\vec{E}|^2 d\sigma$$

$$W = \frac{1}{2} \cdot 8,85 \cdot 10^{-12} \frac{As}{Vm} \cdot 2,0 \frac{V^2}{m^2} \cdot \int dx dy d\sigma$$

$$W = \frac{1}{2} \cdot 8,85 \cdot 10^{-12} \cdot 2,0 \cdot 1 \frac{V^2}{m^2} \text{ je } \text{Nai m}^3 \text{ volumen}$$

$$W = 8,85 \cdot 10^{-12} \cdot 10 \cdot \underline{\epsilon_0} \text{ je imao enaku vrednost energije}$$

$$\begin{aligned}
 \text{rot } \vec{H} &= \vec{j} + i \epsilon_0 c E & \omega = 0 \Rightarrow \text{rot } \vec{H} = \vec{j} \\
 \vec{j} &= \frac{1}{\zeta} \begin{vmatrix} \vec{i} q_1 & \vec{j} q_2 & \vec{k} \\ \frac{\partial}{\partial q_1} & \frac{\partial}{\partial q_2} & \frac{\partial}{\partial t} \\ 0 & 0 & 0 \end{vmatrix} = \frac{1}{\zeta} \begin{vmatrix} \vec{i} q_1 & \vec{j} q_2 & \vec{k} \\ \frac{\partial}{\partial q_1} & \frac{\partial}{\partial q_2} & \frac{\partial}{\partial t} \\ \frac{1}{q_1^2} \sin q & 0 & 0 \end{vmatrix} = \\
 &= \frac{1}{\zeta} \left[ -\vec{i} q_2 \frac{2}{q_1^2} \sin q + \vec{j} q_1 \left( \frac{2}{q_1^2} \cos q \right) + \vec{k} q_1 \left( \frac{2}{q_1^2} \cos q \right) \right] + \\
 &+ \vec{i} q_2 \frac{2}{q_1^2} \left( \frac{2}{q_1^2} \cos q - \frac{2}{q_1^2} \frac{\sin q}{q_1} \right) = \\
 &= -\vec{i} q_2 \frac{2}{q_1^2} \sin q + \vec{j} q_1 \frac{2}{q_1^2} \cos q
 \end{aligned}$$

$$\begin{aligned}
 C_m &= \frac{2V_1}{\alpha} \left( 1 - (-1)^k \right) \left( 1 - \cos\left(\frac{\pi k}{2\alpha} \right) \right) \frac{1}{\sin\left(\frac{\pi k}{2\alpha}\right)} \\
 \forall (x, y) &= \sum_{k=1}^{\infty} \frac{2V_1 \left( 1 - (-1)^k \right)}{\alpha} \sin\left(\frac{\pi k}{2\alpha} x\right) \sin\left(\frac{\pi k}{2\alpha} y\right) \left( \frac{1 - \cos\left(\frac{\pi k}{2\alpha} x\right)}{\sin\left(\frac{\pi k}{2\alpha}\right)} \right) + \sin\left(\frac{\pi k}{2\alpha} x\right) \left( \frac{1 - \cos\left(\frac{\pi k}{2\alpha} y\right)}{\sin\left(\frac{\pi k}{2\alpha}\right)} \right)
 \end{aligned}$$

$$\left. \begin{array}{l}
 \text{2. koloninj EH} \quad 2.1.2.2010 \\
 \text{(1)} \quad \vec{H} = \frac{1}{\mu_0} \text{rot} \vec{A} = \frac{1}{\mu_0 \epsilon} \begin{vmatrix} \vec{A} & 0 \\ \frac{\partial}{\partial x} & 0 \\ \frac{\partial}{\partial y} & 0 \\ \frac{\partial}{\partial z} & 0 \end{vmatrix} \\
 \text{rot} \vec{H} = \vec{j} + \epsilon \text{c} \vec{E} \\
 \text{rot} \vec{H} = \vec{0} \quad \vec{H} = \frac{1}{\mu_0 \epsilon} \begin{vmatrix} \vec{A} & 0 \\ \frac{\partial}{\partial x} & 0 \\ \frac{\partial}{\partial y} & 0 \\ \frac{\partial}{\partial z} & 0 \end{vmatrix} \\
 \vec{E} = \frac{1}{\mu_0 \epsilon} \text{rot} \vec{H} = \frac{1}{\mu_0 \epsilon} \frac{1}{\vec{A}} \begin{vmatrix} \vec{A} & \vec{j} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial x} \end{vmatrix} \\
 \vec{E} = \vec{A} \zeta \frac{\vec{A} \cdot \vec{j}}{\mu_0 \epsilon \vec{A}^2} + \vec{A}_z \frac{e^{-j k z}}{\vec{A}^2} + \vec{A}_z \frac{j A_0 e^{j k z}}{\vec{A}^2}
 \end{array} \right\} \quad \boxed{(4) \quad \frac{H_1}{H_0} = \frac{B_0 A}{2\pi d} \ln \frac{d + \frac{a}{2}}{d - \frac{a}{2}}}$$

$$\begin{aligned}
 & \text{③ } H_1 = \frac{\mu_0 \alpha}{2\pi} \ln \frac{d + \frac{\alpha}{2}}{d - \frac{\alpha}{2}} \\
 & H_2 = \frac{\mu_0}{3} \int_A B d\vec{A} \\
 & H = \frac{1}{I} \int_A B d\vec{A} \\
 & A_2 = \frac{a_2^2}{2} \\
 & a_2^2 = \frac{\alpha^2}{3} \\
 & a_2 = \frac{\alpha}{\sqrt{3}} = 2,30 \text{ mm} \\
 & \text{as more remaining} \\
 & \text{in } 1,7 \text{ mm}
 \end{aligned}$$

$$\text{rot } \vec{H} = \frac{\partial B}{\partial x} + i \omega \epsilon_0 E$$

$$\text{rot } \vec{H} = \frac{1}{\epsilon} \begin{vmatrix} \vec{A}_y & \vec{A}_x \\ \frac{\partial}{\partial y} & \frac{\partial}{\partial x} \end{vmatrix} = -\vec{A}_y \frac{\frac{\partial \vec{E}_0}{\partial x} \sin\left(\frac{2\pi}{L} z\right)}{\frac{\partial \vec{E}_0}{\partial x}} - \vec{A}_x \frac{\frac{\partial \vec{E}_0}{\partial y} \cos\left(\frac{2\pi}{L} z\right)}{\frac{\partial \vec{E}_0}{\partial y}} = -\vec{A}_y \frac{\frac{\partial \vec{E}_0}{\partial x} \sin\left(\frac{2\pi}{L} z\right)}{\frac{\partial \vec{E}_0}{\partial x}} + \vec{A}_x \frac{\frac{\partial \vec{E}_0}{\partial y} \sin\left(\frac{2\pi}{L} z\right)}{\frac{\partial \vec{E}_0}{\partial y}} = \omega \vec{e}_z$$

$$\omega = \sqrt{\frac{1}{\epsilon_1 \epsilon_2}} = \frac{\omega_0 \sqrt{\pi}}{2 \sqrt{\epsilon_1}} = \frac{\omega_0}{2 \sqrt{\epsilon_1}} = \frac{3 \cdot 10^9 \text{ rad/s}}{5 \cdot 10^{-2} \text{ m} \sqrt{\epsilon_2}} = 1,2 \text{ GHz}$$

