

Odboj

Prazen prostor

$$c_0 = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

Vpadni žarek

$\beta$

$$\vec{k}_V$$

$$k_{Vx}$$

$$\lambda_0 = \frac{c_0}{f} = \frac{1}{f \sqrt{\mu_0 \epsilon_0}}$$

Odbiti žarek

$\beta$

$$k_{Ox}$$

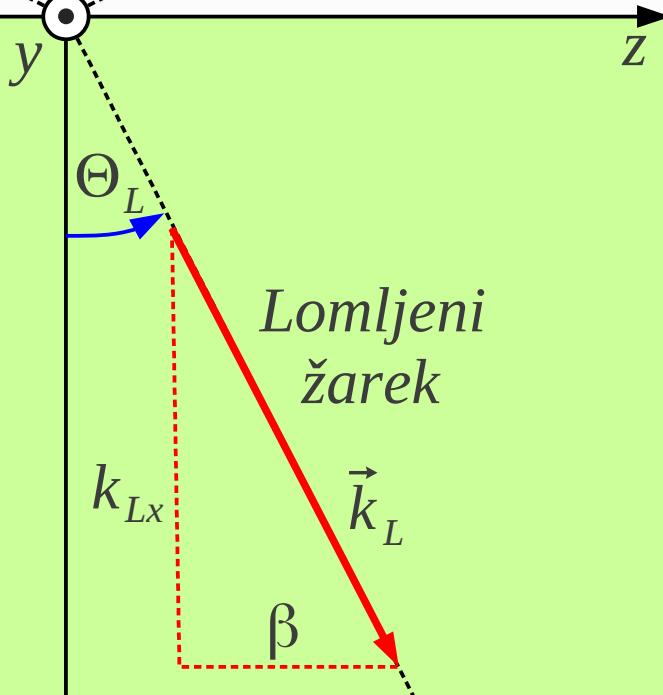
$$\vec{k}_O$$

$$\beta = \frac{2\pi}{\lambda_0} \sin \Theta_V = \frac{2\pi}{\lambda_0} \sin \Theta_O = \frac{2\pi}{\lambda} \sin \Theta_L$$

$$\vec{k}_V = \vec{1}_V \frac{2\pi}{\lambda_0} = \vec{1}_x k_{Vx} + \vec{1}_z \beta$$

$$\vec{k}_O = \vec{1}_O \frac{2\pi}{\lambda_0} = \vec{1}_x k_{Ox} + \vec{1}_z \beta$$

Odbojni zakon       $\Theta_O = \Theta_V$



Odboj in lom na površini snovi

$$\vec{k}_L = \vec{1}_L \frac{2\pi}{\lambda} = \vec{1}_x k_{Lx} + \vec{1}_z \beta$$

$$\lambda = \frac{\lambda_0}{n} = \frac{\lambda_0}{\sqrt{\mu_r \epsilon_r}}$$

Lomni zakon  
Ibn Sahl 984  
 $\sin \Theta_V = n \sin \Theta_L$

$$\sin \Theta_L = \frac{\sin \Theta_V}{\sqrt{\mu_r \epsilon_r}}$$

Prazen prostor

$$Z_0 = \sqrt{\frac{\mu_0}{\epsilon_0}}$$

Vpadni žarek

$$\vec{E}_V = \vec{1}_y E_V e^{-j\vec{k}_V \cdot \vec{r}}$$

$$\vec{H}_V$$

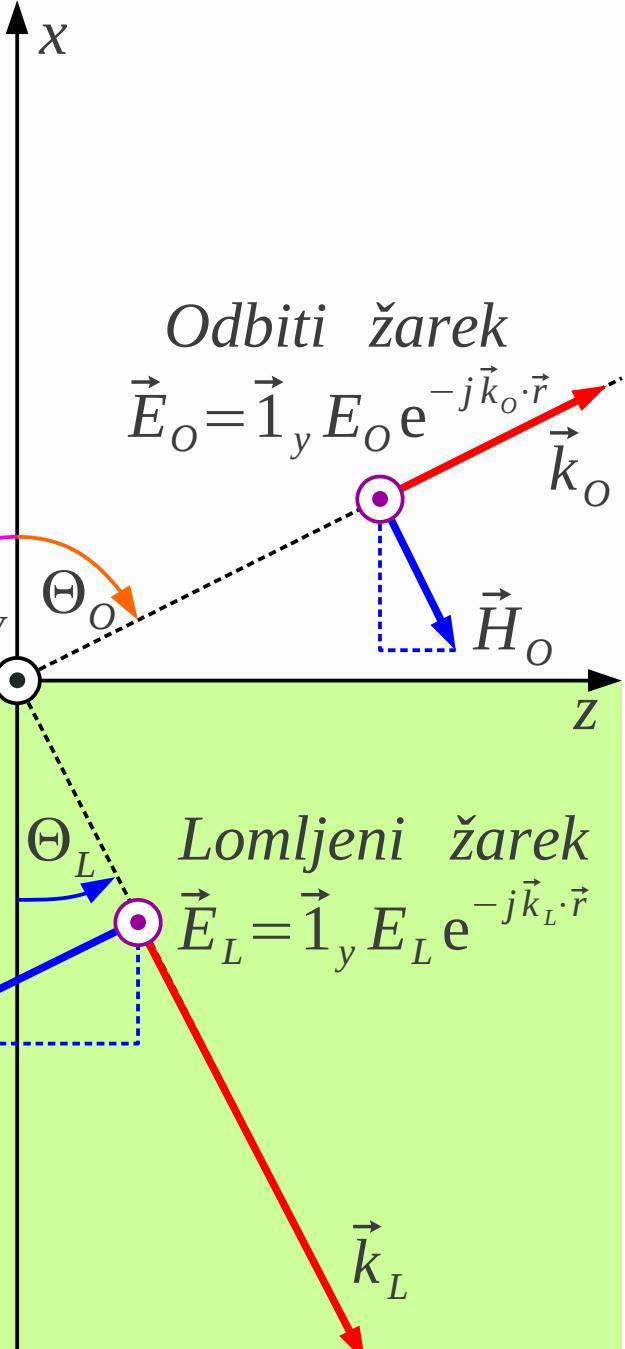
$$\vec{K} = 0$$

$$\vec{K}_m = 0 \quad \sigma_m = 0$$

Snov

$$n = \sqrt{\mu_r \epsilon_r}$$

$$Z = Z_0 \sqrt{\frac{\mu_r}{\epsilon_r}}$$



Odboj vodoravne polarizacije (HP ali TE)

Prestopni pogoji

$$(1) \quad E_{V_y} + E_{O_y} = E_{L_y}$$

$$(2) \quad H_{V_z} + H_{O_z} = H_{L_z}$$

$$(3) \quad B_{V_x} + B_{O_x} = B_{L_x}$$

Odboj

$$\Theta_O = \Theta_V$$

Odbojnost

$$\Gamma_{HP} = \frac{E_O}{E_V}$$

$$(1) \quad E_V + E_O = E_L$$

$$(2) \quad (E_V - E_O) \frac{\cos \Theta_V}{Z_0} = E_L \frac{\cos \Theta_L}{Z}$$

$$(1 - \Gamma_{HP}) \frac{\cos \Theta_V}{Z_0} = (1 + \Gamma_{HP}) \frac{\cos \Theta_L}{Z}$$

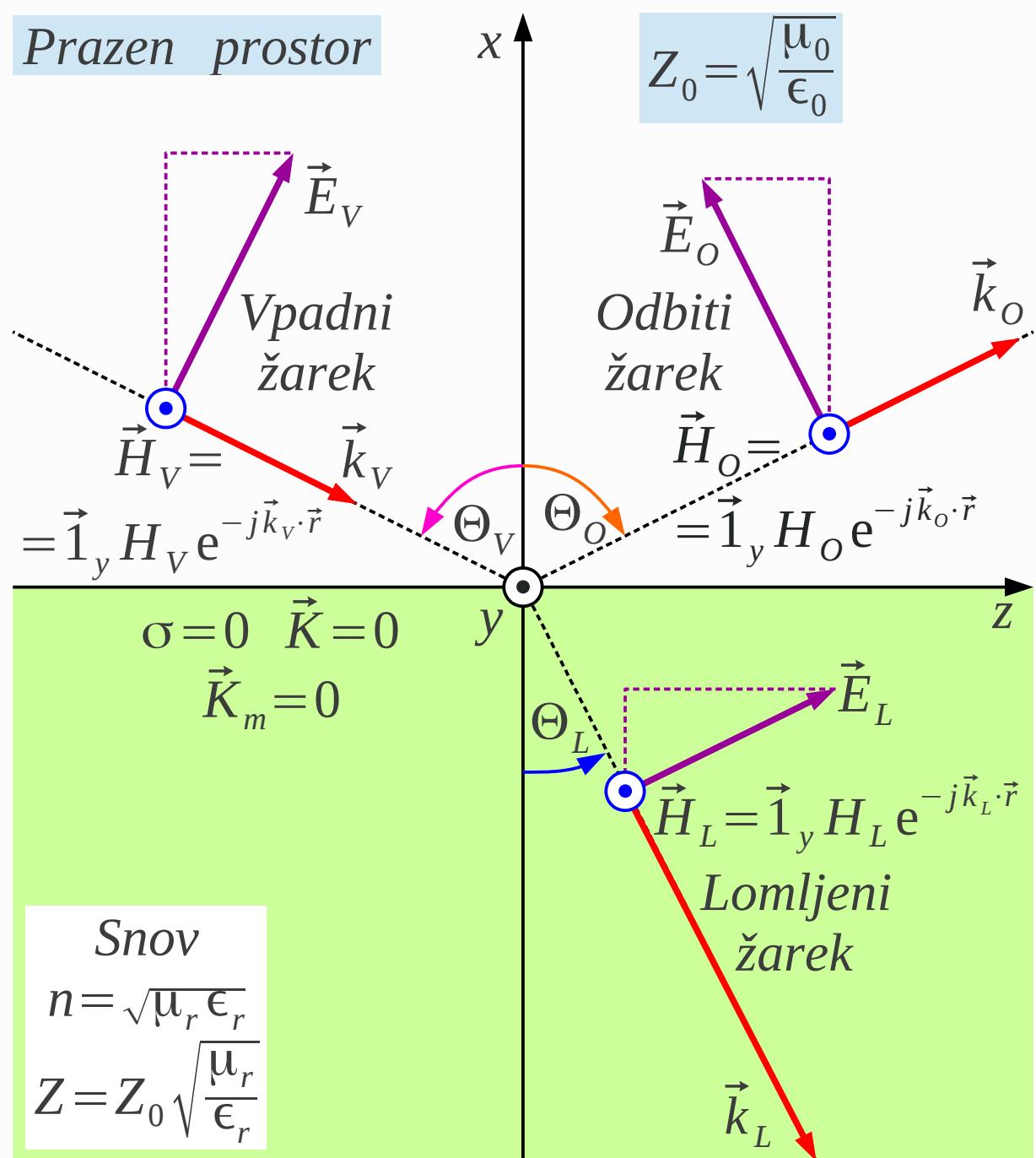
$$\Gamma_{HP} = \frac{Z \cos \Theta_V - Z_0 \cos \Theta_L}{Z \cos \Theta_V + Z_0 \cos \Theta_L}$$

