

# Berlekamp–Massey algorithm

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The **Berlekamp–Massey algorithm** is an algorithm that will find the shortest linear feedback shift register (LFSR) for a given binary output sequence. The algorithm will also find the minimal polynomial of a linearly recurrent sequence in an arbitrary field. The field requirement means that the Berlekamp–Massey algorithm requires all non-zero elements to have a multiplicative inverse.<sup>[1]</sup> Reeds and Sloane offer an extension to handle a ring.<sup>[2]</sup>

Elwyn Berlekamp invented an algorithm for decoding Bose–Chaudhuri–Hocquenghem (BCH) codes.<sup>[3][4]</sup> James Massey recognized its application to linear feedback shift registers and simplified the algorithm.<sup>[5][6]</sup> Massey termed the algorithm the LFSR Synthesis Algorithm (Berlekamp Iterative Algorithm),<sup>[7]</sup> but it is now known as the Berlekamp–Massey algorithm.

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## Description of algorithm

The Berlekamp–Massey algorithm is an alternate method to solve the set of linear equations described in Reed–Solomon Peterson decoder, which can be summarized as:

$$S_{i+\nu} + \Lambda_1 S_{i+\nu-1} + \cdots + \Lambda_{\nu-1} S_{i+1} + \Lambda_{\nu} S_i = 0.$$

In the code examples below, C(x) is a potential instance of  $\Lambda(x)$ . The error locator polynomial C(x) for L errors is defined as:

$$C(x) = C_L x^L + C_{L-1} x^{L-1} + \cdots + C_2 x^2 + C_1 x + 1$$

or reversed:

$$C(x) = 1 + C_1 x + C_2 x^2 + \cdots + C_{L-1} x^{L-1} + C_L x^L.$$

The goal of the algorithm is to determine the minimal degree L and C(x) which results in:

$$S_n + C_1 S_{n-1} + \cdots + C_L S_{n-L} = 0$$

for all syndromes,  $n = L$  to  $(N-1)$ .

Algorithm: C(x) is initialized to 1, L is the current number of assumed errors, and initialized to zero. N is the total number of syndromes. n is used as the main iterator and to index the syndromes from 0 to (N-1). B(x) is a copy of the last C(x) since L was updated and initialized to 1. b is a copy of the last discrepancy d (explained below) since L was updated and initialized to 1. m is the number of iterations since L, B(x), and b were updated and initialized to 1.

Each iteration of the algorithm calculates a discrepancy d. At iteration k this would be:

$$d = S_k + C_1 S_{k-1} + \cdots + C_L S_{k-L}.$$

If d is zero, the algorithm assumes that C(x) and L are correct for the moment, increments m, and continues.

If d is not zero, the algorithm adjusts C(x) so that a recalculation of d would be zero:

$$C(x) = C(x) - (d/b) x^m B(x).$$

The  $x^m$  term *shifts* B(x) so it follows the syndromes corresponding to 'b'. If the previous update of L occurred on iteration j, then  $m = k - j$ , and a recalculated discrepancy would be:

$$d = S_k + C_1 S_{k-1} + \cdots - (d/b)(S_j + B_1 S_{j-1} + \cdots).$$

This would change a recalculated discrepancy to:

$$d = d - (d/b)b = d - d = 0.$$

The algorithm also needs to increase  $L$  (number of errors) as needed. If  $L$  equals the actual number of errors, then during the iteration process, the discrepancies will become zero before  $n$  becomes greater than or equal to  $(2L)$ . Otherwise  $L$  is updated and algorithm will update  $B(x)$ ,  $b$ , increase  $L$ , and reset  $m = 1$ . The formula  $L = (n + 1 - L)$  limits  $L$  to the number of available syndromes used to calculate discrepancies, and also handles the case where  $L$  increases by more than 1.