# ELEKTRO MAGNETIKA

02.04.2010

$$\textcircled{1} \quad \vec{A} = \vec{A}_2 Cg e^{-\alpha g} \sin 3\varphi \quad (\omega=0)$$

$$\vec{H} = ? \quad \vec{E} = ? \quad I = ?$$

$$H = \frac{1}{\mu} \text{rot} \vec{A} = \frac{1}{\mu g} \begin{vmatrix} \vec{A}_2 & \vec{g} & \vec{e}_z \\ \frac{\partial}{\partial x} & 0 & \frac{\partial}{\partial z} \\ \frac{\partial}{\partial y} & \frac{\partial}{\partial z} & 0 \end{vmatrix} =$$

$$= \vec{A}_2 \frac{C}{g \mu} e^{\alpha g} 3 \cos 3\varphi + \vec{A}_2 \frac{C}{\mu} (g \varphi - 1) e^{-\alpha g} \sin 3\varphi$$

$$\vec{g} = \text{rot} \vec{H} = \frac{1}{g} \begin{vmatrix} \vec{A}_2 & \vec{g} & \vec{e}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial}{\partial y} & \frac{\partial}{\partial z} & 0 \end{vmatrix} = \vec{A}_2 \frac{C}{\mu g} (8 + 2 \cos - 4 \varphi) \vec{e}^{\alpha g}$$

$$\vec{E} = 0 \quad \text{in singularitate planar}$$

$$I = \vec{g} \vec{H} \cdot d\vec{s} = 0 \quad (\text{zazdroj } \sin 3\varphi)$$

obd. osi z

$$\textcircled{2} \quad \vec{E} = -\vec{A}_1 \cdot 1000 \text{ V/m} \quad (\omega=0)$$

$$\vec{H} = ? \quad \vec{E} = ? \quad I = ?$$

$$a=1 \text{ cm} \quad b=1.5 \text{ cm}$$

$$V_2 = A_2 g \sin \varphi + B_2 g^{-1} \sin \varphi$$

$$V_\varepsilon = A_\varepsilon g \sin \varphi + B_\varepsilon g^{-1} \sin \varphi$$

$$V_N = A_N g \sin \varphi$$

$$A_2 = 1000 \text{ V/m} \quad @ \varphi \rightarrow \infty$$

$$\vec{E} = -\vec{A}_1 (A - \frac{B}{g}) \sin \varphi - \vec{A}_1 (A + \frac{B}{g}) \cos \varphi$$

$$\textcircled{3} \quad \vec{E} = A_\varepsilon + \frac{B_\varepsilon}{g^2} \varepsilon \quad (\omega=0)$$

$$D_{\varepsilon N} = D_{N\varepsilon} \rightarrow (A_\varepsilon - \frac{B_\varepsilon}{g^2}) \varepsilon_r = A_N \quad A_\varepsilon (1 - \varepsilon_r) + \frac{B_\varepsilon}{g^2} (\varepsilon_r + 1) = 0$$

$$A_\varepsilon = \frac{\varepsilon_r + 1}{\varepsilon_r - 1} \frac{B_\varepsilon}{g^2}$$

$$D_{2N} = D_{N2} \rightarrow A_2 + \frac{B_2}{g^2} = A_\varepsilon + \frac{B_\varepsilon}{g^2} \quad 2A_2 = A_\varepsilon (\varepsilon_r + 1) + \frac{B_\varepsilon}{g^2} (1 - \varepsilon_r)$$

$$2A_2 = \frac{(\varepsilon_r + 1)^2}{\varepsilon_r - 1} \frac{B_\varepsilon}{g^2} + \frac{B_\varepsilon}{g^2} (1 - \varepsilon_r) \rightarrow B_\varepsilon = \frac{2A_2 (\varepsilon_r - 1)}{(\varepsilon_r + 1)^2 g^2 - (\varepsilon_r - 1)^2 g^2}$$

$$B_\varepsilon = \frac{2 \cdot 1000 \text{ V/m} \cdot (2-1)}{(2+1)^2 \cdot 10^4 \text{ m}^{-2} - (2-1)^2 \cdot (2)^2 \cdot 10^4 \text{ m}^{-2}} = 0.02338 \text{ V/m}$$

$$A_\varepsilon = \frac{2+1}{2-1} \frac{B_\varepsilon}{g^2} = 401.3 \text{ V/m}$$

$$A_N = A_\varepsilon + \frac{B_\varepsilon}{g^2} = 935.1 \text{ V/m} \quad \vec{E}_N = -\vec{A}_1 \cdot 935.1 \text{ V/m}$$

$$\Delta f = f_{011} - f_{012} \quad l \gg a, b$$

$$\Delta f = f_{012} - f_{011} \quad l = ?$$

$$\Delta f \approx \frac{c_0}{2} \left( \sqrt{\left( \frac{1}{b} \right)^2 + \left( \frac{2}{l} \right)^2} - \sqrt{\left( \frac{1}{b} \right)^2 + \left( \frac{1}{l} \right)^2} \right)$$

$$\Delta f \approx \frac{c_0}{2} \left( \frac{1}{b} \left( 1 + \frac{1}{2} \left( \frac{2b}{l} \right)^2 \right) - \frac{1}{b} \left( 1 + \frac{1}{2} \left( \frac{b}{l} \right)^2 \right) \right)$$

$$\frac{2 \Delta f}{c_0} \approx \frac{1}{2} \left( \frac{4b}{l^2} - \frac{b}{l^2} \right) = \frac{3b}{2l^2}$$

$$l \approx \sqrt{\frac{3b c_0}{4 \Delta f}} = \underline{\underline{3m}}$$

$$\textcircled{4} \quad a=20 \text{ mm} \quad b=40 \text{ mm}$$

$$\Delta f_r = 1 \text{ MHz}$$

$$f_{011} = \frac{c_0}{2} \sqrt{\left( \frac{1}{b} \right)^2 + \left( \frac{1}{l} \right)^2}$$

$$f_{012} = \frac{c_0}{2} \sqrt{\left( \frac{1}{b} \right)^2 + \left( \frac{2}{l} \right)^2}$$

$$\Delta f = f_{012} - f_{011}$$

$$\Delta f = \frac{c_0}{2} \left( \sqrt{\left( \frac{1}{b} \right)^2 + \left( \frac{2}{l} \right)^2} - \sqrt{\left( \frac{1}{b} \right)^2 + \left( \frac{1}{l} \right)^2} \right)$$

$$\Delta f \approx \frac{c_0}{2} \left( \frac{1}{b} \left( 1 + \frac{1}{2} \left( \frac{2b}{l} \right)^2 \right) - \frac{1}{b} \left( 1 + \frac{1}{2} \left( \frac{b}{l} \right)^2 \right) \right)$$

$$\frac{2 \Delta f}{c_0} \approx \frac{1}{2} \left( \frac{4b}{l^2} - \frac{b}{l^2} \right) = \frac{3b}{2l^2}$$

$$l \approx \sqrt{\frac{3b c_0}{4 \Delta f}} = \underline{\underline{3m}}$$

$$\textcircled{5} \quad P_V = ?$$

$$R = ?$$

$$P = \vec{S} \cdot \vec{A} = \vec{S} \cdot (-\vec{A}_2) \text{ und } =$$

$$= 6 \cdot 10^4 \text{ W/m}^2 \cdot 20 \cdot 10^{-6} \text{ m}^2 = \underline{\underline{1.2 \text{ N}}}$$

$$R = \frac{U}{I} = \frac{Ed}{HW} = \frac{3000 \text{ V/m} \cdot 2 \cdot 10^{-3} \text{ m}}{20 \text{ A/mm} \cdot 10^{-2} \text{ m}} = \frac{6 \text{ V}}{0.2 \text{ A}} = \underline{\underline{30 \Omega}}$$

$$\frac{P_0}{P_V} = \frac{|1|^2}{|1|^2} = 1 \quad |1|^2 < 0.01 \rightarrow R_{max} = \underline{\underline{30 \Omega}}$$

$$\mu_r = \frac{E_U}{E_V} \quad \frac{E_U}{E_V} = \Gamma \quad \frac{E_U}{Z_0} = \frac{E_L}{Z_0} = \Gamma$$

$$\mu_r = \frac{1}{2} (E_U + E_V)$$

# ELEKTRO MAGNETIKA

01.07.2010

$$① g(r, \theta, \phi) = C e^{-\frac{r}{\alpha}}$$

$$Q = 10^{-8} \text{ As}; \quad w = 0; \quad \alpha = 1 \text{ m}, \epsilon_0, \mu_0$$

$$C = ?$$

$$Q = \iiint_{0}^{\infty} \rho r^2 \sin \theta dr d\theta d\phi = 4\pi \int_0^\infty r^2 dr =$$