$$Lom \cos \Theta_L = \sqrt{1 - \left( \frac{\sin \Theta_V}{n} \right)^2}$$

Dielektrik  $\mu_r = 1 \quad n = \sqrt{\epsilon_r}$   
 $\Theta = \Theta_V$

$$\Gamma_{HP} = \frac{\cos \Theta - \sqrt{\epsilon_r - \sin^2 \Theta}}{\cos \Theta + \sqrt{\epsilon_r - \sin^2 \Theta}}$$

# Prazen prostor



$$Z_0 = \sqrt{\frac{\mu_0}{\epsilon_0}}$$

# Prestopni pogoji

- (1)  $H_{V_y} + H_{O_y} = H_{L_y}$
- (2)  $E_{V_z} + E_{O_z} = E_{L_z}$
- (3)  $D_{V_x} + D_{O_x} = D_{L_x}$

$$Odboj \quad \Theta_O = \Theta_V$$

$$Odbojnost \quad \Gamma_{VP} = \frac{E_O}{E_V}$$

$$(1) \frac{E_V + E_O}{Z_0} = \frac{E_L}{Z}$$

$$(2) (E_V - E_O) \cos \Theta_V = E_L \cos \Theta_L$$

$$(1 - \Gamma_{VP}) \frac{\cos \Theta_V}{Z} = (1 + \Gamma_{VP}) \frac{\cos \Theta_L}{Z_0}$$

$$\Gamma_{VP} = \frac{Z_0 \cos \Theta_V - Z \cos \Theta_L}{Z_0 \cos \Theta_V + Z \cos \Theta_L}$$

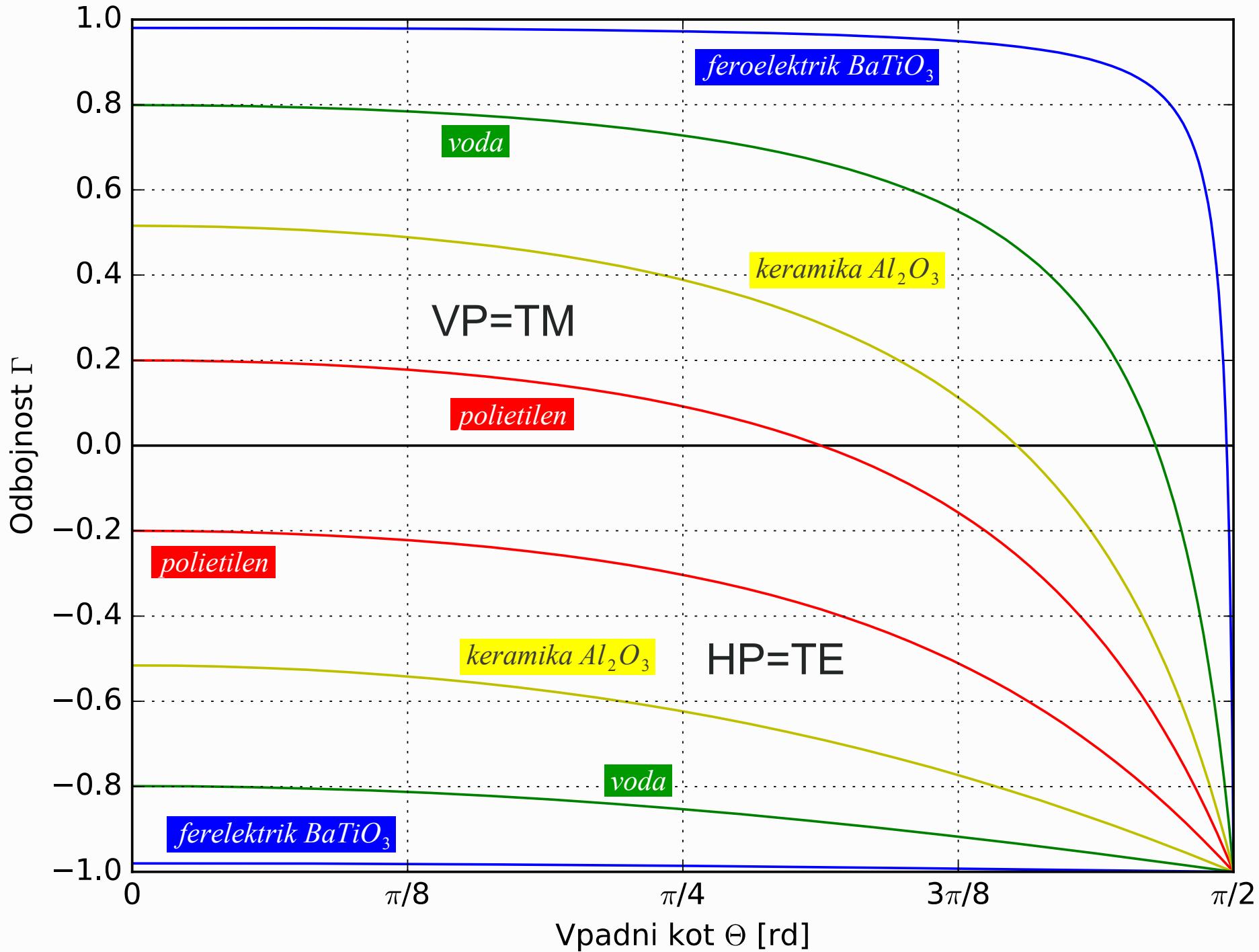
$$Lom \cos \Theta_L = \sqrt{1 - \left( \frac{\sin \Theta_V}{n} \right)^2}$$