## Code sample

The algorithm from Massey (1969, p. 124).

```

polynomial(field K) s(x) = ... /* coeffs are s_j; output sequence as N-1 degree polynomial */
/* connection polynomial */
polynomial(field K) C(x) = 1; /* coeffs are c_j */
polynomial(field K) B(x) = 1;
int L = 0;
int m = 1;
field K b = 1;
int n;

/* steps 2. and 6. */
for (n = 0; n < N; n++)
{
    /* step 2. calculate discrepancy */
    field K d = s_n + \Sigma_{i=1}^L c_i * s_{n-i};

    if (d == 0)
    {
        /* step 3. discrepancy is zero; annihilation continues */
        m = m + 1;
    }
    else if (2 * L <= n)
    {
        /* step 5. */
        /* temporary copy of C(x) */
        polynomial(field K) T(x) = C(x);

        C(x) = C(x) - d b^{n-1} x^m B(x);
        L = n + 1 - L;
        B(x) = T(x);
        b = d;
        m = 1;
    }
    else
    {
        /* step 4. */
        C(x) = C(x) - d b^{n-1} x^m B(x);
        m = m + 1;
    }
}
return L;

```

## The algorithm for the binary field

The following is the Berlekamp–Massey algorithm specialized for the typical binary finite field  $F_2$  and  $GF(2)$ . The field elements are 0 and 1. The field operations  $+$  and  $-$  are identical and become the exclusive or operation, XOR. The multiplication operator  $*$  becomes the logical AND operation. The division operator reduces to the identity operation (i.e., field division is only defined for dividing by 1, and  $x/1 = x$ ).

- Let  $s_0, s_1, s_2 \cdots s_{n-1}$  be the bits of the stream.
- Initialise two arrays  $b$  and  $c$  each of length  $n$  to be zeroes, except  $b_0 \leftarrow 1, c_0 \leftarrow 1$
- assign  $L \leftarrow 0, m \leftarrow -1$ .
- For  $N = 0$  step 1 while  $N < n$ :
  - Let  $d$  be  $s_N + c_1 s_{N-1} + c_2 s_{N-2} + \cdots + c_L s_{N-L}$ .
  - if  $d = 0$ , then  $c$  is already a polynomial which annihilates the portion of the stream from  $N - L$  to  $N$ .
  - else:
    - Let  $t$  be a copy of  $c$ .
    - Set  $c_{N-m} \leftarrow c_{N-m} \oplus b_0, c_{N-m+1} \leftarrow c_{N-m+1} \oplus b_1, \dots$  up to  $c_{n-1} \leftarrow c_{n-1} \oplus b_{n-N+m-1}$  (where  $\oplus$  is the Exclusive or operator).
    - If  $L \leq \frac{N}{2}$ , set  $L \leftarrow N + 1 - L$ , set  $m \leftarrow N$ , and let  $b \leftarrow t$ ; otherwise leave  $L, m$  and  $b$  alone.

At the end of the algorithm,  $L$  is the length of the minimal LFSR for the stream, and we have  $c_L s_a + c_{L-1} s_{a+1} + c_{L-2} s_{a+2} + \cdots = 0$  for all  $a$ .

## Code sample for the binary field in Java

The following code sample is for a binary field.

```

public static int runTest(int[] array) {
    final int N = array.length;
    int[] b = new int[N];
    int[] c = new int[N];
    int[] t = new int[N];
    b[0] = 1;
    c[0] = 1;
    int l = 0;
    int m = -1;
    for (int n = 0; n < N; n++) {
        int d = 0;
        for (int i = 0; i <= l; i++) {
            d ^= c[i] * array[n - i];
        }
        if (d == 1) {
            System.arraycopy(c, 0, t, 0, N);

```

```

int N_M = n - m;
for (int j = 0; j < N - N_M; j++) {
    c[N_M + j] ^= b[j];
}
if (1 <= n / 2) {
    l = n + 1 - l;
    m = n;
    System.arraycopy(t, 0, b, 0, N);
}
}
return l;
}
}

```

## See also

- Reeds–Sloane algorithm, an extension for sequences over integers mod  $n$
- Berlekamp–Welch algorithm
- NLFSR, Non-Linear Feedback Shift Register

## References

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- Massey 1969, p. 124

## External links

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- Berlekamp–Massey algorithm (<http://planetmath.org/encyclopedia/BerlekampMasseyAlgorithm.html>) at PlanetMath.
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- GF(2) implementation in Mathematica (<http://code.google.com/p/lfsr/>)
- (German) Applet Berlekamp–Massey algorithm (<http://www.informationsuebertragung.ch/indexAlgorithmen.html>)
- Online GF(2) Berlekamp–Massey calculator (<http://berlekamp-massey-algorithm.appspot.com/>)

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