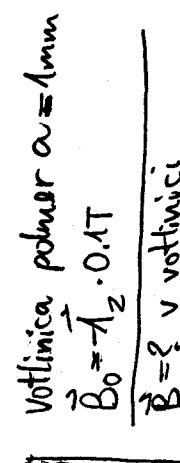
$$= 4\pi C \left[ e^{-\frac{r}{\alpha}} - \int_0^\infty e^{-\frac{r}{\alpha}} dr \right] + \left[ 2ar e^{-\frac{r}{\alpha}} \right]_0^\infty = 4\pi C \left[ 0 - 2a^2 r e^{-\frac{r}{\alpha}} \right]_0^\infty + \left[ 2ar^2 e^{-\frac{r}{\alpha}} \right]_0^\infty =$$

$$= 4\pi C \left[ 0 - 0 - 2a^2 e^{-\frac{r}{\alpha}} \right]_0^\infty = 8\pi C a^3$$

$$C = \frac{Q}{8\pi a^3} = \frac{10^4 \text{ As}}{8\pi (1 \text{ m})^3} = 3.98 \cdot 10^{-10} \frac{\text{As}}{\text{m}^3}$$

$$\vec{B} = -\vec{r}_z \mu_0 C = \frac{2 \vec{B}_0}{\mu_0 + 1} = -\vec{r}_z \cdot 18.2 \text{ mT}$$

③

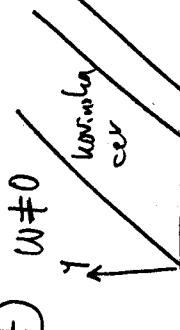


$$w = 0 \quad \text{Votlinica polmer } \alpha = 1 \text{ mm}$$

$$\vec{B}_0 = \vec{r}_z \cdot 0.1 \text{ T}$$

$$\vec{B} = ? \quad \text{v votlinici}$$

④



$$w \neq 0$$

$$\text{korunka cov}$$

$$\epsilon_0, \mu_0$$

$$\alpha = 3 \text{ cm}; \quad \lambda \rightarrow \infty$$

$$b = 1 \text{ cm}; \quad f = 7.5 \text{ GHz}$$

$$|E_{\max}| = 10 \text{ V/m}$$

$$\vec{E}(x, y, z) = ?$$

$$\lambda_0 = \frac{\alpha}{f} = 4 \text{ cm}$$

$$\alpha > \lambda_0 / 2 = 2 \text{ cm} > b$$

$$r \neq TE10_1$$

$$k = \frac{2\pi}{\lambda}$$

$$\vec{E} = \vec{r}_y C \sin\left(\frac{\pi}{\alpha} x\right) e^{\pm j k z}$$

$$C = 10 \text{ V/m} \cdot 0.19; \quad (b = \sqrt{k^2 - (\frac{\pi}{\alpha})^2} = 1.17 \text{ rad/cm})$$

$$\vec{E} = \vec{r}_y 10 \text{ V/m} e^{j\varphi} \sin\left(\frac{\pi}{\alpha} x\right) e^{\pm j (1.17 \text{ rad/cm}) z}$$

⑤  $\epsilon_0, \mu_0, w \neq 0$

$$\vec{S} = \vec{r}_x \vec{A} = |\vec{S}| \pi r^2 = 4398 \text{ W}$$

$$\vec{F} dt = \vec{r}_x C_0 = \vec{r}_x \cdot 3 \cdot 10^8 \text{ m/s}$$

$$N = mc^2; \quad P = \frac{dN}{dt} = c^2 \frac{dW}{dt}$$

$$\vec{F} = \vec{N} \frac{P}{c^2} = \vec{r}_x \cdot 1.466 \cdot 10^{-5} \text{ N}$$

$$\vec{F} = ?$$

$$\text{Chra kružka}$$

$$r = 0.5 \text{ pm}$$

$$r = 1 \text{ m}$$

⑤

$$\vec{E} \perp \vec{B}$$

$$\vec{r} = 0 \text{ km}$$

$$\vec{r} = ?$$

$$\vec{r} = 0 \text{ km}$$

$$\vec{r} = 0 \text{ km}$$

$$\vec{r} = 0 \text{ km}$$

$$\vec{E} \perp \vec{B}$$

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$$\vec{r} = 0 \text{ km}$$

$$\vec{E} \perp \vec{B}$$

$$\vec{r} = 0 \text{ km}$$

&lt;math display

# Rešitev 1. kolokvija iz ELEKTROMAGNETIKE 23.11.2010

Rešitve

$$W = \frac{1}{2} \int_V \rho V dV = \frac{1}{2} \int_0^{R_0} \int_0^{\pi/2} \int_0^r \rho V r^2 \sin\theta dr d\theta d\phi$$

$$V_N = -\frac{\rho}{2\epsilon_0} \left( R_0^2 - \frac{r^2}{3} \right) \text{ smo izračunali na vajah}$$

$$W = \frac{\pi \rho^2}{2\epsilon_0} \int_0^{\pi/2} \int_0^{R_0} \left( R_0^2 - \frac{r^2}{3} \right) r^2 \sin\theta dr d\theta$$

$$W = \frac{\pi \rho^2}{2\epsilon_0} \int_0^{\pi/2} \int_0^{R_0} \left( R_0^2 r^2 - \frac{r^4}{3} \right) dr [-\cos\theta]_0^{\pi/2}$$

$$W = \frac{\pi \rho^2}{\epsilon_0} \left[ R_0^2 \frac{r^3}{3} - \frac{r^5}{3 \cdot 5} \right]_0^{R_0} = \frac{\pi \rho^2}{\epsilon_0} \frac{4}{15} R_0^5$$

$$\rho = \frac{4}{3} \frac{e_0}{\pi \cdot R_0^3}$$

$$W = \frac{\pi}{\epsilon_0} \left( \frac{e_0}{\frac{4}{3} \pi R_0^3} \right)^2 \frac{4}{15} R_0^5 = \frac{3e_0^2}{20\pi\epsilon_0 R_0} = m_e c_0^2$$

$$R_0 = \frac{3e_0^2}{20\pi\epsilon_0 m_e c_0^2} = \frac{3(1.6 \cdot 10^{-19} \text{ As})^2}{20\pi \cdot 8.85 \cdot 10^{-12} \frac{\text{As}}{\text{Vm}} \cdot 9.1 \cdot 10^{-31} \text{ kg} (3 \cdot 10^8 \text{ m/s})^2} = 1.7 \cdot 10^{-15} \text{ m}$$

$\boxed{\begin{array}{l} r > R \\ \frac{1}{r^2} \frac{\partial}{\partial r} \left( \frac{\partial V_Z}{\partial r} r^2 \right) = 0 \\ \frac{\partial}{\partial r} \left( \frac{\partial V_Z}{\partial r} r^2 \right) = 0 \quad | \int dr \\ \frac{\partial V_Z}{\partial r} r^2 = C_1 \\ \frac{\partial V_Z}{\partial r} = \frac{C_1}{r^2} \quad | \int dr \\ V_Z = -\frac{C_1}{r} + C_2 \\ V_Z = -\frac{C_1}{12 \cdot \epsilon_0} - \frac{C_3}{r} + C_4 \end{array}}$