$$Dielektrik \quad \mu_r = 1 \quad n = \sqrt{\epsilon_r} \\ \Theta = \Theta_V$$

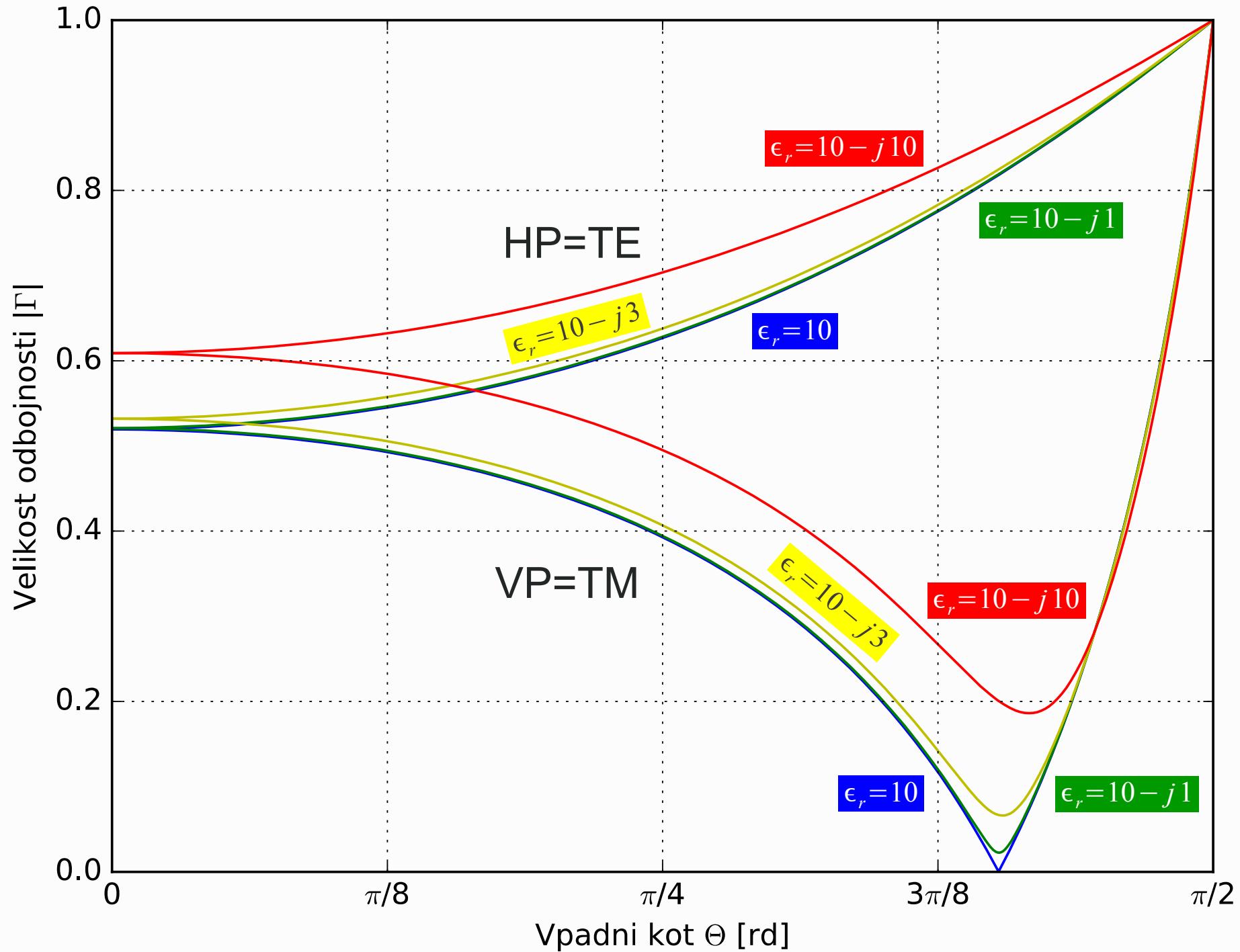
$$\Gamma_{VP} = \frac{\epsilon_r \cos \Theta - \sqrt{\epsilon_r - \sin^2 \Theta}}{\epsilon_r \cos \Theta + \sqrt{\epsilon_r - \sin^2 \Theta}}$$

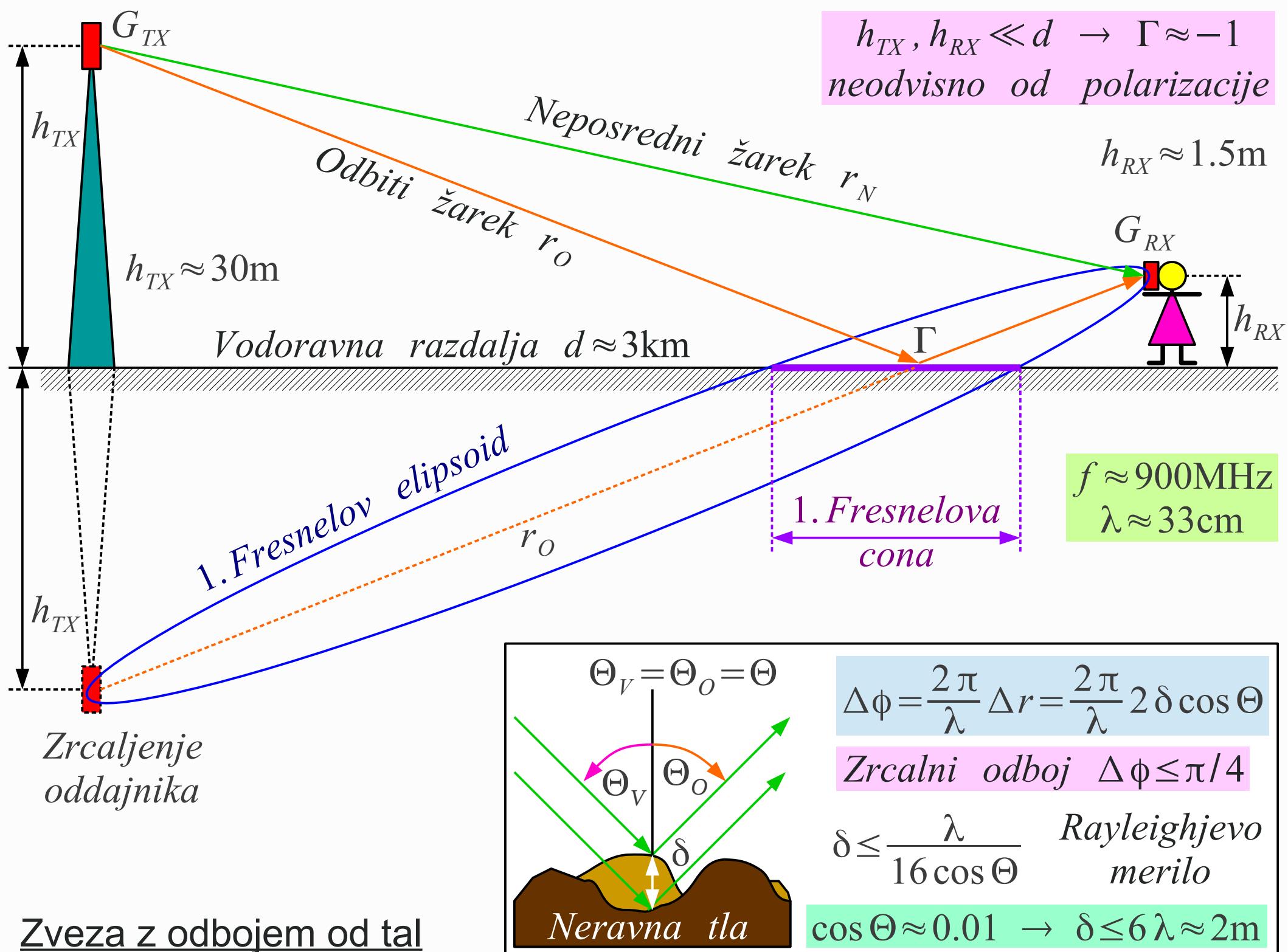
Odboj pokončne polarizacije (VP ali TM)

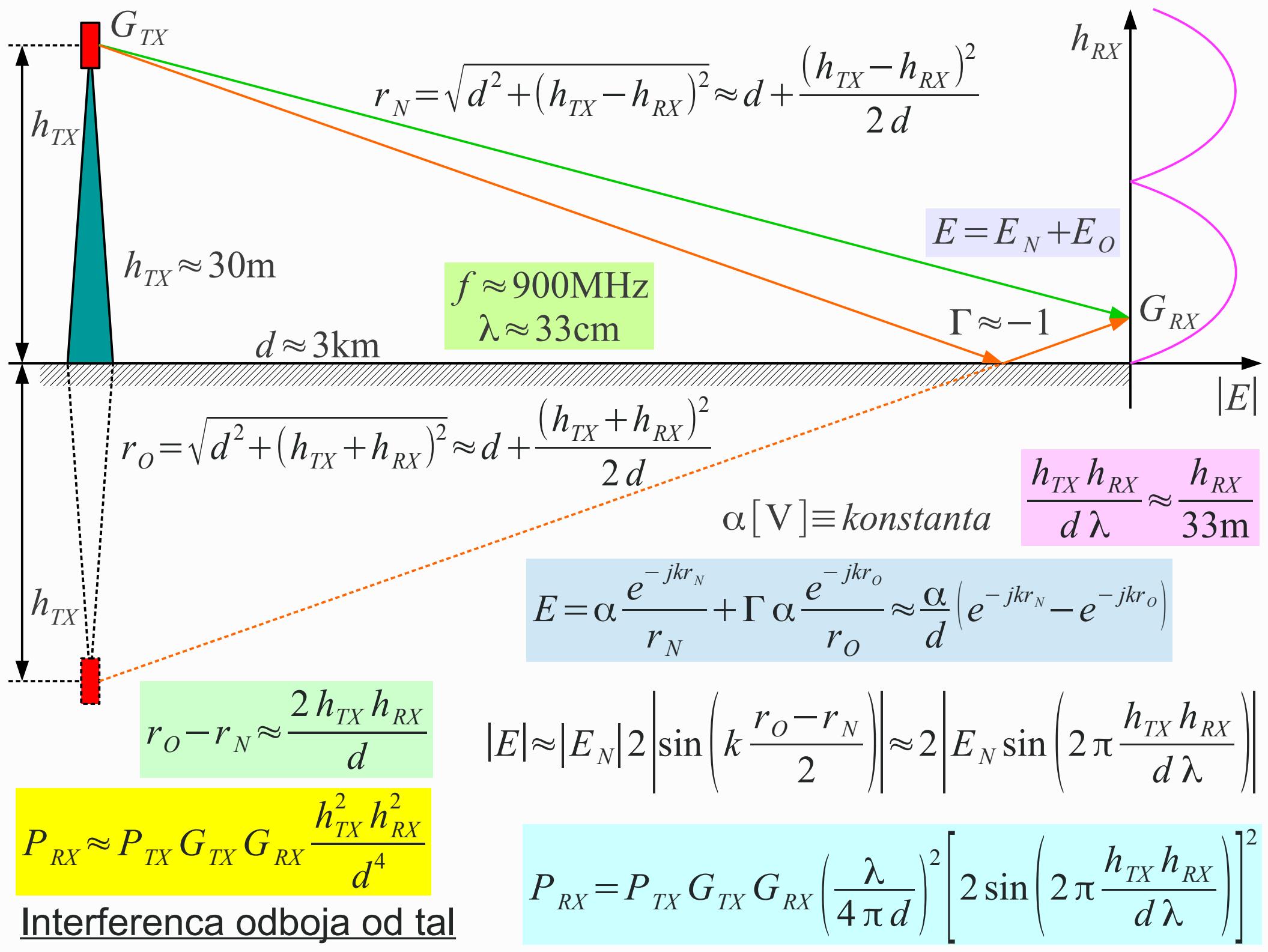
Dielektrik  $\epsilon_r = 2.25$ (polietilen), 9.8( $Al_2O_3$ ), 80(voda), 10000( $BaTiO_3$ )



# Dielektrik z izgubami $\epsilon_r=10, 10-j1, 10-j3, 10-j10$

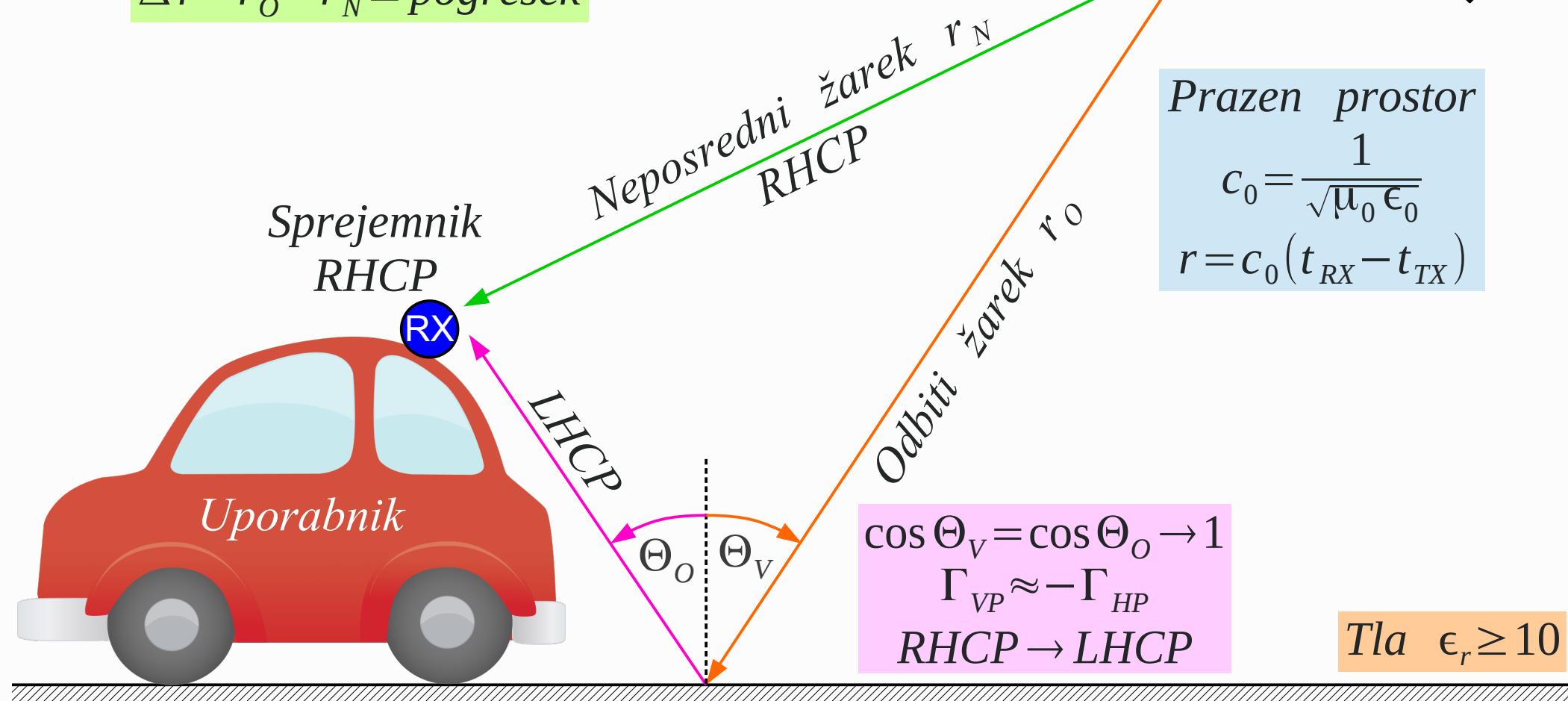
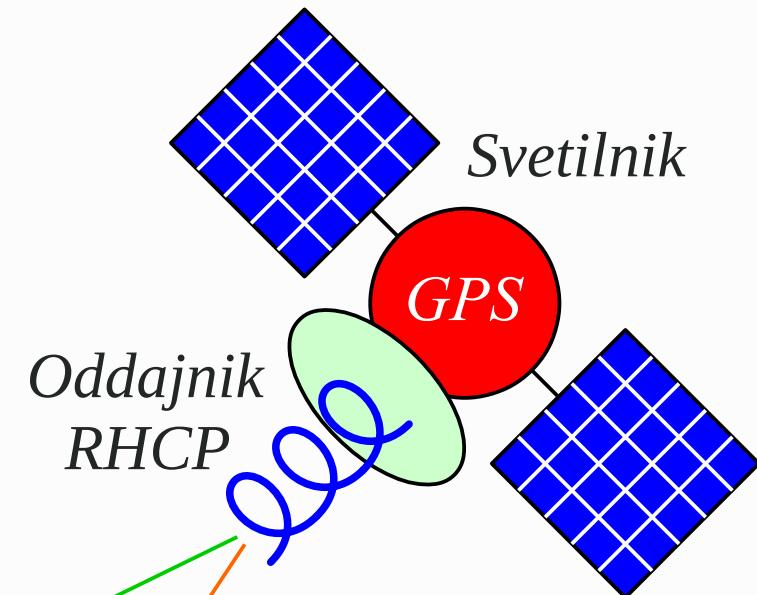






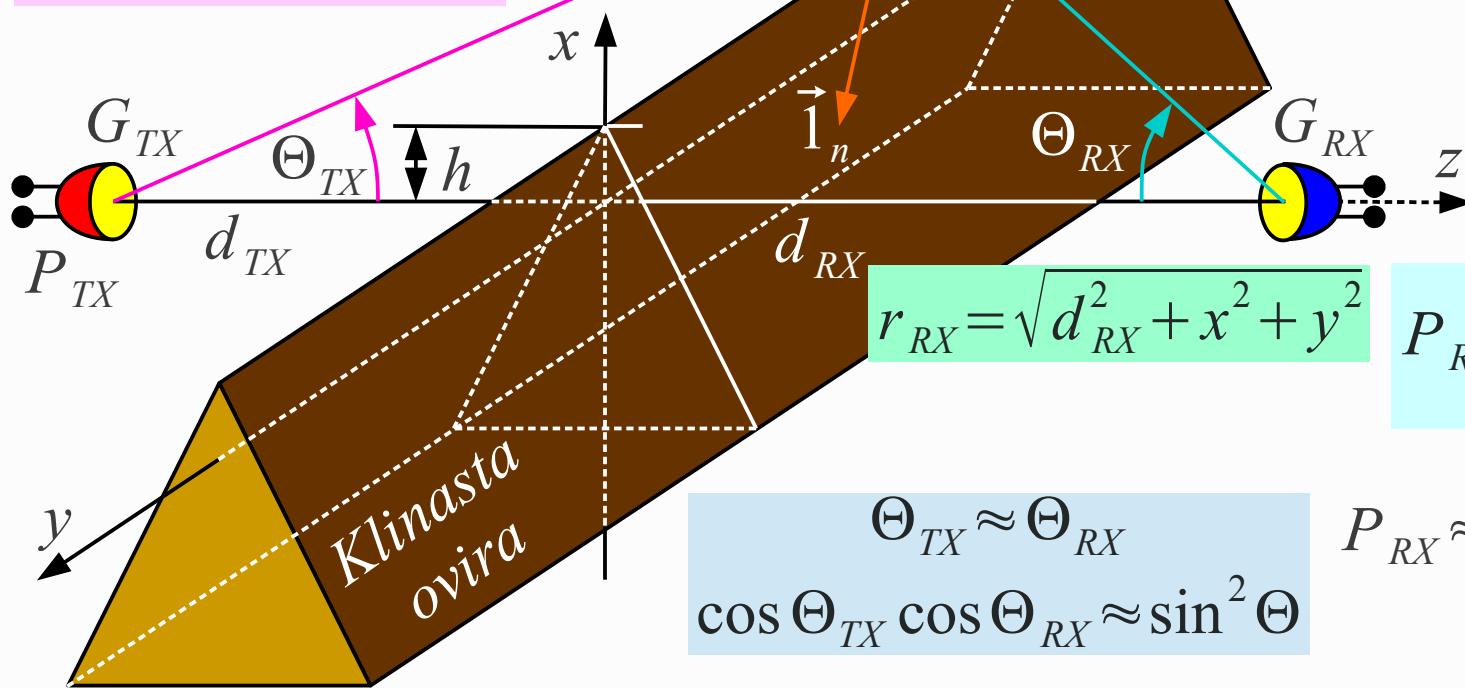
# Pogrešek pri satelitski navigaciji

$r_N \equiv$  pravilna razdalja  
 $r_O \equiv$  napačna razdalja  
 $\Delta r = r_O - r_N \equiv$  pogrešek



$$\Theta_{TX} + \Theta_{RX} + 2\Theta = \pi$$

$$r_{TX} = \sqrt{d_{TX}^2 + x^2 + y^2}$$



$$\sigma = G_Z A_Z \cos \Theta = \frac{4\pi}{\lambda^2} A_Z^2 \cos^2 \Theta \equiv \text{odmevna površina}$$