$C_3 = 0$ , ker potencial v središču ni neskončan

$\bar{E}_N = -\nabla V_N = \bar{I} r \frac{k \cdot r^2}{4 \cdot \epsilon_0}$

$\bar{E}_Z = -\nabla V_Z = -\bar{I} r \frac{C_1}{r^2}$

$$\boxed{R = R} \quad \bar{E}_Z = \bar{E}_N \Leftrightarrow -\bar{I} r \frac{C_1}{R^2} = \bar{I} r \frac{k \cdot R^2}{4 \cdot \epsilon_0} \quad \Leftrightarrow \quad C_1 = -\frac{k \cdot R^4}{4 \cdot \epsilon_0}$$

$$V_Z = \frac{k \cdot R^4}{4 \cdot \epsilon_0 \cdot r}$$

$$\boxed{\begin{array}{c} \bar{B} = \nabla \times \bar{A} = \frac{\partial}{\partial x} \frac{\bar{I}_y}{\partial y} - \frac{\mu_0 I}{4\pi} \left( \frac{x^2+y^2}{\alpha} \right) \\ \bar{B} = \bar{I}_x \left[ \frac{\partial}{\partial y} \left( -\frac{\mu_0 I}{4\pi} \ln \left( \frac{x^2+y^2}{\alpha} \right) \right) \right] - \bar{I}_y \left[ \frac{\partial}{\partial x} \left( -\frac{\mu_0 I}{4\pi} \ln \left( \frac{x^2+y^2}{\alpha} \right) \right) \right] \end{array}}$$

$$\bar{B} = \frac{\mu_0 I}{4\pi} \left[ -\bar{I}_x \frac{2y}{x^2+y^2} + \bar{I}_y \frac{2x}{x^2+y^2} \right]$$

$$\bar{B} = \frac{\mu_0 I}{4\pi} \left[ -\bar{I}_x \frac{2y}{\rho^2} + \bar{I}_y \frac{2x}{\rho^2} \right]$$

$$\bar{B} = \frac{\mu_0 I}{2\pi\rho^2} \left[ -\bar{I}_x y + \bar{I}_y x \right]$$

$$V = \int_1^r \bar{E} \cdot d\bar{r}$$

$$V = \int_1^r \frac{q}{2\pi\epsilon_0 \epsilon_r r} dr = \frac{q}{2\pi\epsilon_0 \epsilon_r} \cdot \ln \frac{r_2}{r_1}$$

$$C = \frac{Q}{V} = \frac{qL}{\frac{q}{2\pi\epsilon_0 \epsilon_r} \cdot \ln \frac{r_2}{r_1}} = \frac{2\pi\epsilon_0 \epsilon_r L}{\ln \frac{r_2}{r_1}} = \frac{2\pi \cdot 8.85 \cdot 10^{-12} \frac{\text{As}}{\text{Vm}}}{\ln \frac{13.6 \text{ mm}}{5 \text{ mm}}} = 1.11 \text{ nF}$$

Vaje iz teorije elektromagnetike, str. 86, vaja 92.

2. Zadanie: EH 2h. 1.2011

$$\text{① } \vec{H} = -\frac{1}{\delta \omega \mu_0} \nabla \times \vec{E} = -\frac{1}{\delta \omega \mu_0} \frac{1}{V^2 \sin \theta} \begin{vmatrix} \vec{r}_r & \vec{r} \cdot \vec{\lambda}_\theta & V \sin \theta \lambda_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & 0 & V \cdot 0 \end{vmatrix} = \frac{1}{\omega \mu_0} \frac{1}{V^2 \sin \theta} \begin{vmatrix} \vec{r}_r & \vec{r} \cdot \vec{\lambda}_\theta & V \sin \theta \lambda_\phi \\ \vec{E}_0 \frac{e^{-jkr}}{V \sin \theta} & 0 & \vec{E}_0 \frac{e^{-jkr}}{V \sin \theta} \\ 0 & 0 & V \cdot 0 \end{vmatrix} = \frac{1}{\omega \mu_0} \frac{1}{V^2 \sin \theta} \frac{e^{-jkr}}{V \sin \theta} \vec{E}_0 = \frac{1}{\omega \mu_0} \frac{1}{V^2 \sin \theta} \frac{e^{-jkr}}{V \sin \theta} \vec{E}_0$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} \begin{vmatrix} \vec{r}_r & \vec{r}_\theta & \vec{r}_\phi \\ 0 & 0 & \vec{E}_0 \frac{e^{-jkr}}{V \sin \theta} \\ 0 & -\frac{1}{2} \vec{E}_0 \frac{e^{-jkr}}{V \sin \theta} & 0 \end{vmatrix} = \frac{1}{2} \frac{\vec{E}_0 \vec{E}_0^*}{2 \vec{E}_0 (V \sin \theta)^2} = 0$$

$$\text{③ } \vec{V}_{m_0} = \vec{V}_0 \frac{(\mu_0 I_0 \alpha^2)}{4 \pi} \frac{\sin \theta}{r^2} \quad \theta = \frac{\pi}{2} \Rightarrow \sin \theta = 1$$

$$H = \frac{1}{I_0 \alpha} \vec{V}_{m_0} d\vec{z}_0 = \frac{1}{I_0} \int_0^{2\pi} \frac{\mu_0 I_0 \alpha^2}{4 \pi} \cdot \frac{1}{r^2} \vec{V}_0 d\phi = \frac{\mu_0 \alpha^2}{4 \pi} \cdot \frac{1}{r^2} \cdot 2\pi = \frac{\mu_0 \alpha^2}{2r}$$

$$\text{⑤ } f_{1, \text{min}} = \frac{\omega_0}{2} \sqrt{\left(\frac{L}{\alpha}\right)^2 + \left(\frac{m}{b}\right)^2 + \left(\frac{n}{c}\right)^2}$$

$$f_{1,0,1} = -\frac{\omega_0}{2} \sqrt{\left(\frac{1}{\alpha}\right)^2 + \left(\frac{1}{c}\right)^2} = 86 \text{ Hz}$$

$$f_{1,0,1} = \frac{\omega_0}{2} \sqrt{\left(\frac{1}{\alpha}\right)^2 + \left(\frac{2}{\alpha}\right)^2 + \left(\frac{1}{c}\right)^2} = 106 \text{ Hz}$$

$$\frac{1}{\alpha^2} + \frac{1}{c^2} = 8$$

$$\frac{5}{\alpha^2} + \frac{1}{c^2} = 10$$

$$Q = 5 \text{ cm}$$

$$C = 2 \text{ cm}$$

$$\text{② } k = \frac{\omega}{\kappa} = \frac{10^7 \text{ rad/s}}{2 \cdot 10^3 \text{ m/s}} = 0.05 \text{ rad/m}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} \vec{E}_0 \frac{e^{-jkr}}{V \sin \theta} \vec{E}_0 \frac{e^{-jkr}}{V \sin \theta} = \vec{H}_0 \vec{E}_0 \frac{e^{-j2kr}}{V^2 \sin^2 \theta}$$

$$\lambda = \frac{2\pi}{k} = 125.66 \text{ m}$$

$$E_r = \frac{1}{2 \epsilon_0 \epsilon_0} = 2.25 \quad (\mu_r = \frac{2}{\epsilon_0 \epsilon_0} = 1)$$

$$\text{④ } \vec{J} = \vec{rot} \vec{H} - j\omega \epsilon_0 \vec{E} = 0$$

$$\vec{H} = -\frac{1}{j\omega \mu_0} \vec{rot} \vec{E} = -\frac{1}{j\omega \mu_0} \begin{vmatrix} \vec{r}_x & \vec{r}_y & \vec{r}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & 0 \end{vmatrix} =$$

$$\vec{H} = -\frac{1}{j\omega \mu_0} \left[ \vec{r}_z \left( -j\omega \mu_0 \frac{\alpha}{\pi} \right) \vec{H}_0 \frac{\alpha}{\pi} \cos\left(\frac{\pi}{\alpha} x\right) \vec{e}^{j\beta z} + \vec{r}_x \left( j\omega \mu_0 \frac{\alpha}{\pi} \right) \vec{H}_0 \sin\left(\frac{\pi}{\alpha} x\right) \left( -j\beta \right) \vec{e}^{j\beta z} \right] =$$

$$\vec{H} = \vec{r}_x j\omega \frac{\alpha}{\pi} \vec{H}_0 \sin\left(\frac{\pi}{\alpha} x\right) \vec{e}^{j\beta z} + \vec{r}_z \vec{H}_0 \cos\left(\frac{\pi}{\alpha} x\right) \vec{e}^{-j\beta z}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} \begin{vmatrix} \vec{r}_x & \vec{r}_y & \vec{r}_z \\ \vec{E}_0 \frac{e^{-jkr}}{V \sin \theta} & 0 & 0 \\ 0 & -\frac{1}{2} \vec{E}_0 \frac{e^{-jkr}}{V \sin \theta} & 0 \end{vmatrix} =$$

$$\vec{S} = \frac{1}{2} \frac{\vec{r}_x \vec{r}_z}{\alpha} = 0$$

$$\vec{S} = \frac{1}{2} \frac{\vec{r}_x \vec{r}_z}{\alpha} \left[ -j\omega \mu_0 \frac{\alpha}{\pi} \vec{H}_0 \sin\left(\frac{\pi}{\alpha} x\right) \vec{e}^{j\beta z} \right] =$$

$$\vec{P} = \int_A \vec{S} \cdot d\vec{A} = \int_0^a \int_0^a \int_0^a \frac{1}{2} \omega \mu_0 \left( \frac{\alpha}{\pi} \right)^2 H_0 H_0^* \beta \sin^2\left(\frac{\pi}{\alpha} x\right) dx dy dz$$

$$P = \frac{1}{2} \omega \mu_0 \left( \frac{\alpha}{\pi} \right)^2 H_0 H_0^* \beta \frac{\alpha}{2} \alpha = \frac{4 \omega \mu_0 H_0^2 \alpha^2}{4 \pi} \omega \mu_0 \left( \frac{\alpha}{\pi} \right)^2 \beta$$

$$\int_0^a \sin^2 \alpha x = \frac{x}{2} + \frac{\sin 2ax}{4a}$$

$$\alpha \int_0^a \sin^2 \left( \frac{\pi}{\alpha} x \right) dx = \frac{\alpha}{2}$$

$$\textcircled{1} \quad (r, \theta, \phi) \quad \vec{A} = \vec{A}_\theta r \sin \theta \hat{r}, \vec{B} = \vec{A}_\phi \hat{C}$$

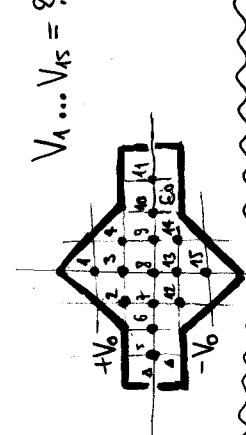
$$\text{grad}(\vec{A} \cdot \text{rot} \vec{B} - \vec{B} \cdot \text{rot} \vec{A}) = ?$$

$$\vec{A} \cdot \text{rot} \vec{B} - \vec{B} \cdot \text{rot} \vec{A} = \text{div}(\vec{B} \times \vec{A})$$

$$\vec{A} \parallel \vec{B} \rightarrow \vec{A} \times \vec{B} = 0$$

$$\text{grad}(\vec{A} \cdot \text{rot} \vec{B} - \vec{B} \cdot \text{rot} \vec{A}) =$$

$$= \text{grad}(\text{div}(\vec{B} \times \vec{A})) = \text{grad}(\text{div} 0) = 0$$



$$\text{Simetria: } V_5 = V_6 = V_7 = V_8 = V_3 = V_{10} = V_{11} = 0$$

$$4V_1 = 3V_6 + V_3 = V_6 + 4V_2 = 56V_2 - 32V_0 \rightarrow V_2 = \frac{33}{52}V_0$$

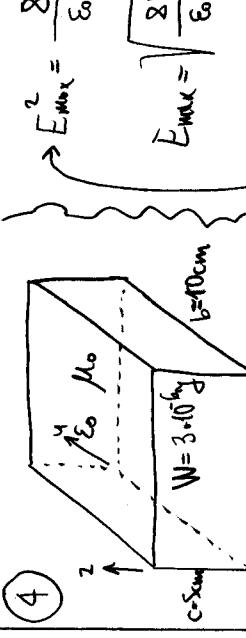
$$4V_2 = 2V_0 + V_3 \rightarrow V_3 = 4V_2 - 2V_0 \rightarrow V_3 = \frac{7}{13}V_0$$

$$4V_3 = V_1 + 2V_2 = 16V_2 - 8V_0 \rightarrow V_1 = 14V_2 - 8V_0$$

$$\rightarrow V_1 = \frac{23}{26}V_0$$

$$V_{12} = V_4 = -V_1 = -\frac{33}{52}V_0$$

$$V_{13} = -V_3 = -\frac{7}{13}V_0 \quad V_{15} = -V_4 = -\frac{23}{26}V_0$$



$$E_{\max}^2 = \frac{8W_0}{\epsilon_0 abc}$$

$$E_{\max} = \sqrt{\frac{8W_0}{\epsilon_0 abc}}$$

$$E_{\max} = 73.7 \text{ kV/m}$$

$$\vec{E}_{\max} = \vec{E}_2 = 73.7 \text{ kV/m}$$

$$\text{TE } 1/10$$

$$f = \frac{c_0}{2} \sqrt{\left(\frac{1}{a}\right)^2 + \left(\frac{1}{b}\right)^2} = 2.12 \text{ GHz}$$

$$\vec{E}(x, y, z) = \int_a^b \int_0^c \int_0^z \epsilon_0 |\vec{E}|^2 dx dy dz = \frac{1}{2} \frac{a}{2} \frac{b}{2} c \epsilon_0 E_{\max}^2$$

$$W_e = \frac{1}{2} \int_a^b \int_0^c \int_0^z \epsilon_0 |\vec{E}|^2 dx dy dz = \frac{1}{2} \frac{a}{2} \frac{b}{2} c \epsilon_0 E_{\max}^2$$

\textcircled{4}

osimoni red  $\vec{E}_{\max} = ?$

$f = ?$

$\vec{E}_1 = ?$

$\vec{E}_2 = ?$

$\vec{E}_3 = ?$

$\vec{E}_4 = ?$

$\vec{E}_5 = ?$

$\vec{E}_6 = ?$

$\vec{E}_7 = ?$

$\vec{E}_8 = ?$

$\vec{E}_9 = ?$

$\vec{E}_{10} = ?$

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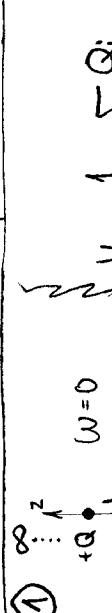
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①   $\omega = 0$   $V = \frac{1}{4\pi\epsilon_0} \sum_i \frac{Q_i}{r_i}$