Radijska zveza preko zrcala

$$P_Z = \frac{P_{TX} G_{TX} A_Z \cos \Theta}{4\pi r_{TX}^2}$$

$$G_Z = \frac{4\pi}{\lambda^2} A_Z \cos \Theta$$

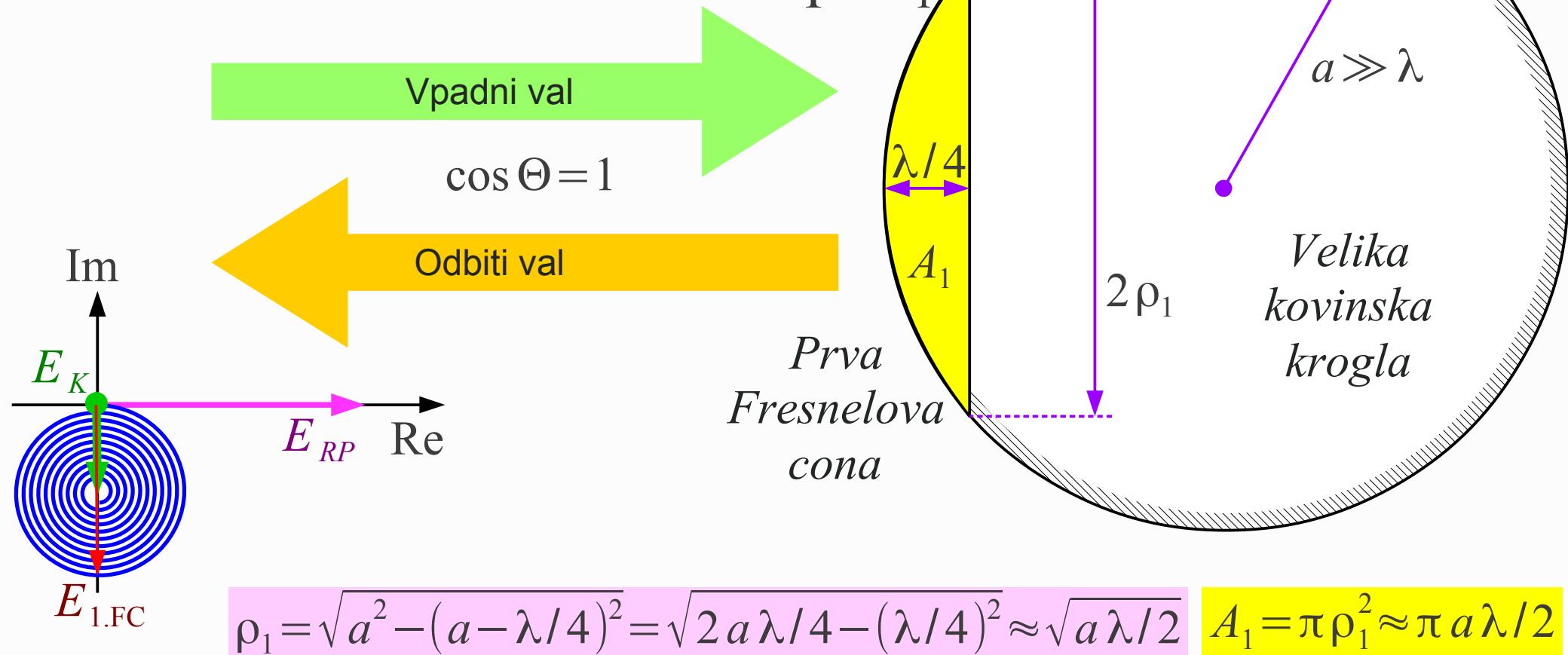
$$P_{RX} = P_Z G_Z G_{RX} \left( \frac{\lambda}{4\pi r_{RX}} \right)^2$$

$$P_{RX} \approx \frac{P_{TX} G_{TX} G_{RX}}{(4\pi r_{TX} r_{RX})^2} A_Z^2 \cos^2 \Theta$$

$$P_{RX} \approx \frac{P_{TX} G_{TX} G_{RX} \lambda^2}{(4\pi)^3 r_{TX}^2 r_{RX}^2} \sigma$$

Primerjava	Smer	Odmevna površina	Pogoji uporabe
Uklanjalnik	$\Theta_{TX} \neq \Theta_{RX}$	$\sigma = \frac{4\pi}{\lambda^2} A_U^2 \cos \Theta_{TX} \cos \Theta_{RX} / \pi^2$	$x, y \ll d_{TX}, d_{RX}$
Zrcalo	$\Theta_V = \Theta_O = \Theta$	$\sigma = \frac{4\pi}{\lambda^2} A_Z^2 \cos^2 \Theta$	$x, y \approx d_{TX}, d_{RX}$

# Odmevna površina velike kovinske krogle



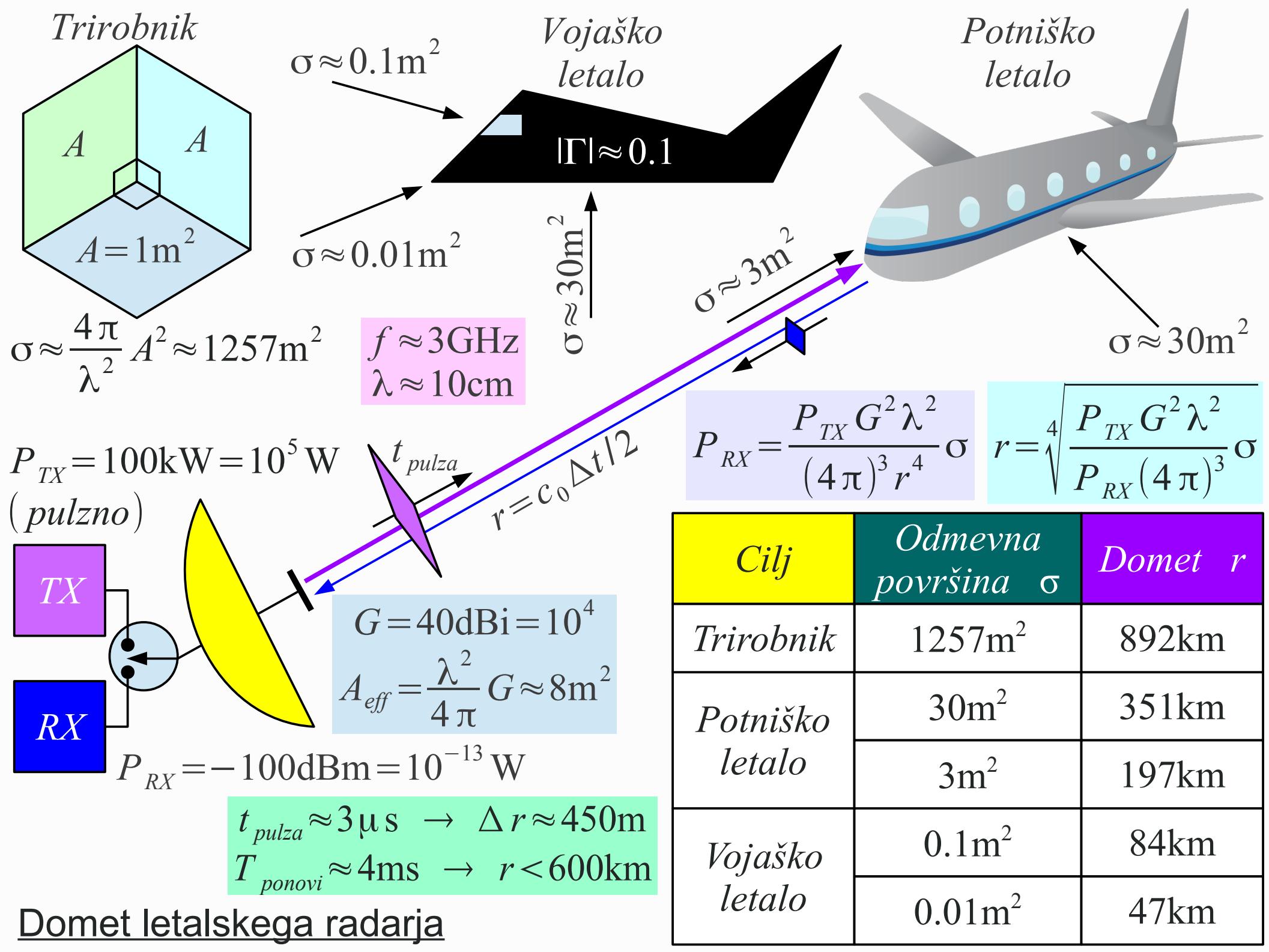
$$\rho_1 = \sqrt{a^2 - (a - \lambda/4)^2} = \sqrt{2a\lambda/4 - (\lambda/4)^2} \approx \sqrt{a\lambda/2}$$

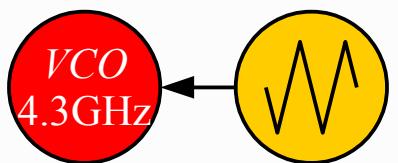
$$A_1 = \pi \rho_1^2 \approx \pi a \lambda / 2$$

$$\text{Ravna plošča } A_1 \rightarrow \sigma_{RP} = \frac{4\pi}{\lambda^2} A_1^2 \approx \frac{4\pi}{\lambda^2} (\pi a \lambda / 2)^2 = \pi^3 a^2$$

$$\text{Prva Fresnelova cona } A_1 \rightarrow E_{1.FC} = -j \left( \frac{2}{\pi} \right) E_{RP} \rightarrow \sigma_{1.FC} = \left( \frac{2}{\pi} \right)^2 \sigma_{RP} \approx 4\pi a^2$$

$$\text{Velika kovinska krogla} \rightarrow E_K = \frac{1}{2} E_{1.FC} \rightarrow \sigma_K = \frac{1}{4} \sigma_{1.FC} \approx \pi a^2$$

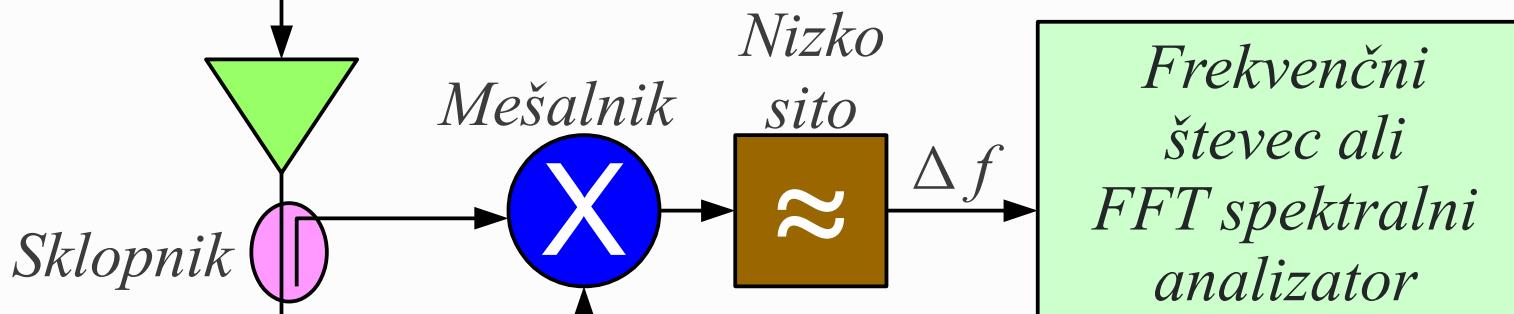




$\check{Z}aga$   
100Hz

$$\frac{df}{dt} \approx \frac{\pm 200\text{MHz}}{5\text{ms}}$$

FMCW radar

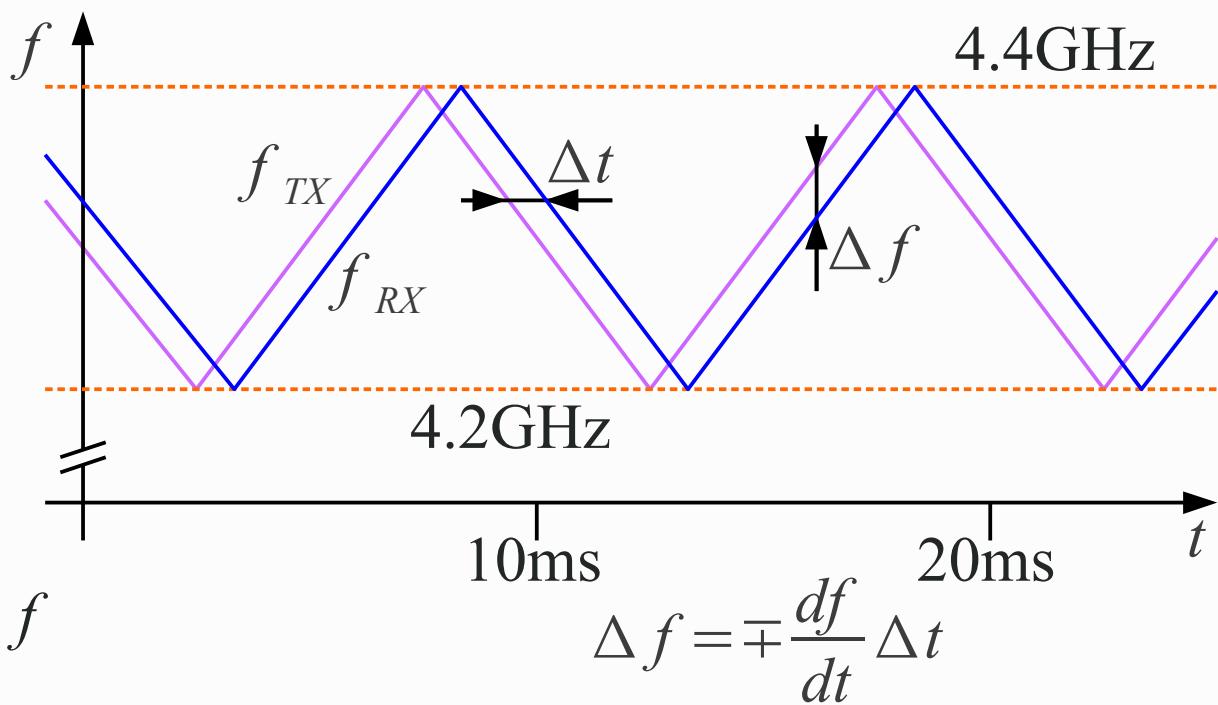
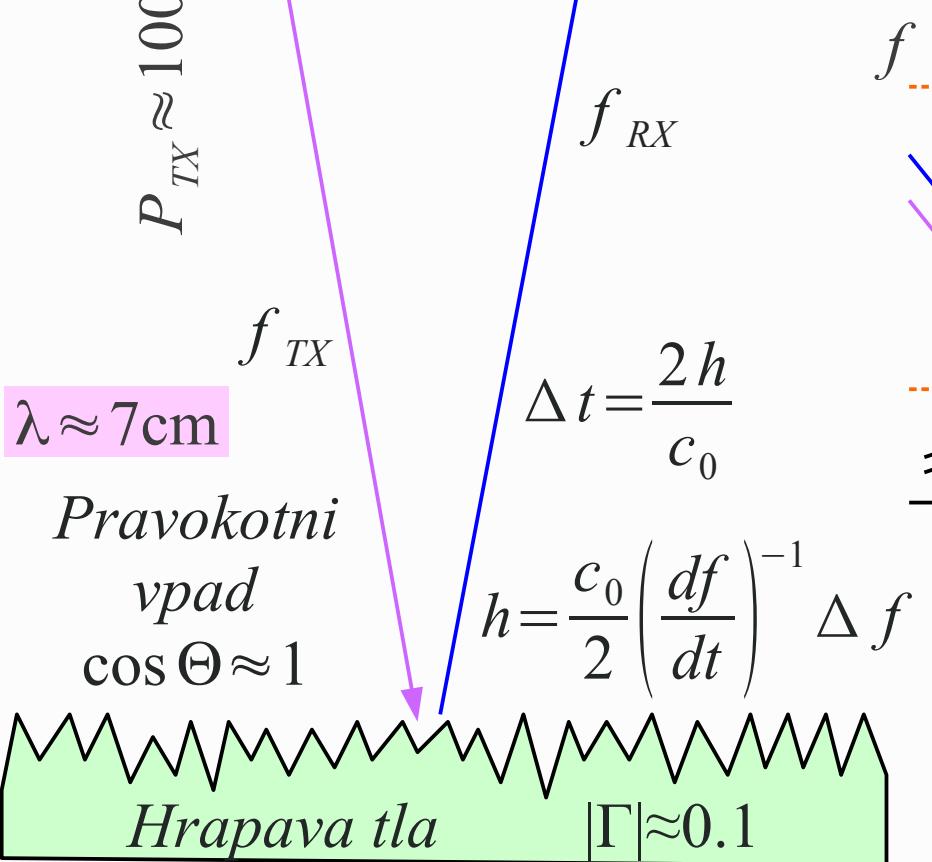


$$h \approx 1500\text{m}$$

$$\Delta t = 10\mu\text{s}$$

$$\Delta f \approx \mp 400\text{kHz}$$

$$P_{RX} = P_{TX} \left( \frac{G \lambda |\Gamma|}{4\pi 2 h} \right)^2 \approx 0.35\text{pW} \approx -94.6\text{dBm}$$