$\epsilon_0$   $V(\infty) = 0$

$d = 1\text{m}$   $Q = 10^9 \text{ As}$

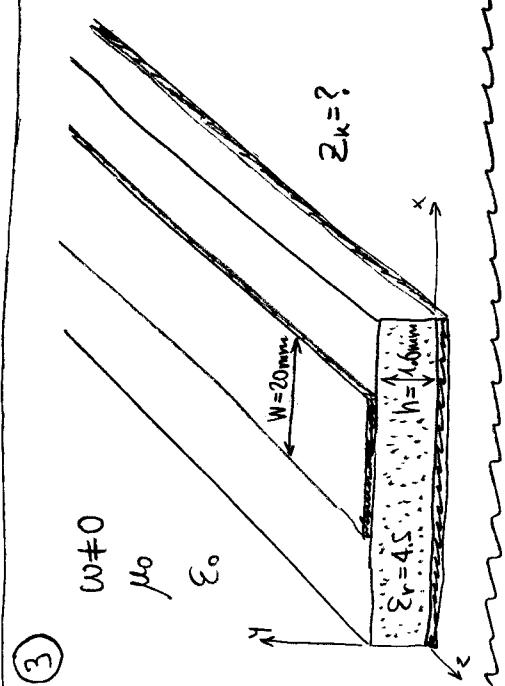
$\omega \neq 0$   $V = \frac{Q}{4\pi\epsilon_0 d} \sum_{i=1}^{\infty} \frac{(-1)^{i+1}}{r_i}$

$V(0) = ?$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \frac{x^5}{5} - \dots$$

$$\ln 2 = 1 - \frac{1}{2} + \frac{1}{3} - \frac{1}{4} + \frac{1}{5} - \dots$$

$$V = \frac{Q}{4\pi\epsilon_0 d} \ln 2 = \frac{10^{-9} \cdot 1 \cdot 0.693}{4\pi \cdot 9 \cdot 10^9 \cdot 1 \cdot 1} = \frac{6.24 \text{ V}}{=}$$



$$\Delta V = \frac{1}{C/2} = \frac{1}{\frac{\mu_0 \epsilon_r}{\epsilon_0} \frac{W}{h}} = \frac{h}{W} \frac{Z_0}{\epsilon_r} = \frac{14.2 \Omega}{=}$$

④ 

$\omega \neq 0$   $\mu_0$   $\epsilon_0$

$V(0) = ?$

$Z = \vec{S} = \vec{H}_r \cdot 1 \text{ kW/m}^2$

$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \vec{E}_{\text{eff}} \times \vec{H}_{\text{eff}}^*$

$|\vec{E}| = |\vec{H}| Z_0$   $|\vec{E}_{\text{eff}}| = |\vec{H}_{\text{eff}}| Z_0$   $Z_0 = \sqrt{\frac{\mu_0}{\epsilon_0}}$

$|\vec{S}| = \frac{|\vec{E}|^2}{2 Z_0} = \frac{|\vec{E}_{\text{eff}}|^2}{Z_0} = \frac{|\vec{H}|^2 Z_0}{2} = |\vec{H}_{\text{eff}}|^2 Z_0$

$|\vec{E}_{\text{eff}}| = \sqrt{|\vec{S}| Z_0} = \frac{6.14 \text{ Veff}}{=}$

$|\vec{H}_{\text{eff}}| = \sqrt{\frac{|\vec{S}|}{Z_0}} = \frac{1.63 \text{ Aeff}}{=}$

$N = 20 \text{ mm} \gg h = 1.6 \text{ mm} \rightarrow$  zanemarim strenganicu

$C/k = \epsilon_0 \epsilon_r \frac{W}{h}$

$L/k = \mu_0 \frac{h}{W}$

$$\frac{h}{\epsilon_0 \epsilon_r \frac{W}{h}} = \frac{h}{W} \frac{Z_0}{\epsilon_r} = \frac{h}{W} \frac{14.2 \Omega}{\epsilon_r} = \frac{14.2 \Omega}{=}$$

② 

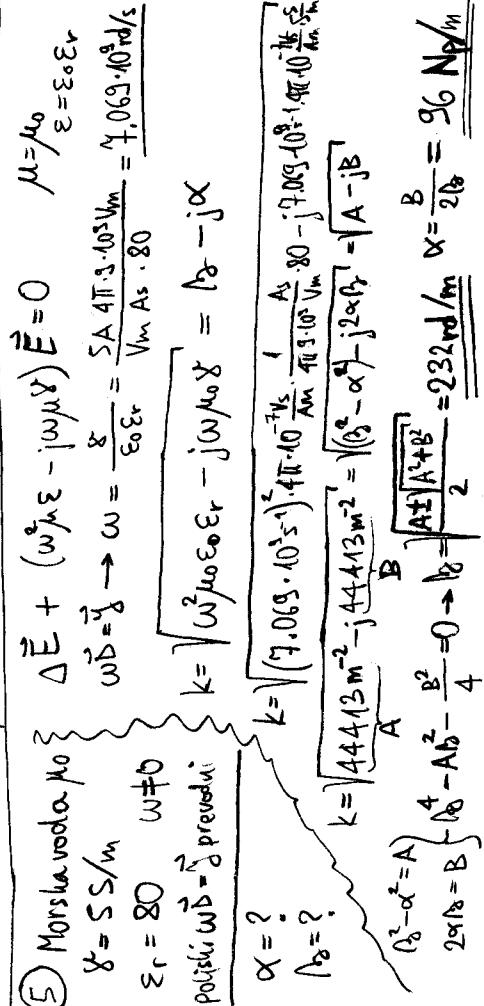
$\omega = 0$   $\epsilon_0$

$\frac{\partial^2 V}{\partial z^2} = 0 \rightarrow V = C_1 z + C_2$

$V_2 = -10V$   $V_1 = 10V$   $\frac{\partial V}{\partial z} = 0 \rightarrow$

$+10V @ x > 0$   $-10V @ x < 0$

$\frac{\partial^2 V}{\partial z^2} = 0 \rightarrow V(x, y=0) = ?$

⑤ 

$\mu = \mu_0$   $\epsilon = \epsilon_0 \epsilon_r$

$\gamma = SS/m$

$\Sigma_r = 80$   $W \neq 0$

polistri  $w \vec{b} = \vec{p}$  preduvi

$k = \sqrt{\mu^2 \mu_0 \epsilon_0 \epsilon_r - j \gamma \mu_0 \gamma} = k_0 - j \alpha$

$k = \sqrt{(\gamma \cdot 0.69 \cdot 10^9)^2 + 4\pi \cdot 10^{-7} \cdot \frac{1}{Am} \cdot \frac{1}{4\pi \cdot 10^9 \cdot 80 - j 4\pi \cdot 9 \cdot 10^9 \cdot 1 \cdot 4\pi \cdot 10^{-7} \cdot \frac{1}{Am} \cdot 80}} = \sqrt{4.069 \cdot 10^9 - j 4\pi \cdot 9 \cdot 10^9 \cdot 1 \cdot 4\pi \cdot 10^{-7} \cdot \frac{1}{Am}}$

$\alpha = ?$

$\beta = ?$

$\lambda = ?$

$\lambda = \frac{444.13 \text{ m}^2 - j 444.13 \text{ m}^2}{A} = \frac{(j\alpha - \gamma)^2 - j 2 \alpha \beta}{B}$

$\lambda^2 - \alpha^2 = A$

$2\pi/\lambda = B$

$\frac{A^2 + B^2}{B} = 0 \rightarrow B = \frac{A^2}{B}$

$\alpha = \frac{B}{2A} = \frac{96}{24} = \underline{\underline{4 \text{ rad/m}}}$