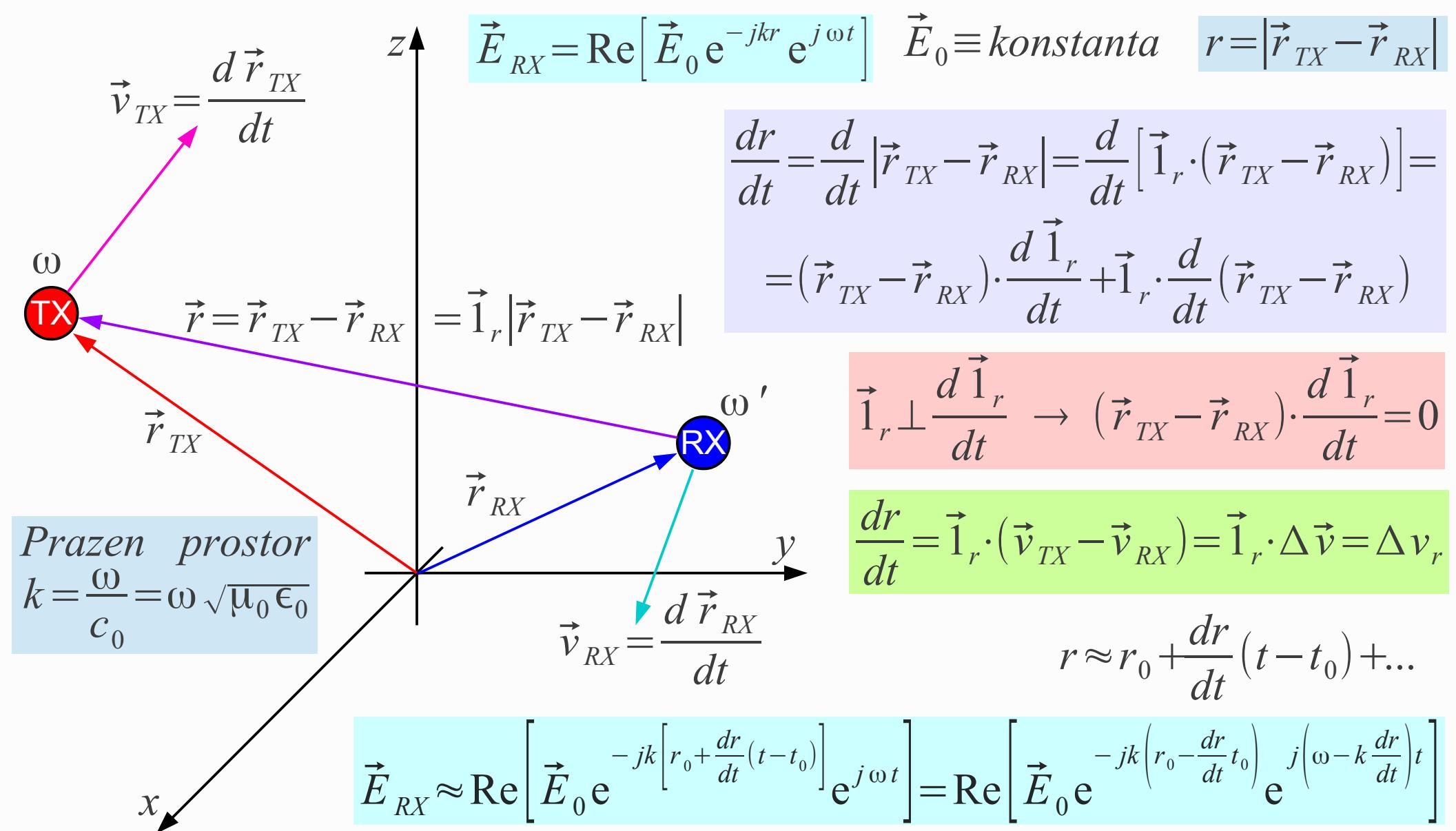


*Letalski višinomer*

$4.3\text{GHz} \pm 100\text{MHz}$

*Avtomobilski radar*

$77\text{GHz} \pm 1\text{GHz}$

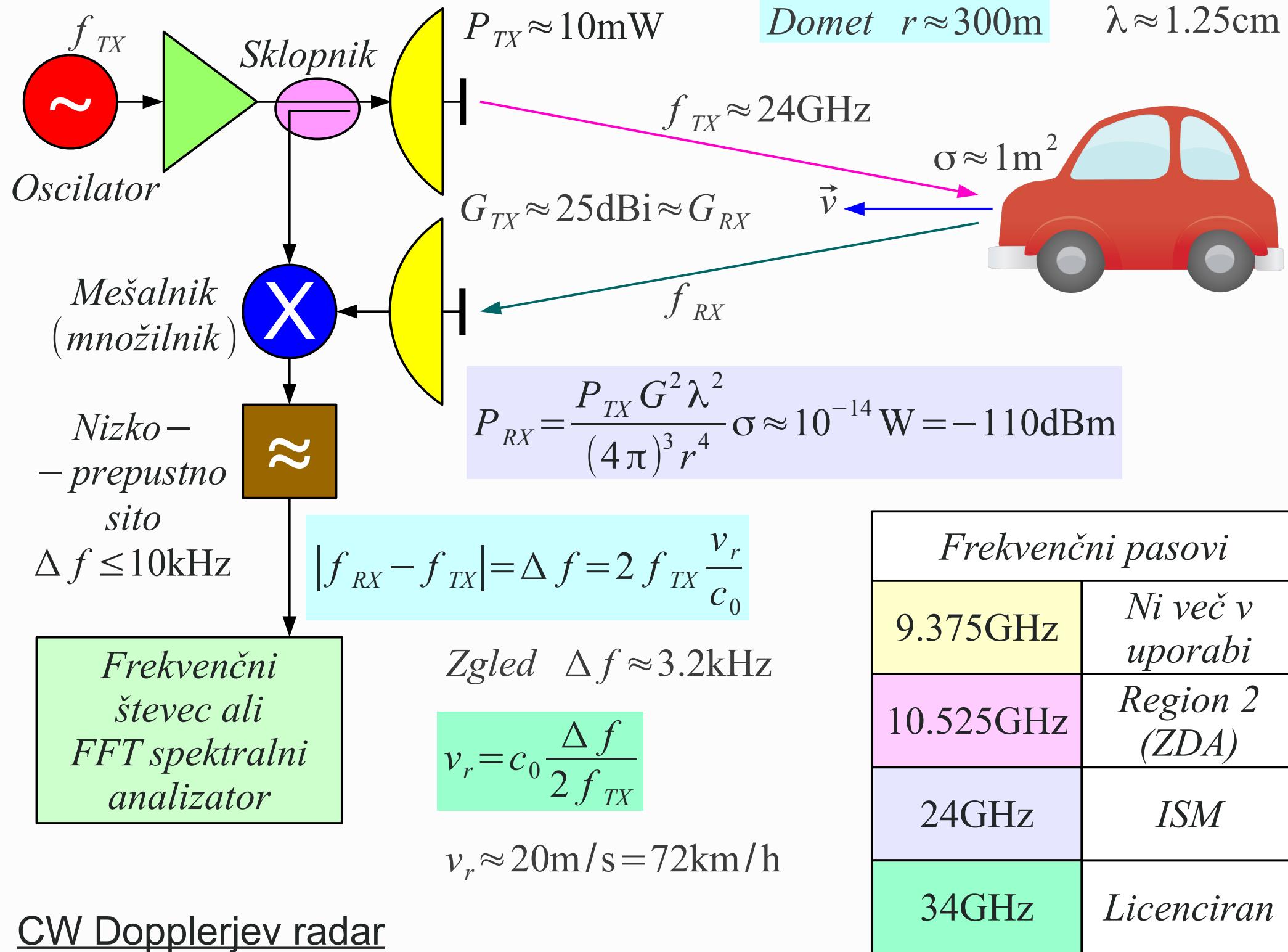


Christian A. Doppler 1842

$$\omega' \approx \omega - k \frac{dr}{dt} = \omega - \frac{\omega}{c_0} \frac{dr}{dt}$$

$$\Delta \omega = \omega' - \omega \approx -\frac{\omega}{c_0} \frac{dr}{dt} = -\frac{\omega}{c_0} \frac{(\vec{r}_{TX} - \vec{r}_{RX}) \cdot (\vec{v}_{TX} - \vec{v}_{RX})}{|\vec{r}_{TX} - \vec{r}_{RX}|}$$

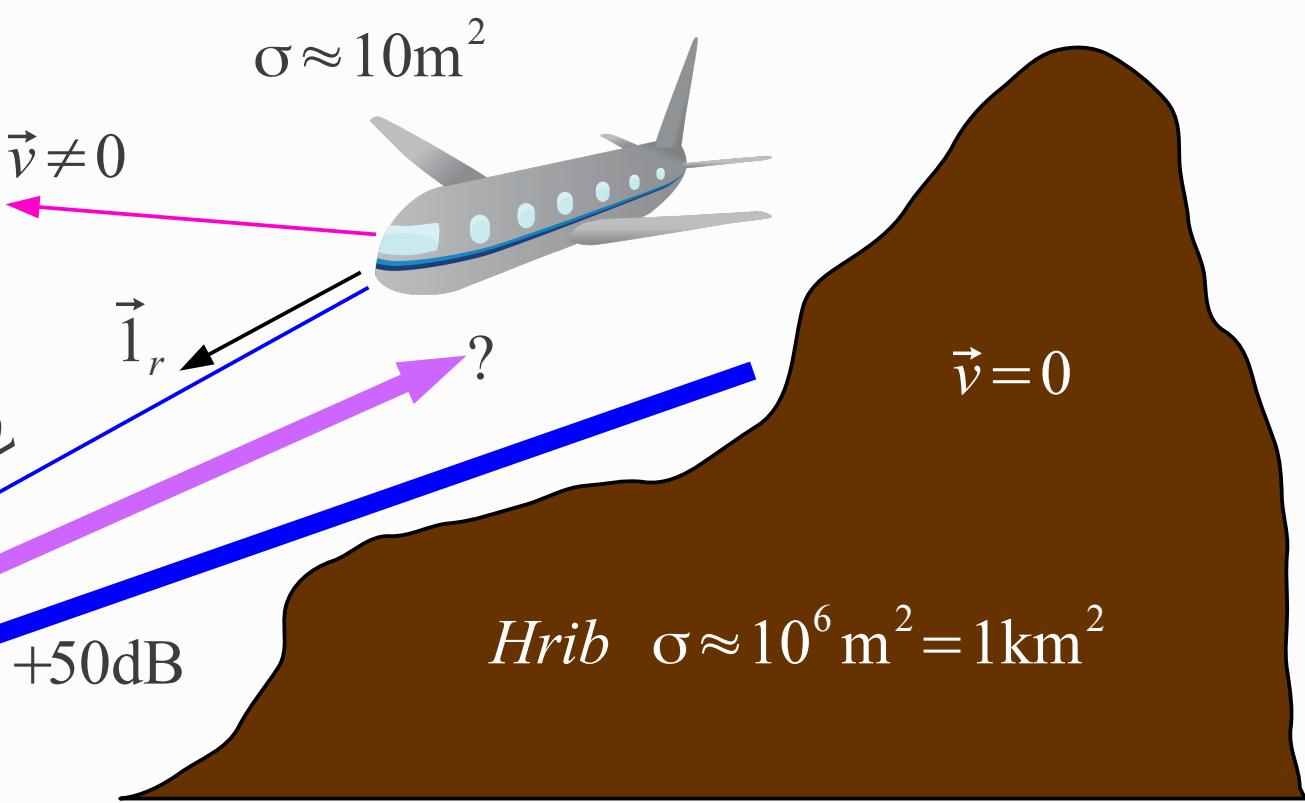
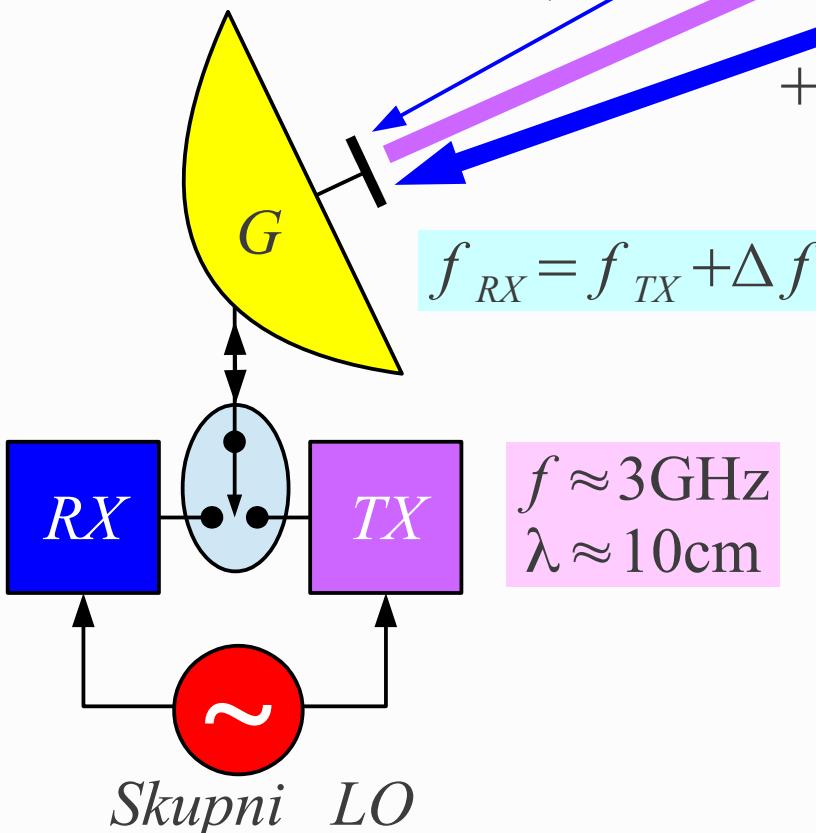
Dopplerjev pomik



$$t_{pulza} \approx 3 \mu s \rightarrow \Delta r \approx 450m$$

$$T_{ponovi} \approx 4ms \rightarrow r < 600km$$

Zahtevna  
primerjava  
faze zaporednih  
odmevov  
 $\Delta f \ll 1/t_p$



$$\Delta f = 2 \frac{f_{TX}}{c_0} (\vec{v} \cdot \vec{l}_r) \equiv \text{Dopplerjev pomik}$$

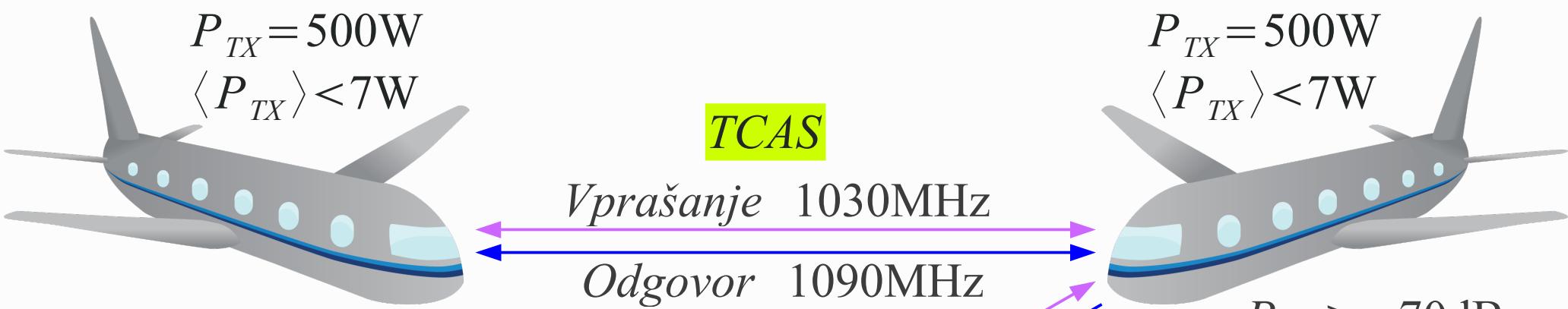
Razločevanje  
premičnih  
ciljev MTI

Letalo  $v \approx 250\text{m/s} = 900\text{km/h}$   
 $\rightarrow \Delta f \leq 5\text{kHz}$

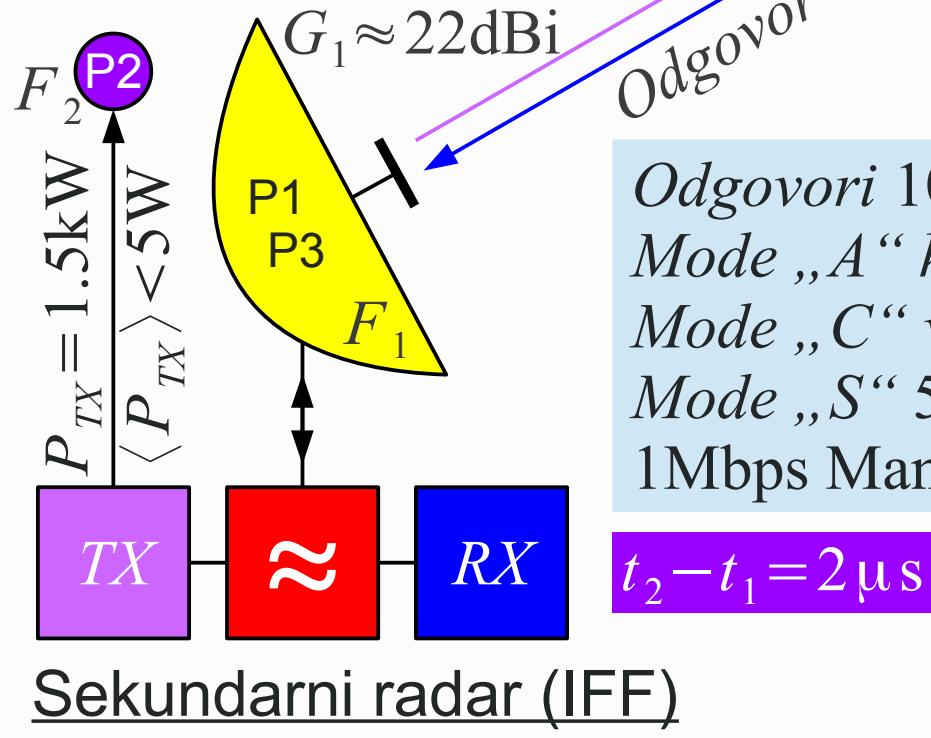
Hrib  $v \approx 0 \rightarrow \Delta f \approx 0$

Pulzno-Dopplerjev radar ne vidi:  
(1) Počasnih ciljev: baloni, jadralci...  
(2) Tangencialnih ciljev:  $\vec{v} \perp \vec{l}_r$

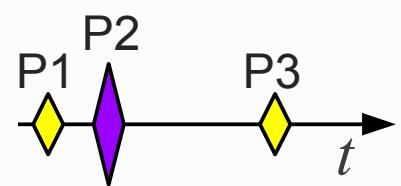
Pulzno-Dopplerjev radar



Vprašanja 1030MHz:  
Mode „A“  $t_3 - t_1 = 8\mu\text{s}$   
Mode „C“  $t_3 - t_1 = 21\mu\text{s}$   
Mode „S“ 56bit/112bit  
4Mbps BPSK



Odgovori 1090MHz:  
Mode „A“ koda letala 15bit  
Mode „C“ višina letala 13bit  
Mode „S“ 56bit/112bit  
1Mbps Manchester/ASK



$TCAS \equiv Traffic\text{-}alert Collision Avoidance System$   
 $TCAS\text{-}1: Traffic\text{ }Advisory\text{ }C/S$   
 $TCAS\text{-}2: Resolution\text{ }Advisory\text{ }S$