# ELEKTROMAGNETIKA

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$$\begin{aligned} \textcircled{1} \quad & \frac{\partial}{\partial \theta} = 0 \quad V(r, \theta, \phi) = \begin{cases} C_0 \cos \theta @ r < a \\ C \frac{a^2}{r^2} \cos \theta @ r > a \end{cases} \\ & \epsilon = \epsilon_0 \quad \omega = 0 \end{aligned}$$

$$\begin{aligned} S = \operatorname{div} (-\epsilon \mathbf{E} \cdot dV) &= -\epsilon \left[ \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial V}{\partial \theta} \right) \right] \\ r < a \rightarrow \varrho = 0 & \quad D_r = \vec{H}_r \cdot (-\epsilon \mathbf{grad} V) = -\epsilon \frac{\partial V}{\partial r} \\ r > a \rightarrow \varrho = 0 & \quad |\vec{B}| = \mu_0 |\vec{H}| = 4\pi \cdot 10^{-7} \frac{V_s}{A \cdot m} \cdot 2000 A/m = 0.8 T \cdot T \\ Q(r=a) = \vec{H}_r (\vec{D}_z - \vec{D}_N) &= \left( \frac{2\epsilon C_0 a^2}{r^3} \cos \theta + \epsilon C \frac{1}{a} \cos \theta \right) = \frac{3\epsilon C_0 \cos \theta}{a} \\ Q(r=0) &= \lim_{r \rightarrow 0} \int_0^r \vec{D}_z \cdot \vec{D}_N \cdot r \sin \theta d\theta = 0 \\ q(\theta=0) &= \lim_{\theta \rightarrow 0} \int_0^\pi \vec{D}_z \cdot \vec{D}_N \cdot r \sin \theta d\theta = \lim_{\theta \rightarrow 0} \int_0^1 \frac{1}{r} \frac{\partial V}{\partial \theta} r \sin \theta d\theta = 0 \\ q(\theta=\pi) &= 0 \end{aligned}$$

$$\begin{aligned} \textcircled{2} \quad & 2r = 1 \text{ cm} \quad \omega = 0 \\ & N = 200 \text{ ovovier} \\ & L = 10 \text{ cm} \Rightarrow N_m = ? \end{aligned}$$

$\vec{H} \cdot d\vec{s} \approx |\vec{H}| \cdot L = IN \rightarrow |\vec{H}| = \frac{IN}{L} = 2000 \text{ A/m}$

$$|\vec{B}| = \mu_0 |\vec{H}| = 4\pi \cdot 10^{-7} \frac{V_s}{A \cdot m} \cdot 2000 A/m = 0.8 T \cdot T$$

$$N_m = \frac{1}{2} \int_{\text{ring}} \vec{H} \cdot \vec{B} d\sigma = \frac{1}{2} |\vec{H}| |\vec{B}| \pi r^2 L =$$

$$= \frac{1}{2} 2000 \text{ A/m} \cdot 0.8 T \cdot T \cdot 10^{-3} \frac{Vs}{m^2} \cdot \pi \cdot (5 \cdot 10^{-3} \text{ m})^2 \cdot 0.1 \text{ m} =$$

$$= 1,974 \cdot 10^{-5} \text{ Vs} = 19,74 \mu \text{Wb}$$

$$\textcircled{3} \quad 2r = 1 \text{ cm} \quad \omega = 0$$

$\vec{H} = \vec{H}_r + \vec{H}_\theta + \vec{H}_z$

$$\vec{H} = \frac{i}{\omega \mu_0} \operatorname{rot} \vec{E} = \begin{vmatrix} \vec{I}_x & \vec{I}_y & \vec{I}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \vec{E}_{\text{ring}} & 0 & 0 \end{vmatrix}$$

$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \vec{I}_z \frac{1}{2} C \sin \theta \vec{J} \frac{1}{2a} \cos \theta = \vec{I}_z (1,33 \text{ kW/m}^2 \text{ inside})$$

$$\vec{H} = \operatorname{rot} \vec{H} - i\omega \vec{C} = \begin{vmatrix} \vec{I}_x & \vec{I}_y & \vec{I}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & 0 \end{vmatrix} - i\omega \vec{C} \cos \theta = 0$$

$$S = \operatorname{div} (\epsilon_0 \vec{E}) = \frac{\partial}{\partial x} (\epsilon_0 C \sin \theta) = 0$$

$$\textcircled{4} \quad \text{HeNe laser} \quad f = 474 \text{ THz} \quad \omega \neq 0$$

$\vec{E} = \vec{E}_x C \sin \theta \vec{k}_z \quad C = 1000 \text{ V/m} \quad k = \omega / \sqrt{\mu_0 \epsilon_0}$

$$\vec{H} = ? \quad \vec{S} = ? \quad \vec{J} = ? \quad \vec{C} = ?$$

$$\vec{H} = \begin{vmatrix} \vec{I}_x & \vec{I}_y & \vec{I}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \vec{E}_0 & 0 & 0 \end{vmatrix} = \sqrt{\frac{\omega C}{\mu_0}} \cos \theta = \sqrt{\frac{\omega C}{\mu_0}} \cos \theta = \vec{I}_y \frac{\omega}{2a} \cos \theta$$

$$\vec{F}_1 = \vec{I}_y j 2,653 \text{ A/m} \cos \theta$$

$$\textcircled{5} \quad \begin{aligned} & \alpha/\ell [\text{dB/m}] = \frac{10}{\ln 10} \cdot \frac{\beta/\ell}{Z_0} = \frac{10}{\ln 10} \cdot \frac{\frac{10 \cdot 10^{10}}{2 \pi f} \left( \frac{1}{2 \pi R_2} + \frac{1}{2 \pi R_1} \right)}{\frac{Z_0}{2 \pi f \epsilon_0} \ln \frac{R_0}{R_2}} = \frac{10 \cdot 10^{10}}{2 \pi f} \left( \frac{1}{2 \pi R_2} + \frac{1}{2 \pi R_1} \right) \\ & \alpha/\ell [\text{dB/m}] = \frac{10}{\ln 10} \cdot \frac{\frac{10 \cdot 10^{10} \cdot 14\pi \cdot 10^{-10} \cdot 10^{-12} \text{ A/Vm}}{2 \cdot 56 \cdot 10^6 \text{ A/Vm}} \left( \frac{1}{0.5 \cdot 10^{-3} \text{ m}} + \frac{1}{1.8 \cdot 10^{-3} \text{ m}} \right)}{\frac{3772}{\ln 1.5} \ln \frac{1.8 \cdot 10^{-3} \text{ m}}{0.5 \cdot 10^{-3} \text{ m}}} = \frac{215 \Omega / \text{m}}{90 \Omega / \text{m}} \\ & \alpha/\ell = 0.236 \text{ dB/m} \\ & \alpha/\ell [\text{dB/m}] = ? \end{aligned}$$

$$\begin{aligned} \textcircled{2} \quad & \begin{aligned} & \sqrt{(S_{1,2})} = \sum_{n=0}^{\infty} C_n S^n \cos n\varphi \quad (\text{symmetria } \pm \varphi) \\ & V(S=0) = C_0 S^0 \cos 0 \cdot \varphi = C_0 \quad \varphi = \frac{\pi}{4} \\ & S = \alpha \rightarrow \sum_{n=0}^{\infty} C_n S^n \cos n\varphi = \sum_{n=0}^{\infty} C_n \cos n\varphi = \frac{V_1 \cos \varphi + V_2 \cos 3\varphi}{2} \end{aligned} \\ & W=0 \rightarrow 2\pi C_0 = \frac{V_1}{2} + \frac{3\pi}{4} V_2 \quad (\text{voltagee zwischen } \Delta V=0) \\ & C_0 = \frac{1}{4} V_1 + \frac{3}{4} V_2 = 2,5V = V(S=0) \\ & \sqrt{(S_{1,2})} = ? \end{aligned}$$

# ELEKTROMAGNETIKA

18.9.2014

<p>1) <math>(r, \theta, \phi)</math> <math>\omega = 0</math> <math>\epsilon = \epsilon_0</math></p> $S(r) = \begin{cases} 0 & ; r < a \\ \frac{C}{r^4} & ; r \geq a \end{cases}$ <p><math>\nabla = ?</math></p> $\frac{\partial}{\partial \theta} = \frac{3}{8\pi} = 0 \rightarrow \vec{D} = \int \frac{1}{r^2} \frac{1}{4\pi r^2} d\Omega \vec{S}(r) 4\pi r^2 dr$ $\vec{D} = \vec{l}_r \cdot \frac{1}{r^2} \int \frac{C}{a^4} r^2 dr = \vec{l}_r \frac{C}{r^2} \left( \frac{1}{r^4} - \frac{1}{a^4} \right) = \vec{l}_r \frac{C}{r^2} \left( \frac{1}{a^2} - \frac{1}{r^2} \right)$ $W = \frac{1}{2} \int \vec{E} \cdot \vec{D} d\Omega r = \frac{1}{2\epsilon_0} \int \left  \vec{D} \right ^2 4\pi r^2 dr = \frac{C^2}{2\epsilon_0 a} \int \frac{1}{r^4} \left( \frac{1}{a^2} - \frac{1}{r^2} \right)^2 4\pi r^2 dr$ $W = \frac{2\pi C^2}{3\epsilon_0 a} \int \left( \frac{1}{a^2} - \frac{2}{ar^2} + \frac{1}{r^2} \right) dr = \frac{2\pi C^2}{\epsilon_0 a} \left( \frac{1}{a^2} - \frac{1}{a^2} + \frac{1}{3a^2} \right)$ $W = \frac{2\pi C^2}{3\epsilon_0 a} = \frac{2\pi \cdot 10^{-12} A^2 S^2 m^2 V_m^2 4\pi \cdot 9 \cdot 10^9}{3 \cdot 1 m^3 As} = 2,37 \cdot 10^{-7} J$	<p>3) <math>\vec{E}_0 = -\vec{l}_z E_0</math></p> $E_0 = 100V/m$ $\nabla(r=0, \theta, \phi) = ?$ $\nabla(r=a, \theta, \phi) = ?$ $\nabla(r \gg a) = ?$ $\nabla(r=a) = 0 \rightarrow B = -Aa^2 = -Ea^3$ $\nabla(r=a, 0) = E_0 \left( r - \frac{a^3}{r^2} \right) \cos \theta$ $\vec{E} = -\vec{l}_z E_0 \left( r - \frac{a^3}{r^2} \right) \cos \theta$ $\vec{E} = -\vec{l}_r E_0 \left( 1 + \frac{2a^3}{r^3} \right) \cos \theta$ $G = \vec{l}_r \cdot \vec{D}(r=a) = \vec{l}_r \cdot \vec{E}(r=a) = -\epsilon_0 E_0 (\lambda + 2) \cos \theta$ $G = -3 \epsilon_0 E_0 \cos \theta = -3 \frac{As}{4\pi \cdot 3 \cdot 10^9 J m} \cos \theta$ $G = 2,65 \cdot 10^{-9} \frac{As}{m^2} \cos \theta = 26,5 \frac{nAs}{m^2} \cos \theta$ $\epsilon_0 \approx \frac{1}{4\pi \cdot 9 \cdot 10^9} \frac{As}{Vm}$	<p>4) <math>a = 10cm</math> <math>b = 7cm</math> <math>c = 5cm</math></p> $\vec{E} = \vec{l}_z E_0 \sin \frac{\pi}{a} x \sin \frac{\pi}{b} y$ $f = ?$ $\vec{s} = ?$ <p>okvirinės voltinės <math>E_0</math></p> $\vec{E} = 0 \rightarrow (\frac{1}{a})^2 + (\frac{1}{b})^2 = k_0^2 \rightarrow f = \frac{c_0}{2} \sqrt{(\frac{1}{a})^2 + (\frac{1}{b})^2}$ $\vec{l}_r \cdot \frac{1}{r^2} \nabla \vec{E} = \frac{\partial}{\partial r} \left[ \frac{\epsilon_0}{\epsilon_r} \frac{\partial \vec{E}}{\partial r} \right] = \frac{i \omega}{\epsilon_0 \mu_0} \left( \frac{\epsilon_0}{\epsilon_r} \frac{\partial \vec{E}}{\partial r} \right)$ $\vec{S} = \frac{1}{2} \vec{E} \times \vec{H}^* = \vec{l}_z E_0 \sin \frac{\pi}{a} x \sin \frac{\pi}{b} y \times \frac{i \omega s}{2\pi c_0} \left( \vec{l}_z \sin \frac{\pi}{b} y \cos \frac{\pi}{a} x - \vec{l}_y \sin \frac{\pi}{a} x \cos \frac{\pi}{b} y \right)$ $\vec{S} = \frac{i \omega B_0 l}{2\pi c_0} \left( -\vec{l}_y \frac{1}{b} \sin \frac{\pi}{a} x \sin \frac{\pi}{b} y \cos \frac{\pi}{a} x - \vec{l}_x \frac{1}{a} \sin \frac{\pi}{a} x \cos \frac{\pi}{b} y \right)$	<p><math>\omega = 100kHz</math></p> <p><math>\sigma = 5m</math></p> <p>Vida <math>\mu = \mu_0</math></p> <p><math>\epsilon = \epsilon_r \epsilon_0</math> <math>\epsilon_r = 80</math></p> <p><math>f = ?</math></p> <p>priduojančios galios <math>G = \frac{1}{2} \frac{\omega \mu_0 \sigma}{\epsilon_0 \epsilon_r}</math></p> <p><math>G = \frac{2}{2\pi \cdot 10^5 \cdot 4\pi \cdot 10^{-7} Vs \cdot 25m^2} = 0,101 S/m \Rightarrow G = 0,101 S/m</math></p>
<p>2) <math>10A = I_1</math></p> <p><math>\mu = \mu_0</math> <math>\omega = 0</math></p> <p><math>\vec{F} = ?</math></p>	<p><math>\vec{d}F = \vec{B} \vec{r} \times \vec{B}</math></p> <p><math>\vec{B}_1(z=0) = -\vec{l}_2 \frac{\mu_0 I_1}{2\pi x}</math></p> <p><math>F = \vec{F}_A + \vec{F}_B + \vec{F}_C + \vec{F}_D = I_2 \vec{l}_1 \alpha \times (-\vec{l}_2) \frac{\mu_0 I_1}{2\pi a} +</math></p> <p><math>+ \int_a^a \vec{l}_2 \vec{l}_1 dx \times \left( -\vec{l}_2 \right) \frac{\mu_0 I_1}{2\pi x} + \int_a^a \left( \vec{l}_2 \right) dx \times \left( \vec{l}_1 \right) \frac{\mu_0 I_1}{2\pi a}</math></p> <p><math>\vec{F}_D = -\vec{F}_D \rightarrow \vec{F}_B + \vec{F}_D = 0</math></p> <p><math>= -\vec{l}_x \frac{\mu_0 I_1 I_2}{2\pi \cdot 2} + \vec{l}_x \frac{\mu_0 I_1 I_2}{2\pi \cdot 2} = -\vec{l}_x \frac{\mu_0 I_1 I_2}{4\pi}</math></p> <p><math>\vec{F} = ?</math></p>	<p><math>f = 100kHz</math></p> <p><math>\sigma = 5m</math></p> <p>Vida <math>\mu = \mu_0</math></p> <p><math>\epsilon = \epsilon_r \epsilon_0</math> <math>\epsilon_r = 80</math></p> <p><math>f = ?</math></p>	